

EcoStruxure Machine Expert V1.2.7

Release Notes

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Safety Information

Important Information

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, service, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a “Danger” or “Warning” safety label indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

⚠ DANGER
DANGER indicates a hazardous situation which, if not avoided, will result in death or serious injury.
⚠ WARNING
WARNING indicates a hazardous situation which, if not avoided, could result in death or serious injury.
⚠ CAUTION
CAUTION indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.
NOTICE
NOTICE is used to address practices not related to physical injury.

Please Note

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

About the Book

Document Scope

This document contains important information about the delivery of the product EcoStruxure Machine Expert V1.2.7, and the history of previous Release Notes. Read the complete document before you use the product or products that are described in here.

Validity Note

The information in this Release Notes document is applicable only for EcoStruxure Machine Expert compatible products.

This document has been updated for the release of EcoStruxure™ Machine Expert V1.2.7.

The technical characteristics of the devices described in the present document also appear online. To access the information online go to the Schneider Electric homepage www.se.com.

The characteristics that are described in the present document should be the same as those characteristics that appear online. In line with our policy of constant improvement, we may revise content over time to improve clarity and accuracy. If you see a difference between the document and online information, use the online information as your reference.

Product Information V1.2.7

Product Information

Overview

EcoStruxure Machine Expert

EcoStruxure Machine Expert is a unique solution software for developing, configuring, and commissioning the entire machine in a single software environment, including logic, motion control, HMI, and related network automation functions.

NOTE: If you are using templates and examples which are not updated with the update of EcoStruxure Machine Expert V1.2.7, you may be presented the **Update Project** dialog. If you are opening an example or template for the first time, you should update to have the correct and corresponding libraries and other necessary support.

EcoStruxure Machine Expert - Safety

EcoStruxure Machine Expert - Safety is a component of EcoStruxure Machine Expert. It is an engineering tool used to develop safety-related applications for the Safety Logic Controller TM5CSLC•00FS.

The application is based on the standard IEC 61131-3 and meets the applicable safety-related requirements of IEC 61508. It provides the components necessary for the different development phases of a Safety Logic Controller application.

EcoStruxure Machine Expert - Installation Note

In our efforts of continuous improvement, major releases such as EcoStruxure Machine Expert V1.1 or EcoStruxure Machine Expert V1.2 may have some minor releases thereafter to improve quality, add minor features or add hardware that may not have been available at the time of the major release. These minor releases will update the existing installed version on your machine to which they belong. However, major releases are installed as separate instances on your PC. For example, EcoStruxure Machine Expert V1.2.7 provides a full installation of the software and related system components, but when installed on a PC where EcoStruxure Machine Expert V1.2 or V1.2.x was already installed, it will update this existing version by adding new components and replacing existing components.

Contrast this to a PC that has EcoStruxure Machine Expert V1.1 installed as you install, for example, EcoStruxure Machine Expert V1.2.7. In this case, EcoStruxure Machine Expert V1.2.7 will be installed as a complete and separate instance to EcoStruxure Machine Expert V1.1 (or any of its minor releases like, for example, EcoStruxure Machine Expert V1.1 SP1).

Product Identification

Reference	Description
Machine Expert Installer	V12.20.08301
EcoStruxure Machine Expert	V1.2.7
EcoStruxure Machine Expert - Safety	V1.2.42.6801
Safety Plugin (SafeLogger, Safety Offline Help)	(5.2.43.6808)

NOTE: You can see the installed software versions in the Machine Expert Installer.

Release History

Version	Release Date	Description
V1.1	July 2019	EcoStruxure Machine Expert V1.1
V1.1 SP1	November 2019	EcoStruxure Machine Expert V1.1 SP1
V1.2	December 2019	EcoStruxure Machine Expert V1.2
V1.2.1	February 2020	EcoStruxure Machine Expert V1.2.1
V1.2.2	March 2020	EcoStruxure Machine Expert V1.2.2
V1.2.3	May 2020	EcoStruxure Machine Expert V1.2.3
V1.2.4	August 2020	EcoStruxure Machine Expert V1.2.4
V1.2.5	September 2020	EcoStruxure Machine Expert V1.2.5
V1.2.6	October 2020	EcoStruxure Machine Expert V1.2.6
V1.2.7	February 2021	EcoStruxure Machine Expert V1.2.7

System Requirements

EcoStruxure Machine Expert can be installed on a personal computer with the following hardware:

- Processor Core 2 Duo or greater
- RAM Memory 4 GB minimum, 8 GB recommended or greater
- Hard disk 8 GB for typical and 15 GB for full software installation
- Display 1280 x 1024 resolution or greater
- Mouse or compatible pointing device
- USB interface
- Internet access

EcoStruxure Machine Expert V1.2.7 can be installed on the following operating systems:

- Microsoft Windows 8.1 Professional Edition (64 Bit)
- Microsoft Windows 10 (64 Bit)

NOTE: Some components still support 32 Bit operating systems (see the following table).

Software	Supported OS
EcoStruxure Machine Expert	64 Bit
EcoStruxure Machine Expert - Safety	32 Bit & 64 Bit
Machine Expert Installer	32 Bit & 64 Bit
SQL gateway	32 Bit & 64 Bit
Gateway	32 Bit & 64 Bit
Device Assistant	32 Bit & 64 Bit
Diagnostics	32 Bit & 64 Bit
Controller Assistant	32 Bit & 64 Bit
Motion Sizer	32 Bit & 64 Bit

Microsoft.NET Framework

EcoStruxure Machine Expert requires the .NET Framework 4.7.2. Therefore, it is required to have a current Windows version on your system. If a previous version is found on your current Windows version, EcoStruxure Machine Expert will install the required version.

EcoStruxure Machine Expert was tested using the following Windows versions:

Version	Version Name
6.3.9600	Windows 8.1
10.0.14393	Windows 10

EcoStruxure Machine Expert - Safety and DTM require the Microsoft.NET Framework 3.5 Service Pack 1 with the latest updates.

This package is not installed with Windows 8.1 or Windows 10. An internet connection is required to install Microsoft.NET Framework 3.5.

For information on how to install it, refer to <https://msdn.microsoft.com/en-US/library/hh506443>.

Installation Instructions

Overview

The Machine Expert Installer is used for configuring and installing the EcoStruxure Machine Expert software. For information on the installation procedure, refer to the Machine Expert Installer User Guide.

Limitations on USB Driver Installation for M241/M251 Controllers

In some cases, this driver installation is incomplete. The controller is shown with a yellow triangle in the **Device Manager**.

You can solve this issue by manually installing the USB driver for the marked device. The driver is available in the following directories:

- *C:\Program Files (x86)\Schneider Electric\EcoStruxure Machine Expert\Tools\Gateway\Driver\USB PLC Driver\Win7_x64 for x64 systems*
- *C:\Program Files (x86)\Schneider Electric\EcoStruxure Machine Expert\Tools\Gateway\Driver\USB PLC Driver\Win7_x86 for x86 systems*

Limitations on EcoStruxure Machine Expert - Safety Installation

Installing the Safety component via Machine Expert Installer requires at minimum to select and install one available controller (Modicon or PacDrive) component to get a full usable system environment (refer to Machine Expert Installer User Guide).

Make sure that during the installation of EcoStruxure Machine Expert - Safety, no instance of a previously installed legacy version of SoSafe programmable V2.x is running.

Installation of CodeMeter

In order to take advantage of the latest bug fixes and security enhancements, you must update the third-party tool CodeMeter. Go to <https://www.wibu.com/support/user/user-software.html> and install the latest patch.

Licensing Information

Refer to the Online help.

Cybersecurity Information for User Rights Management V1.2.7

Overview

NOTE: To help keep your Schneider Electric products secure and protected, it is in your best interest that you implement the cybersecurity best practices as indicated in the *Cybersecurity Best Practices* document provided on the Schneider Electric website.

User Rights Management - General Information

Overview

In order to meet constantly evolving cybersecurity requirements, with EcoStruxure Machine Expert the user rights management is by default activated for Schneider Electric LMC058, M241, M251, M258, M262, PacDrive LMC Eco, PacDrive LMC Pro/Pro2 controllers. This has the effect that every Schneider Electric controller equipped with the latest EcoStruxure Machine Expert firmware prompts you for user credentials whenever you attempt to gain access.

NOTE: The new user rights management does not apply for HMISCU controllers.

For general information regarding device user management, refer to the Programming Guide in the EcoStruxure Machine Expert [online help](#), section **Software > Programming > Programming Guide > Configuration > Common Device Editor Dialogs > Device Configuration > Users and Groups > Users and Groups Management**.

First Login to Schneider Electric Controller with User Rights Management Activated Using Default Credentials

As user management is activated by default in the controllers, use the following default credentials for first login and modify them immediately.

Step	Action
1	At first login to a Schneider Electric controller, enter the default user credentials: <ul style="list-style-type: none"> • User name: Administrator • Password: Administrator Result: You are requested to change the default password.
2	Enter your individual Password .
3	Re-enter your individual Password .
4	Click OK to confirm. Result: Access to your controller is now protected by these new credentials. They are assigned the highest user rights level and allow you to manage access rights for users or user groups.

NOTE: For future login, the new **Password** will be required.

Controller Locked After Entering Incorrect Credentials

If you enter incorrect credentials for three times, the controller will be locked for 60 seconds. After this time, retry to connect by entering the correct credentials.

Logoff Procedure

After successful login to the controller, you can perform further online actions on the controller with EcoStruxure Machine Expert. As long as your project remains open, you will not be prompted to enter your credentials again.

In order to log off the present user from the controller, execute the command **Online > Security > Logoff current device user**.

After that you will be prompted for your credentials when you attempt to perform another online command on the controller.

Firewall Settings

Most of the communication services like FTP or OPC UA access the controller by using the settings of the user rights management. Therefore, make sure that the firewall settings on the controller allow the services to access the controller file system.

Controller - HMI Communication with User Rights Management Activated

With user rights management activated in the controllers, the connection between an HMI programmed with Vijeo-Designer and the controller will not be established.

The following solutions are available to solve this issue:

- In Vijeo-Designer, open the **Network Equipment Settings** dialog box of the **I/O Manager** and enter the **Username** and the **Password** to access the controller.
- Reset the device user rights of the controller, page 11.

Resetting Device User Rights

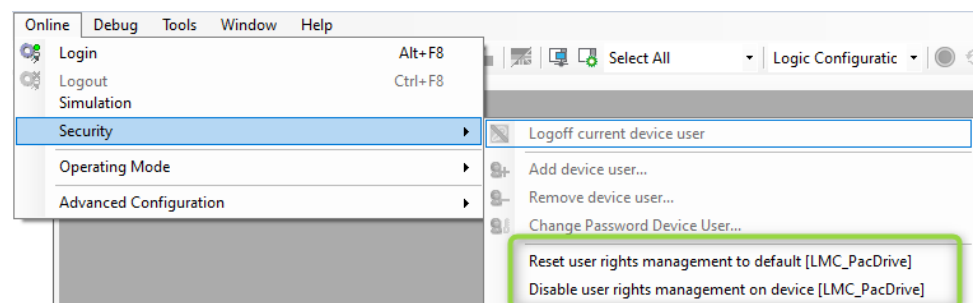
Overview

You can reset the device user rights to the default settings by using different software tools. Your individual credentials are required for this procedure. For further information on the default settings, refer to the *First Login to Schneider Electric Controller with User Rights Management Activated Using Default Credentials* paragraph, page 10.

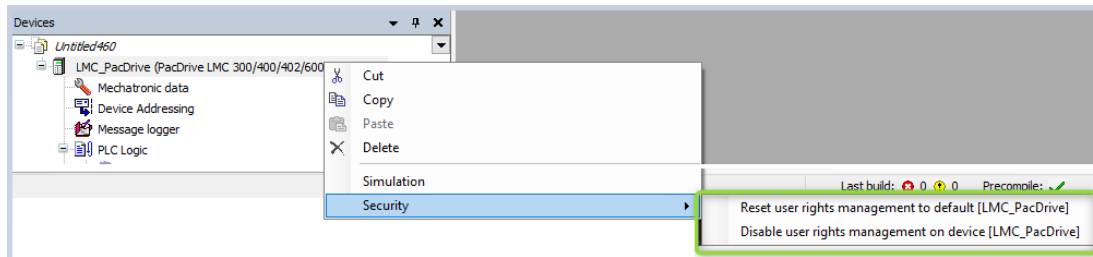
Reset via EcoStruxure Machine Expert Logic Builder

For Modicon LMC058, M258, PacDrive LMC Eco and PacDrive LMC Pro/Pro2 controllers, you can reset the device user rights using the **Reset user rights management to default** command that is available at two different locations:

Online > Security > Reset user rights management to default menu:

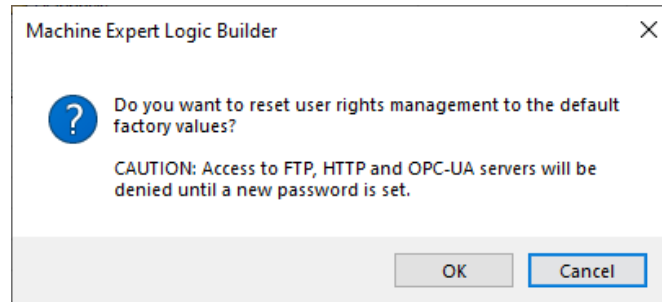


Contextual menu of the controller, **Security > Reset user rights management to default** command:



NOTE: When you reset the user rights management to the default values, access to FTP, HTTP and OPC-UA servers is denied until you set your individual user name and password.

Confirm the message with **OK**.



Reset via Controller Webserver

The Modicon LMC058 Motion Controller, Modicon M241, M251, M258 Logic Controller, and the Modicon M262 Logic/Motion Controller support the reset of device user rights management via the embedded webserver: **MAINTENANCE > USER MANAGEMENT > USER ACCOUNTS MANAGEMENT > RESET TO DEFAULT**

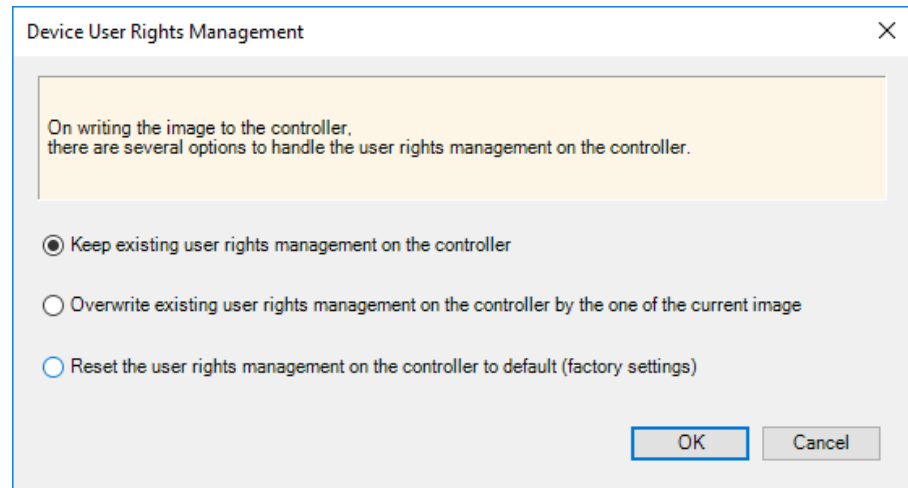
Consult the *Programming Guide* specific to your controller in the EcoStruxure Machine Expert online help for further information:

- Modicon LMC058 Motion Controller
Machine Expert > V1.2 > Controllers > LMC058 Motion Controllers > LMC058 Motion Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- Modicon M241 Logic Controller
Machine Expert > V1.2 > Controllers > M241 Logic Controllers > M241 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- Modicon M251 Logic Controller
Machine Expert > V1.2 > Controllers > M251 Logic Controllers > M251 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- Modicon M258 Logic Controller
Machine Expert > V1.2 > Controllers > M258 Logic Controllers > M258 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- Modicon M262 Logic/Motion Controller
Machine Expert > V1.2 > Controllers > M262 Logic/Motion Controllers > M262 Logic/Motion Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server

Reset via Controller Assistant

As of EcoStruxure Machine Expert V1.2, the service tool Controller Assistant supports user rights management of Modicon LMC058, Modicon M258, PacDrive LMC Eco and PacDrive LMC Pro/Pro2 controllers.

By attempting to write an image to the controller in online mode, or to the SD card or flash disk, or to the USB key, you will be prompted to decide how to manage user rights in the controller:



The following options are available:

- **Keep existing user rights management on the controller**
Activate this option to keep the existing user rights management as it is. This applies even if the user rights management is disabled.
NOTE: If you attempt to write an EcoStruxure Machine Expert V1.2 or later firmware to a controller without user rights defined, the user rights management in the controller will be set to the default settings.
- **Overwrite existing user rights management on the controller by the one on the current image**
The user rights management in the controller will be overwritten by the user rights management that is defined in the image you attempt to write.
NOTE: If you attempt to write an EcoStruxure Machine Expert V1.2 or later firmware and if there is no user rights management defined in the image, the user rights management in the controller will be set to the default settings.
- **Reset the user rights management on the controller to default (factory settings)**
The user rights management in the controller will be set to the default settings.

By default, the user rights management existing in the controller are preserved when writing to the controller in online mode.

Reset Without Credentials

If you have lost the credentials, you can reset the user rights management of the controller by using the service tool Controller Assistant to write the image to the SD card or flash disk, or to the USB key.

From the message prompting you to decide how to handle user rights in the controller, select the option **Reset the user rights management on the controller to default (factory settings)**. If this option is not available, you can create a new firmware from scratch that comes with the default settings. Then you can restart the controller directly from this SD card or flash disk.

The Modicon LMC058 Motion Controller, Modicon M241, M251, M258 Logic Controller, and the Modicon M262 Logic/Motion Controller also allow you to

modify a script.cmd file by using a SD card or a USB key (depending on the support of your particular controller) to reset the user rights management. Consult the *Programming Guide* specific to your controller for further information.

Deactivating Device User Rights

Overview

In order to help prevent unauthorized access to your controller, keep the device user rights management function activated. If you ensure that your machine or process is not accessible to unauthorized personnel, you can deactivate the function as described in this chapter. Your individual credentials are required for this procedure.

Deactivating via EcoStruxure Machine Expert Logic Builder

For Modicon LMC058, Modicon M258, PacDrive LMC Eco and PacDrive LMC Pro/Pro2 controllers, you can deactivate the device user rights management using the **Disable user rights management on device** command that is available at two different locations:

- **Online > Security > Disable user rights management on device** menu
- Contextual menu of the controller, **Security > Disable user rights management on device** command

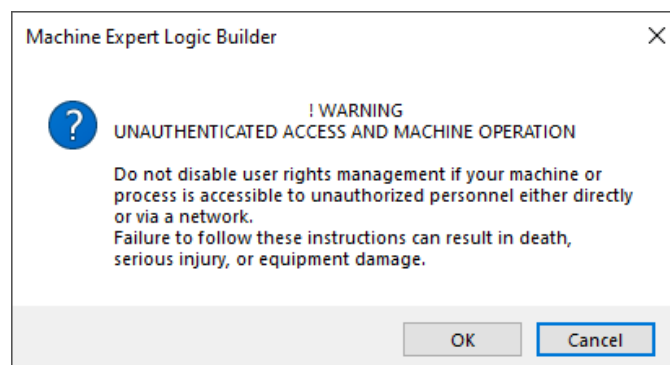
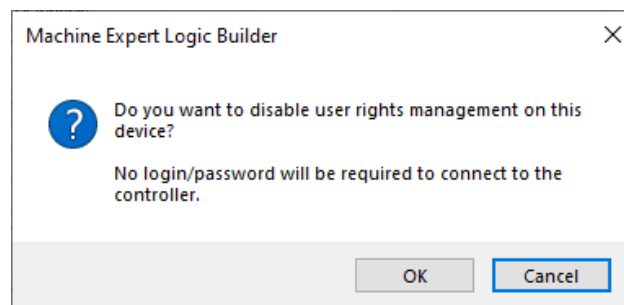
! WARNING

UNAUTHENTICATED ACCESS AND MACHINE OPERATION

Do not disable user rights management if your machine or process is accessible to unauthorized personnel either directly or via a network.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Confirm the two confirmation messages with **OK** if you are sure to deactivate the device user rights.



Result: Access the controller is now available without credentials.

Deactivating via Controller Webserver

The Modicon LMC058 Motion Controller, Modicon M241, M251, M258 Logic Controller, and the Modicon M262 Logic/Motion Controller allow you to deactivate the device user rights management via the embedded webserver:

MAINTENANCE > USER MANAGEMENT > USER ACCOUNTS MANAGEMENT > DEACTIVATE

Consult the *Programming Guide* specific to your controller in the EcoStruxure Machine Expert online help for further information:

- **Modicon LMC058 Motion Controller**
Machine Expert > V1.2 > Controllers > LMC058 Motion Controllers > LMC058 Motion Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- **Modicon M241 Logic Controller**
Machine Expert > V1.2 > Controllers > M241 Logic Controllers > M241 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- **Modicon M251 Logic Controller**
Machine Expert > V1.2 > Controllers > M251 Logic Controllers > M251 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- **Modicon M258 Logic Controller**
Machine Expert > V1.2 > Controllers > M258 Logic Controllers > M258 Logic Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server
- **Modicon M262 Logic/Motion Controller**
Machine Expert > V1.2 > Controllers > M262 Logic/Motion Controllers > M262 Logic/Motion Controller - Programming Guide > Ethernet Configuration > Ethernet Services > Web Server

Deactivating User Rights for the Simulation Device in EcoStruxure Machine Expert Logic Builder

The simulation device in EcoStruxure Machine Expert Logic Builder has own user rights that can differ from those that are defined in the real controller.

NOTE: To help avoid account lockout (deadlocking), first disconnect EcoStruxure Machine Expert Logic Builder from the controller and make sure no other client, for example, an HMI, automatically attempts to connect using the previous user rights configuration.

In order to deactivate user rights in the simulation device, proceed as follows:

Step	Action
1	Close all instances of EcoStruxure Machine Expert Logic Builder.
2	Close all instances of Vijeo-Designer.
3	Remove the folder c:\ProgramData\CODESYS\Simulation. Result: The simulation device is reset to the default settings.

Managing Device User Rights by Call Parameters

Overview

The service tools Controller Assistant and Diagnostics provide command line arguments that are used to connect to a controller with the required credentials. For detailed information, refer to the Controller Assistant - User Guide and the Diagnostics - User Guide in the EcoStruxure Machine Expert online help.

The following arguments are available:

- `-username <Username>`
- `-password <Password>`
- `-renewalpassword <RenewalPassword>`

Examples

```
ControllerAssistant.exe -username Administrator -password  
Administrator -renewalpassword MyNewPassword  
-getcontrollerinfo etcp4://192.168.3.40  
Diagnostics.exe -username Administrator -password MyPassword  
-save ip etcp4://192.168.3.40 c:\Temp\MyDiagnosticsFile.pdi
```

`-renewalpassword` Argument

The argument `-renewalpassword` is used when a new password needs to be inserted. This is typically the case when the first login to a controller is performed and the default credentials (user name = `Administrator` and password = `Administrator`) are required.

The argument `-renewalpassword` cannot be used to change the password.

Starting Controller Assistant

Controller Assistant can also be started with graphical user interface using the command line arguments. In this case, you are not prompted to enter the credentials. They are retrieved from the values of the arguments.

Managing Device User Rights Using the Scripting API

Scripting for Using Online Services

EcoStruxure Machine Expert provides access to many of its online services via the scripting API. In order to establish a connection or to use an online service at a later time, valid credentials must be stored in the system.

Providing Specific Credentials for Online Services

You can store credentials via online device or online application in case of multi-controller projects. If there are specific credentials provided for the connection, they will be used by the system.

Example:

```
# create an "online device" to use online services  
root_device = projects.primary.find("LMC_PacDrive", False)  
[0]  
online_device = online.create_online_device(root_device)  
  
# store credentials specific to this "online device"  
online.set_specific_credentials(online_device, "my_user",  
"my_password")  
  
# use of any online service  
online_device.connect()
```

Providing Default Credentials for Online Services

If no specific credentials are provided for the connection, the system uses the default credentials.

Example:

```
# create an "online device" to use online services
root_device = projects.primary.find("LMC_PacDrive", False)
[0]
online_device = online.create_online_device(root_device)

# store default credentials
online.set_default_credentials("my_user", "my_password")

# use of any online service
online_device.connect()
```

Scripting for Enforced Password Renewal

The following scenarios require the password to be changed by the user after authentication:

- First login to a new controller.
- First connection after the user rights management has been reset to default.
- A password renewal is enforced for a specific user by an administrator of the device.

EcoStruxure Machine Expert does not support the renewal of passwords using the scripting API. Perform this by using the service tool Controller Assistant.

You can call the latest version of Controller Assistant from command line as indicated in the following example:

```
"c:\Program Files (x86)\Schneider Electric
\EcoStruxureMachine Expert\Tools\ControllerAssistant
\ControllerAssistant.exe" -username Administrator -password
Administrator -renewalpassword MyNewPassword
-getcontrollerinfo etcp4://192.168.3.50
```

Including User Rights While Cloning the SD Card

Overview

The Modicon M241 Logic Controller, Modicon M251 Logic Controller, and the Modicon M262 Logic/Motion Controller provide a clone function that allows you to write the image of the controller to an SD card. By default, the user rights management is not written to the SD card with the image. If supported by your controller, you can activate the user rights management for the clone procedure in the **Clone management** on the webserver of the controller. Consult the *Programming Guide* specific to your controller for further information.

Including User Rights While Cloning the USB key

Overview

The Modicon M258 Logic Controller and Modicon LMC058 Motion Controller provide a clone function that allows you to write the image of the controller to a USB key. By default, the user rights management is not written to the USB key with the image. If supported by your controller, you can activate the user rights management for the clone procedure in the **Clone management** on the webserver of the controller. Consult the *Programming Guide* specific to your controller for further information.

Hardware/Firmware Information V1.2.7

Hardware/Firmware Information

There are no additional hardware/firmware information for this release.

Library Information V1.2.7

Library Information

Version Identification

Description	Version
IoDrvEthernetIpScanner	V1.54.1.18

Mitigated Anomalies

PacDrive LMC Controls & I/Os

ID	Description
LMCFW-4090	Invalid I/O mapping for TM5 EtherNet/IP bus coupler has been solved.

Known Operational Anomalies

PacDrive LMC Controls & I/Os

ID	Description
BTE-1087	Modules connected after a 'dummy' module are unresponsive.
BTE-1088	Potential incorrect behavior when using TM5 EtherNet/IP bus coupler with analog modules configured for current measurement. Workaround: First select all channels to Voltage and then back to Current.
BTE-1091	Disabling of slices connected to TM5 EtherNet/IP bus coupler may lead to an error. Workaround: Instead of 'Disable' use 'Exclude'.
LMCFW-2820	Incorrect status display of the TM5 EtherNet/IP bus coupler: Running is displayed instead of Error . The message <i>Sending SpecificMessage failed. 1#C008</i> can be acknowledged. Workaround: Monitoring via the application is possible.

Software Information V1.2.7

Software Information

There are no additional software information for this release.

Release Notes History

EcoStruxure Machine Expert V1.1

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M241	5.0.7.20
M251	5.0.7.20
M262	5.0.2.1
TMSES4	1.0.0.8
TM3BCEIP	1.2.1.1
TM3•HSC202•	2.0
TM3DI16	2.0
TM3DI16G	2.0
TM3DI16K	2.0
TM5NS31	2.74
LXM32S•••M2 drive	1.06.03
LXM32S•••M2 Sercos	1.08.04
LXM32S•••N4 drive	1.06.03
LXM32S•••N4 Sercos	1.08.04
LXM52••••C•••••	1.54.26.0
ILM••••••••••••••	1.54.26.0
LXM62••••C•••••	<ul style="list-style-type: none"> • 1.60.0.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62••••D•••••	<ul style="list-style-type: none"> • 1.60.0.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62••••E•••••	1.54.27.0
LXM62••••F•••••	1.54.27.0
LXM62••••G•••••	1.60.1.0
LMC Eco	1.60.3.3
LMC Pro	1.60.3.3
LMC Pro2	1.60.3.3

Description	Safety-Related Firmware Version
LXM62••••E•••••	1.2.4.0
LXM62••••F•••••	1.2.4.0
VW3E702200000 safety option module	1.2.4.0
TM5CSLC100FS	2.52
TM5CSLC200FS	2.52
BWU2984 SWID	134253
BWU2984 Safe CPU A	135115
BWU2984 Safe CPU B	135116
ASIMON360	3.2.6.7

Safety-Related Products

Additional information on the Safety Option Module VW3E702200000 for Lexium 62 ILM:

Lexium ILM070, ILM100 and ILM140 motors must have a certain hardware revision of the electronic unit and a new FPGA (field-programmable gate array) to be compatible with the Safety Option Module for Lexium 62 ILM.

The new revision is included in Lexium ILM motors with the following S/N and DOM:

- ILM070: S/N \geq 2506064503 (DOM \geq 11.09.2015)
- ILM100: S/N \geq 2506058831 (DOM \geq 18.08.2015)
- ILM140: S/N \geq 2506059644 (DOM \geq 21.08.2015)
- New FPGA version: CB0013_D010_0109_00_04

When using earlier versions of the Lexium ILM, the Safety Option Module is not recognized, and the drive does not start.

For PacDrive architectures the AS-i/Sercos III Safety Gateway BWU2984 is integrated. For more information, refer to the AS-i/Sercos III Safety Gateway BWU2984 for Embedded Safety System - Bihl+Wiedemann Integration Guide.

Performance and System Limitations of New TM5CSLC•00FS Firmware Version

The new TM5CSLC•00FS firmware version delivered with EcoStruxure Machine Expert V1.1 has some performance improvements in relation to previous TM5CSLC•00FS firmware versions.

The total number of safety axis and safety I/Os in a system depends on several factors such as, for example, Sercos cycle time, activated/simulated devices, configured devices in the architecture, and local device configurations using additional IDNs, local I/Os on drives, etc. When the system limit is reached, a C1D C30F 0109 hex is triggered.

The supported axis in a system running on the edge of device limitations can vary between boot up by ± 1 . Therefore, it is a good practice to stay two axis away from the detected system limit.

For more information on performance refer to System Limitations (see Embedded Safety for M262, Integration Guide).

Contact your local Schneider Electric representative in case you need specific information for your intended machine architecture.

New Features

M241/M251

- Support of CoDeSys V3.5 SP12
- Default login/password changed when user rights are not activated.
- User right management adapted to CoDeSys V3.5 SP12
- Support of TM3BCEIP TM3 EtherNet/IP bus coupler for distributed I/O architectures
- Behavior of outputs in STOP mode: default value applies after application download, controller power cycle, reset cold/warm
- Behavior of outputs during the transitions from RUN to STOP, and from RUN to EXCEPTION also sets default output values
- Support of TM3DI16/G and TM3DI16K renewal modules (latch and filter functions are only configurable with modules of software version 2 or greater).
- Support of FC_GetFreeDiskSpace, FC_GetLabel, FC_GetTotalDiskSpace

- Extended Motion Function Blocks to allow the configuration of 4 *JerkRatio* parameter settings.

M262

Modicon M262 Logic/Motion Controller offer is made for performance - demanding machines.

- M262 controllers are ready for IIoT, (MQTT, AMQP, OPC UA, TLS,...) and combine logic, motion and safety-related control applications:
 - TM262L: for the logic control of multiple input and output configurations
 - TM262M: for the motion control of up to 16 synchronized axes
In combination with a TM5CSLC•00FS for safety-related control applications up to SIL3.
- Modicon M262 Logic/Motion Controller embed 4 fast digital inputs and 4 fast digital outputs, connected to the controller with the use of screw terminals on the front face of controllers.
- Modicon M262 Logic/Motion Controllers (TM262M•••) embed an encoder input (SSI or incremental).
- Modicon M262 Logic/Motion Controllers can be combined with Modicon TM3, Modicon TM5, and Modicon TM7 offers using Sercos III, EtherNet/IP and CANopen bus couplers.
- Modicon M262 Logic/Motion Controllers have a Dual Core processor:
 - Core 1: is dedicated exclusively to managing program tasks and offers the maximum resources for real-time execution of the application code.
 - Core 2: is dedicated to executing communication tasks, which then have no further impact on the application execution performance.
- Performance:
 - 256 MByte RAM memory
 - 128 MByte Flash memory
 - 3-5 ns/ instruction
- A slot for an industrial memory card is available on the front face of the controllers:
 - SD-card up to 2 GB, or
 - SDHC-card up to 32 GB
- A QR-code, printed on the front face of the controllers and Smart Communication modules, provides a link to the Schneider Electric maintenance page of the product.
- A TMS bus port allows the connection of Smart Communication modules, assembled by simple interlocking on the left-hand side of the controllers.
- A TM3 bus port allows the connection of TM3 expansion modules, assembled by simple interlocking on the right-hand side of the controllers.

PacDrive LMC Controls

- Watchdog supervision during I/O-update:
 - Watchdog was deactivated during the cyclic execution when I/Os were updated. Now the watchdog stays active during I/O-updates.
 - If a given limit for I/O updates is exceeded, a watchdog is triggered.
- PROFINET:
 - The consumer and provider statuses (CS and PS) are now available in the application. The provider status appears in the tab **PNIO Module I/O Mapping**.

NOTE: Verify the direct call of % addresses in your application. The preferred solution to access the % addresses in your application is to map variables to all the % addresses.

Accessories TMS

The TM262 Logic/Motion Controllers allows to connect 3 TMS communication modules.

TM3 EtherNet/IP Bus Coupler

TM3 EtherNet/IP Bus Coupler is a distributed architecture solution, which enables the creation of distributed islands of industrial TM3 I/Os managed by a master controller M241, M251 or M262 via Ethernet fieldbus.

New features:

- The TM3 EtherNet/IP bus coupler supports TM3 and TM2 I/O modules:
 - Up to 14 TM3 I/O modules
 - Up to 7 TM2 I/O modules
 - Up to 7 TM2 I/Os mixed with TM3
- The TM3 EtherNet/IP bus coupler has an embedded webserver which supports:
 - User rights management
 - BOOTIP, DHCP, fixed IP-configuration
 - Bus coupler firmware update
- The TM3 EtherNet/IP bus coupler has an embedded switch with isolated RJ45 ports to support daisy chaining and ring topologies (RSTP/SNMP).
- The TM3 EtherNet/IP bus coupler provides cyber security protection features supporting Achilles level 1.

Limitations:

- Latch feature is not supported for TM3DI16, TM3DI16G, TM3DI16K.
- TM3 expert I/O are not supported.
- Only single user can modify the firmware update or write values through embedded webserver.
- The maximum number of TM3 I/O modules will be validated by software and may result in a lower number, depending on the number of analog I/O modules used.

TM3 Expert I/O

The TM262 Logic/Motion Controller supports 4 types of high speed counting modules:

- TM3XFHSC202
- TM3XFHSC202G
- TM3XHSC202
- TM3XHSC202G

These modules are connected on the right side of the controller and allow management of 2 counting channels with / without reflex output.

TM3XFHSX202 / TM3XFHSX202G can be configured to raise events in the controller to manage fast actions.

The firmware of the I/O module can be updated by the controller.

Limitations:

The TM3XFHSC202 / TM3XFHSC202G and TM3XHSC202 / TM3XHSC202G high speed counting modules are not supported by M241/M251 logic controllers nor the TM3 EtherNet/IP bus coupler

TM3 Standard I/O

New hardware revision for TM3DI16, TM3DI16G, TM3DI16K.

These new TM3 I/O modules are supported by M241, M251, M262 and TM3 EtherNet/IP bus coupler and support new features:

- Configurable input filter
 - The input acquisition time filter can be adjusted to allow fast input signals (0.3 - 12 msec).
- Input latch function
 - The input latch function allows to capture input signals with short durations and memorize the state till the next controller task execution.
 - This feature is not supported by the TM3 EtherNet/IP bus coupler.
- Firmware upgrade
 - The firmware of the I/O-module can be updated by the controller.

LXM32S Servo drives

The Lexium 32 product family consists of various servo drive models that cover different application areas. Together with Lexium BMH servo motors or Lexium BSH servo motors, as well as a comprehensive portfolio of options and accessories, the drives are suited to implement compact, high-performance drive solutions for a wide range of power requirements.

New features:

- Sercos module firmware update with Device Assistant
- Diagnostic object S-0-0390 can be mapped to the realtime data, showing C1D / C2D with corresponding error number
- IP-settings coming from Sercos become valid without powercycle
- DS402 statusword P-0-3027.0.2 can be mapped to the real-time data.
- Support of ProfileTorque mode with target value via parameter
- Support of PTI/PTO Torque mode
- Support of index pulse with SinCos1Vpp as machine encoder
- Controlled ramp down when drive will be disabled
- Locate device function by commissioning the SoMove configuration software
- SIN/COS values are traceable
- Error class for error A344 can be defined when using machine encoder for position control.

LXM32S Firmware Version Requirements

The LXM32S firmware is not automatically updated from M262. Therefore, the following firmware version requirements must be met:

- Drive firmware: V1.06.03 or later
- Sercos module firmware: V1.08.04 or later

If the firmware does not meet these requirements, it must be updated. For performing the firmware update, please contact your local Schneider Electric representative.

Lexium 62 Standard Plus and Advanced Plus System Integration

- System integration of the LXM62 Standard Plus and Advanced plus drive within the basic object Lexium LXM62 Drive.

- New configuration tab **Feature Configuration** to select the **DeviceVariant** within the drive object.

DeviceVariant for Lexium 62:

DeviceVariant type	Description
Standard	Standard Lexium 62 functions are available. No additional user functions.
Standard Plus	Additional Standard Plus user functions are supported.
Advanced Plus	Additional Advanced Plus user functions are supported.
Application defined	<ul style="list-style-type: none"> • Selection of the available user functions. • Possibility to create a generic project. • Configuration of the device variant type via IEC before the Sercos phase-up check.

During Sercos phase-up, PacDrive LMC Pro, PacDrive LMC Pro2 and PacDrive LMC Eco verifies if the configuration matches with the connected physical devices.

User functions

The new concept allows you to select the new drive-specific features with EcoStruxure Machine Expert inside the **Lexium LXM62 Drive** object. After selecting the **DeviceVariant** type in the **Feature Configuration** tab, the supported user functions are visible in the user interface and can be activated with the check box or using the IEC application. After the activation of a user function, the corresponding parameters appear in the parameter editor and can be used in the IEC application.

Supported features of LXM62 Standard Plus:

Feature	Description
Brake check functions (new system interface library functions)	<ul style="list-style-type: none"> • FC_BrakeCheckGetState(...) • FC_BrakeCheckSet(...) Verify whether the coupled brake is able to hold its specified torque.
Encoderless velocity control	<ul style="list-style-type: none"> • Support of BMP servo motors without encoder • Open-loop control for low velocity. The current is pre-defined by the drive and displayed by the object parameter <i>StartingRefCurrent</i>. You can adjust it with object parameter <i>UserStartingRefCurrent</i>. • Closed-loop position control for high velocity. The required velocity for the closed-loop control is displayed by the object parameter <i>MinimalOperatingVelocity</i>.
Torque limitation	Two new modes available: acceleration-dependent torque limitation and mechanical overload protection. <ul style="list-style-type: none"> • Both configurations allow to limit the torque on load side. • The functionality is enabled and switched with the object parameter <i>TorqueLimitationMode</i>. • The torque levels are set by the user with two object parameters <i>AccelerationTorqueLimit</i> and <i>DecelerationTorqueLimit</i>. • In mechanical overload protection mode, the motor is switched to torque free, when the adjusted torque is exceeded on the load side. It can be filtered to adjust the sensitivity. • In acceleration-dependent torque limitation mode, the torque on the load side is limited.

Supported features of LXM62 Advanced Plus:

- All features for LXM62 Standard Plus
- Incremental Encoder Output
Encoder signal reflection of motor encoder or machine encoder.
- Machine Encoder Input

The Machine Encoder Input is only used for the position control in the drives control loop.

Supported features of the *UserMotorTypePlate* library:

- *FB_InitMachineEncoder*
POU to initialize the machine encoder type plate for LXM62 Advanced Plus.

Fast Device Replacement

- Support of the new Lexium LXM62 Drive Standard Plus and Advanced Plus with fast device replacement.
- A message logger entry is added if the configuration and physical device do not match.

Lexium ILM62 Integrated Servo Drives

Multiaxis integrated servo drives from 0.31 to 1.91 kW for automation solutions based on PacDrive 3.

Mitigated Anomalies

PacDrive LMC Controls & I/Os

ID	Description
OEM00069352 / LMCFW-1153	For the TM5 modules TM5SE11C20005 and TM5SE1MISC20005, the counter data type is corrected (DWORD).
OEM00069411 / IECLIB-1547	Functions returning a large amount of data (for example, with an ARRAY[0..1023] OF STRING[255]) triggered a watchdog error message.
OEM00070481	After a project download, the EtherNet/IP scanner started with the diagnostic message: <i>Module not found</i> .
OEM00071401 / LMCFW-1985	TM5CSLCx00FS (Safety Logic Controller) did not start if the SLC was the first device in the Sercos ring.
OEM00071989	A <i>Not enough memory on device</i> exception detected in a Logic Motion Controller during download triggered a watchdog error message.
OEM00074169	An OPC UA server detected a <i>page fault</i> in the Logic Motion Controller when an OPC UA client initialized an OPC UA item with the value <i>OPC_Quality_BadWaitingForInitialData</i> .
OEM00076495 / LMCFW-1184	The internal function <i>TranslateBrowsePathsToNodeIds</i> of the OPC UA server terminated with an error and returned the diagnostic code <i>BadNoMatch</i> during a client request.

Lexium52 / 62 / 62 ILM

ID	Description
OEM00055840	Lexium 62 Double Drive with two different <i>InverterEnable</i> : A rising edge on the <i>InverterEnable</i> input for drive B caused a peak current in drive A. The diagnostic message <i>8107 Overcurrent</i> was displayed and a jerk was detected in drive A.
OEM00074423	A new Lexium 62 firmware was successfully updated with a legacy Device Assistant . Nevertheless, the drive did not operate after the update. No diagnostic message was displayed.

M241/M251

ID	Description
OEM00060178	Different versions of the <i>IoDrvModbusSerial</i> library were added to the Library Manager when using the Modbus IO Scanner with different controllers.
OEM00063394	After disconnecting the CANbus connection of a J1939_ECU device, the device in the Devices tree was still displayed in green color and the status of the J1939_ECU device was still displayed as running.

ID	Description
OEM00066740	The Task Configuration > Monitor tab displayed more tasks than the number of tasks that had been configured.
OEM00068203	The Input Assistant did not provide instances of the HSCSimple counter.
OEM00068334	Configuring fast outputs (pulse generators) for an M241 controller caused a shutdown of the programming software.
OEM00069524	The Relocation Table editor allowed to assign variables outside of the dynamic memory area (read and write).
OEM00069581	Relocation Table : Downloading an application was possible even though the relocation table provided invalid values.
OEM00071569	The NetManage tool provided incorrect information when connected to an M241 controller by a TM4ES4 Ethernet communication module.
OEM00073294	Using a PTO (Pulse Train Output) with an M241 controller configured in homing mode <i>ShortReference_Reversal</i> did not operate correctly. The movement did not end as intended.
OEM00075330	FDR (Fast Device Replacement) service authentication is successful now when IP mode is set to DHCP.
OEM00072090	Using the Modbus TCP IO Scanner , the inputs no longer keep the former values after an application download.
OEM00076970	EtherNet/IP Scanner is more stable now after an online change (no timeout).
OEM00077608	The file system is no longer corrupted after multiple manually executed HTTP requests with long URL addresses.
OEM00077471	Using the <i>FB_ControlClone</i> (to control cloning of a M241 controller) is possible now when the user rights are activated.
OEM00072657	X-Frame-Options header is now protected against clickjacking (user interface redress attack).
PEP0502989R	Communication with Festo motor controller CMMO/CMMP devices can be established now.
PEP0310789R / PLAT-239	The Modbus TCP connection timeout is adjusted now.
PEP0351007R / PLAT-337	The Ethernet connection is interrupted no longer when receiving Modbus TCP requests not written correctly.
PEP0439107R	The communication between the Controller Assistant and an M241 controller is possible now when connecting to the second ETH2 network interface.
PEP0408448R	Misleading error log messages in the M241 controller log file are removed.
PEP0428747R	The status of the homing function block is correct now when using homing mode 20.
PEP0444388R	Loading/storing of data parameters table in the webserver is improved.

Library Information

Version Identification

Description	Version
ApplicationLogger	1.1.2.0
AsyncManager	1.0.5.0
AutoTune	1.3.14.0
Booster Pumping	5.0.0.5
CommonMotionTypes	1.0.1.0
CrankModule	1.3.4.0
EMailHandling	2.0.4.0
EtherNetIP Explicit Messaging	1.1.7.0
EtherNetIP Remote Adapter	1.0.10.0

Description	Version
FileFormatUtility	1.2.6.0
FtpRemoteFileHandling	1.2.3.0
GMC Independent Altivar	1.2.4.0
GMC Independent Lexium	1.1.7.0
GMC Independent PLCopen	1.2.3.0
HttpHandling	1.0.11.0
M262 Encoder	1.0.0.2
M262 PLCSystem	1.0.0.19
M262Diagnostics	1.0.1.0
MotionInterface	1.0.69.5509
MqttHandling	2.0.6.0
PackML	1.2.3.0
PD_AxisModule	1.6.2.0
PD_EDesignAxisModule	2.3.2.0
PD_EdesignCore	2.2.6.0
PD_EdesignCrankModule	1.5.2.0
PD_ETest	1.3.6.0
PD_GlobalDiagnostics	1.3.1.0
PD_MultiBelt	1.4.2.0
PD_MultibeltModule	1.4.1.0
PD_PacDriveLib	1.8.7.0
PD_SmartInfeed	1.4.3.0
PD_SmartInfeedModule	1.3.1.0
PD_SoMotionGenerator	1.5.1.0
PD_Template	1.6.1.0
PLCopen MC part 1	1.0.69.5509
PreventaSupport	1.1.1.0
Robotic	2.12.1.0
RoboticModule	2.8.0.0
SchneiderElectricRobotics	2.8.0.0
SchneiderElectricRobotics Parameters	2.9.0.0
SchneiderElectricRobotics Toolbox	1.2.0.0
SercosCommunication	1.0.1.0
SercosDriveUtility	1.1.1.0
SercosMaster	1.0.69.5509
SlcRemoteController	1.3.6.0
SnmpManager	1.2.1.0
SqlRemoteAccess	1.1.2.0
TcpUdpCommunication	2.0.11.0
TeSys island	1.1.0.0
TimeSync	1.1.2.0
Toolbox	3.2.1.0
TwidoEmulationsupport	1.2.2.0

Description	Version
Unwinder	1.2.2.0
UnwinderModule	1.1.0.0
UserMotorTypePlate	1.3.9.0
UserTorqueFeedForward	1.1.2.0

Version Identification Safety Libraries

Description	Version
EnableSwitch_SE_SF	V0.99 from 10/28/15
PLCopen_SF	V1.00 from 09/14/07
Preventa_SafeMotion	V0100.0100 from 02/08/16

New Features

ApplicationLogger

The controller related dependencies are deleted. The library is now also working on M2•• controllers.

AsyncManager

Offers the functionality to call time-intensive jobs asynchronously to help prevent cycle time overruns without the need to create additional tasks separately.

CommonMotionTypes

This library supports common motion data types independent of the controller platform.

EmailHandling

- The function block `FB_SendEmail` provides parameters for recipients of type CC and BCC.
- Improved online modification behavior:
 - All function blocks in the library can detect an online modification of the application.
In the event of a detected online modification while the function block is in progress, all input parameters of type REFERENCE TO and POINTER TO are updated.
 - New global variable `SE_Email.GCL.G_xOnlineChangeAllowed` indicates if an online modification can be performed in executed function blocks out of the EmailHandling library.

FileFormatUtility

- Added function block `FB_CreateJsonFormattedString` which is used to facilitate the creation of a text STRING in JavaScript Object Notation (JSON) format.
- Added function block `FB_WriteFile` which is used to write or append content into a new or existing file on the file system of the controller.
- Improved online change behavior:
 - All function blocks in the library can detect an online modification of the application.

In the event of a detected online modification while the function block is in progress, all input parameters of type REFERENCE TO and POINTER TO are updated.

- New global variable `FFU.GCL.G_xOnlineChangeAllowed` indicates if an online modification can be performed in executed function blocks out of the FileFormatUtility library.

GMC Independent Altivar

- Support for ATV32 and ATV71 are removed.
- Improvement of the function blocks `SetDriveRamp_ATV` and `SetFrequencyRange_ATV`: Errors resulting from write requests inside the function block abort subsequent write commands and will no longer cause communication deadlock.

GMC Independent Lexium

- Integration of LXM32 and ILX CANopen drives.
- Improvement of the function blocks `SetDriveRamp_LXM` and `SetDriveRamp_ILX`: Errors resulting from write requests inside the function block abort subsequent write commands and will no longer cause communication deadlock.
- Integration of Lexium SD328A (CANopen).

GMC Independent PLCopen

`ET_DeviceType` to use this Enum together with the `AxisRefBase` to identify the added axis type.

HttpHandling

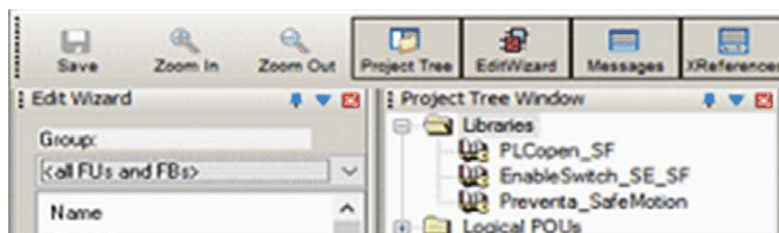
New library providing HTTP client with GET and POST commands.

Library EnableSwitch_SE_SF

The safety-related `SF_EnableSwitch` function block evaluates the signals of a manually actuated three-stage enable switch (in accordance with EN 60204) to identify its switching stage and direction.

Library PLCopen_SF

The safety-related functions or function blocks described within this library are solely intended for creating safety-related code for suitable Safety Logic Controllers using EcoStruxure Machine Expert - Safety software. You can only combine your safety-relevant tasks within the safety-related control system if the tasks are integrated into the execution process in a correct and functionally safe manner as defined in the applicable standards.



Library Preventa_SafeMotion

The safety-related `SF_SafeMotionControl` function block acts as an interface between the Safety Logic Controller and the Safety Module (option module) which is the safety-related component of the ILM62 or LXM62 standard drive.

M262Diagnostics

Library added to gather system information on the M262 controller application and the configured devices in it.

M262 Encoder

Library added to support standard encoder input service for M262 controller.

M262 PLCSystem

Library added to provide read & write services for M262 controller.

MachineAssistantServices

Library added to provide functionality to discover Ethernet devices connected to the controller and to perform commands to detected devices.

MotionInterface

Library added to affect low level access for motion control for M262M•5 controllers.

MqttHandling

- Library added to provide the MQTT client functionality to exchange data with other devices over the network through an MQTT message server.
- Includes feature to establish an encrypted connection to a TCP server.

PackML

- Library is updated to support the ANSI/ISA TR88.00.02-2015.
 - Two new POUs, `FC_SetWarning` and `FC_GetDateTimeAsArray`, are provided accordingly.
 - Five new frame visualizations, `FR_StateDisabled`, `FR_AlarmSingleLine`, `FR_AlarmHistorySingleLine`, `FR_DateTimeDisplay` and `FR_Warning`, are provided accordingly.
- The variable `GPL.Gc_uiNumberOfMaterials` has been removed.
- The background colors for offline mode in the provided visualizations corresponds now to the color which becomes effective in online mode.
- `FB_ModeManager`:
 - In the event of a detected error during execution (`q_xError = TRUE`) the output `q_xError` is reset.
 - The values of the inputs `i_diUnitMode` and `i_diStateCurrent` are verified only upon a rising edge of `i_xUnitModeChangeRequest`.
 - A rising edge of the inputs `i_xUnitModeChangeRequest` and `i_xModeChangeDone` is detected only if output `q_xReady` is `TRUE`.
 - Upon a falling edge of the input `i_xUnitModeChangeRequest`, a detected error during latest execution is reset. A restart of the function block is no longer required.

PD_PacDriveLib

The PacDriveLib Homing functions and function blocks are prepared for use with MachineEncoder. If the MachineEncoder is active, then the EncoderPosition from the MachineEncoder is used for homing.

PLCopen MC part 1

Library added to provide motion control according to PLCopen Motion Control Part 1 v2.0 (formerly parts 1 and 2) for M262M•5 controller.

PreventaSupport

Library added to support diagnostic and maintenance tasks for Preventa safety-related modules.

Robotic

Library added to provide a collection of POU's for controlling robot kinematics.

The following kinematics can be controlled:

- Triaxial delta robot - `IF_RobotConfiguration.Delta3Ax`
- Triaxial cartesian robot - `IF_RobotConfiguration.Cartesian3Ax`
- Biaxial cartesian robot - `IF_RobotConfiguration.Cartesian2Ax`
- Biaxial delta robot - `IF_RobotConfiguration.Delta2Ax`
- Biaxial articulated robot - `IF_RobotConfiguration.Articulated2Ax`
- Four axial SCARA robot - `IF_RobotConfiguration.Scara4Ax`
- Up to triaxial user-defined robot - `IF_RobotConfiguration.User3Ax`

Motion interpolation in order to move to a point in two or three-dimensional space:

- Linear interpolation - `IF_RobotMotion.MoveL`
- Circular interpolation - `IF_RobotMotion.MoveC`
- Spline interpolation - `IF_RobotMotion.MoveS`
- Joint interpolation - `IF_RobotMotion.MoveJ`

RoboticModule

Library added containing the equipment module for the default PacDrive 3 template and auxiliary functions. It includes the functionality of the Robotic library.

- The interfaces of the provided equipment module enable an integration into the default PacDrive 3 template.
- RoboticModule provides the operation modes Auto, Homing, Manual and BrakeRelease.

SchneiderElectricRobotics

Library added containing function blocks to parametrize a Schneider Electric robot.

SchneiderElectricRobotics Parameters

Library added containing the parameters for a Schneider Electric robot.

SchneiderElectricRobotics Toolbox

Library added to provide provides structures, functions and function blocks for the following purposes:

- Read the protocol of a camera.
- Send data, for example, to simulate the protocol of a camera.
- Generate random Cartesian poses.
- Parameterize and generate a list of targets.

SercosDriveUtility

Library added to read and write drive configurations using the Sercos III fieldbus network.

SercosMaster

Library added to provide low level access to the Sercos master for M262M•5 controllers.

SlcRemoteController

- The command `ET_UserCommand.SetSafeKeyPassword` added for the function block `FB_RemoteController`, to allow setting or modifying the password on the `SafeKey`.

Execute this command to set a password before downloading the application using the function block `FB_DownloadApplication`.

- The library is compatible with M262 by substitution of `PacDriveLib` dependency with generic `AsyncManager`.

TcpUdpCommunication

- Fix of an anomaly in buffer handling on receiving messages with fill level greater than 65535 bytes.
- Corrected behavior: In case of an interruption of the connection while sending or receiving data, the property `State` indicates `ShutDown` and the property `Result` indicates `ClosedByPeer`.
- The property `IsReadable` is reset if the connection is interrupted.
- The function block `FB_TcpClient` provides the property `SocketOpt_CustomPort` which is used to specify the port used by the client for the next connection.
- The function block `FB_TcpServer` provides the property `SocketOpt_LingerEnabled`. This property is used to enable or disable the socket option `Linger` influencing the behavior on closing a connection.
- The processing of methods is no longer influenced by online monitoring of certain properties at the same time.
- The library offers functionality to establish TLS encrypted TCP connections.

TeSys Island

- Library added to provide function blocks to develop applications for TeSys island.
- The function blocks manage the digital functional object known as Avatar by:
 - `controllingAvatars`.
 - reading diagnostic information from Avatars.
 - reading energy data from Avatars.

- reading asset data from individual modules of TeSys island.

UserMotorTypePlate

The function block `FB_InitMachineEncoder` is included to initialize the machine encoder with a typeplate (the machine encoder object is available on Lexium 62 Advanced Plus).

Examples

New example projects:

- XML file handling example
- CSV file handling example
- Email handling example
- MQTT example using JSON format
- Machine Advisor communication example

Updated example projects:

- PackML example updated according to the library update
- RTC TimeZone example with SNTP client
- SLC remote controller example

New function template:

- HTTP client

Mitigated Anomalies

Libraries

ID	Description
OEM00052518 / IECLIB-1631	<i>MTP.FB_MotorDataRead</i> : Improved diagnostic message if no type plate is stored in the drive.
OEM00071708 / IECLIB-1551	PacDriveLib library: After disabling the function blocks <i>FB_HomeForce</i> and <i>FB_HomeTorque</i> , all outputs are reset.
OEM00071904 / IECLIB-1349	MultiBelt Library: The parameter <i>xLeaveStation</i> of <i>ST_Station</i> is now compatible with indexed stations.
OEM00075161 / IECLIB-1771	SmartInfeed library: After <i>SI.FB_Infeed.i_xStart := FALSE</i> , the state machine is now finished correctly. To achieve this, a new GPL parameter was added: <i>Gc_IrMasterMotionActiveVelLimit</i> Internal velocity limit parameter to verify in <i>FB_Infeed</i> if the master of the <i>InfeedBelt</i> is in motion.
OEM00060445 / IECLIB-1348	TcpUdpCommunication library: You can access the properties of the <i>FB_TcpServer</i> function block from different tasks. The <i>InputOutOfRange</i> message is no longer reported.
OEM00069263 / IECLIB-957	EMailHandling library: By setting <i>GVL.Gc_udiMaxNumberOfAttachmentPaths</i> to a value greater than one, the function block can receive more than one email.
OEM00064768 / IECLIB-404	GMC Independent Altivar library and GMC Independent Lexium library: You can use now <i>ET_DeviceType</i> together with <i>AxisRefBase</i> to identify an added axis type.
OEM00043940	IoDrvModbusSerial library: It is now possible to write a single register and to initialize a server.
IECLIB-1708	GMC Independent Altivar library: Active movements of Altivar drives are stopped now if the application is set to stop.

Software Information

Version Identification

Description	Version
Machine Expert Installer	11.19.16801
Diagnostics	18.0.10.0
Controller Assistant	18.0.10.0
Device Assistant	18.0.10.0
DiffViewer	18.0.10.0
Gateway	18.0.10.0
Launcher	18.0.10.0
OPCServer	3.5.12.70
SoftSPS	3.5.12.80
SVN	4.2.4.0
Logic Builder ⁽¹⁾	1.1
Vjeo-Designer	6.2.8.1016
CoDeSys	V3.5 SP12 Patch8 HF1
SQL Gateway	18.0.1.0
Motion Sizer	4.1.0.0
(1) If using a virtual machine, the download of the online help operates correctly only if the option Accelerate 3D graphics is deactivated in the VM settings.	

New Features for Machine Expert Installer and Online Help

Machine Expert Installer

The Machine Expert Installer provides an intuitive user interface to perform an online installation. During installation phase, you can select required sets which will be automatically downloaded and installed.

You can also use the Machine Expert Installer to customize an existing installation of the EcoStruxure Machine Expert product.

Online Help

With EcoStruxure Machine Expert, the online help is published as HTML5 help only on a Web server. You can download a local copy of the online help using Machine Expert Installer.

Known restrictions on different browsers used with the HTML5 help:

Browser and Version	Restriction	Workaround
Internet Explorer V11	Poor graphic / display quality	–
	If the HTML5 help is located on a local PC, then: <ul style="list-style-type: none"> • Contents are blocked. • Help pages cannot be opened. NOTE: When the HTML5 help is located on the Web, the restrictions do not exist.	<ol style="list-style-type: none"> 1. Open the Internet Explorer and go to Tools -> Internet Options. 2. Click the Advanced tab and scroll down to the Security section. 3. Enable the check box Allow active content to run in files on My computer.

Browser and Version	Restriction	Workaround
Chrome V63	<p>If the HTML5 help is located on a local PC, then:</p> <ul style="list-style-type: none"> Printing subtopics is not supported. Changing the topic language is not supported. <p>NOTE: When the HTML5 help is located on the Web, the restrictions do not exist.</p>	–
Edge V40	<p>If the HTML5 help is located on a local PC, then:</p> <ul style="list-style-type: none"> The contextual help opens only the individual topic, but not the HTML5 GUI. <p>NOTE: When the HTML5 help is located on the Web, the restrictions do not exist.</p>	–

New Features EcoStruxure Machine Expert

Project Update

- Project update categories are separated in single pages.
- Overview page summarizes the update actions: sufficient in most cases.
- Details for update of different parts of the system in separate tabs.
- Update of visualization styles added.
- Detailed information on library update enhanced by presenting the updated list of libraries.
- Display of progress status added.

NOTE: When you update a SoMachine project which contains solution libraries (Pumping, Packaging, Hoisting) to EcoStruxure Machine Expert, the solution libraries will not be updated. You have to replace the Pumping library manually by the Booster Pumping library. Hoisting and Packaging libraries are not supported by EcoStruxure Machine Expert V1.1.

Functional View

- A view has been introduced to group the project objects by logical machine units.
- These groups can be saved and re-used in other projects.

Smart Template

The Smart Template has been conceptually redesigned to open the framework beyond Robotics functionality.

The benefits of the revised version of Smart Template are:

- You can start to program with a default project and can add smart template functionality afterwards. Robotics projects can now be under SVN control and support folder structures.
- Can be used for more than one controller in a project. Smart Template functions or modules can be added to several controllers in a project.
- Supported SVN-functionality. Smart Template modules are handled in SVN (commit, update...) like any other POU in the system. Sub-elements (configuration, methods, ...) are considered appropriately.

- Smart Template is open for new IEC-frameworks. The modules are self-describing and no longer limited to a specific infrastructure like PacDrive Template. Basically any IEC-environment can be used from zero to maximum.

Supported Features:

- **Modules** view

Smart Template module instances can be added in an own view called **Modules**.

- **Add module / Add object**

Modules can be added using the **Add module** dialog providing more information and flexibility in terms of versioning, etc. Currently the following modules and objects are usable:

- Camera module
- Camera configuration
- Module interface
- Method
- Action
- Transition
- Notes

- **Module manager**

- Key element to manage several modules, their version and their referenced libraries.
- Modules can be updated as easy as libraries.
- The user code, the user configuration and the resolved library version are used to generate the code for smart template

- **Camera Module**

- Supports the known functionality to connect vision systems - generic cameras and specific for Cognex cameras.
- Online views allow to see the camera status, the position of products identified.

Migration Strategy of Smart Template

As the old Robotics for SmartTemplate-Framework is not supported any longer, the code and configuration has to be transferred to a new **Standard** project.

1. Create a new empty project in EcoStruxure Machine Expert.
2. Copy and paste the source code.
3. Add the modules to the new project via **Add module** and adapt the configuration according to the old project.

Code Analysis

Code Analysis add-on was improved and stabilized.

- New metrics (cyclomatic complexity)
- Compile messages as part of the convention results output.
- Analysis of libraries (POU-space analysis) is supported now.
- User interface and scripting API for machine advisor code analysis connection to upload snapshots and queries

ETEST

ETEST improves the usability and the handling of integration in Continuous Integration systems, especially when working with big and/or long running test projects.

- Optional test case methods

- The ETEST standard methods (**Prepare, Execute, Finalize, CleanUp**) are optional for test cases and test resources
- Test duration
 - The test results view shows the duration of each executed test case.
 - The exported result file contains the start, end time and duration of each test case.
- Test progress:
 - The result of each test case will be printed to the shell console, if executed via scripting.
 - You always know which tests are already finished in long-running test-series.

Diagnostics

- Diagnostics supports the Safe Logger for safety-related devices.
- Support for Lexium 62 Standard Plus and Advanced Plus.

Controller Assistant

Support for Lexium 62 Standard Plus and Advanced Plus.

Device Assistant

Support for Lexium 62 Standard Plus and Advanced Plus.

New Features for EcoStruxure Machine Expert - Safety

Overview

- EcoStruxure Machine Expert - Safety component distribution / installation using Machine Expert Installer together with the EcoStruxure Machine Expert components (Install new Software (Online) (see Schneider Electric Software Installer, User Guide)).
- Floating licenses: New license type for EcoStruxure Machine Expert - Safety and BWU2984 AS-i safety gateway available.
- Embedded Safety integration into TM262M• controller architectures. (TM5CSLCx00FS, TM5/TM7 Safety I/Os).
- Online Help:
 - HTML 5
 - Online help (safety and non-safety parts)
 - Offline help (safety)
- Support of context-sensitive help in EcoStruxure Machine Expert - Safety.
- Integration of latest help and documentation content.
- Update to EcoStruxure Machine Expert product changes.
- Fixed documentation issues of previous versions.
- Lexium 62 with new hardware revision is supported (no change on safety functionality).
- Updated EULA (End User License Agreement)

Compatibility EcoStruxure Machine Expert

Overview

EcoStruxure Machine Expert can be installed in parallel to other Schneider Electric software products, such as SoMachine and SoMachine Motion.

For general information on compatibility of EcoStruxure Machine Expert, refer to the Compatibility and Migration Guide (see EcoStruxure Machine Expert Compatibility and Migration, User Guide).

Behavior Modifications in EcoStruxure Machine Expert compared to SoMachine / SoMachine Motion Versions

NOTE: For a list of compiler versions included in EcoStruxure Machine Expert, SoMachine and SoMachine Motion versions indicated in the following table, refer to the Compatibility and Migration Guide appendices (see EcoStruxure Machine Expert Compatibility and Migration, User Guide).

ID	Description
OEM00071037	Firewall: The file name Firewall is case sensitive. Only a default firewall file, named FirewallDefault.cmd , is recognized.
OEM00071000 / SI-5249	I/O Mapping: Modified behavior of Default Value . If the compiler version is EcoStruxure Machine Expert V1.1 or later: You can edit this field only, when mapping an input/output to a new created variable. When mapping to an existing variable, the initialization value of the variable is used as the default value. Selecting a compiler version earlier than EcoStruxure Machine Expert V1.1, the default values can also be edited and are applied in case of mapping to an existing variable or to no variable. When importing projects from SoMachine / SoMachine Motion, default values are still imported for the cases above, but are not visible and not applied, as long as the compiler version is \geq EcoStruxure Machine Expert V1.1. See also OEM00072811.
OEM00071094 / CDSYS-72	Trace: Multi-selection of variables in the Trace Record part of the Trace Configuration dialog is not supported.
OEM00071748 / CDSYS-82	Tabular Declaration: The number of variables in online mode is limited to 1000.
OEM00071929 / CDSYS-83	Online Change: Adding a library opens the Online Change dialog, even if nothing was used out of this library. After confirming this dialog, the message Code has not changed. No online change necessary is generated.
OEM00072060 / CDSYS-84	Auto-Declare: Using a statement like <i>IF Var_0 OR Var_1 THEN</i> triggers an auto-declaration proposal of INT instead of BOOL.
OEM00072474 / CDSYS-100	SVN: After checking out a project from SVN and closing the project, an entry is created in the Recent files menu, even though the corresponding file has not been saved. Selecting this entry will fail to open the project with an error message.
OEM00072745	Compiler: Bool is not supported as a base type in enumerations and causes a compiler error message. Only Integer data types are supported.
OEM00072811 / CDSYS-105	I/O Mapping: Reset Mapping does not delete default values. Reset Mapping deletes the variables in the I/O Mapping . If a Default variable was associated with such a deleted variable, this is no longer shown and applied. However, creating a new variable for the same I/O will bring back the old Default value. Note, that you can only modify the Default value, when you have created a new variable first. See also OEM00071000.
OEM00073255 / CDSYS-119	Find: The Find command is associated to the shortcut Ctrl+F. The shortcut only works, when an editor window is open.
OEM00073314 / CDSYS-120	FBD: If the FBD option Connect boxes with straight lines is selected , connection lines (links) between function blocks may overlap.

ID	Description
OEM00074431 / CDSYS-139	Auto-Declare Using a statement like <code>ptVar := ADR(var);</code> , where <code>ptVar</code> is declared a <code>POINTER TO INT</code> , will lead to an auto-declaration proposal of <code>POINTER TO INT</code> for <code>var</code> , instead of <code>INT</code> .
OEM00074574 / CDSYS-141	Auto-Declare: Using a statement like <code>GVL.toto := bool_1;</code> , where <code>bool_1</code> is declared as <code>BOOL</code> and <code>GVL</code> is the name of a <code>GVL</code> , causes an autodeclaration proposal of <code>INT</code> for <code>toto</code> instead of <code>BOOL</code> .
OEM00074609 / SI-4762	Reset Cold/ Reset Warm: Breakpoints that were activated before executing the commands are still active after the execution of the command. (In <code>SoMachine / SoMachine Motion</code> they were deactivated).
OEM00074647 / CDSYS-143	Auto-Declare: Using Auto-Declare from a POU will not offer an already existent <code>PersistentVars</code> as object, except if selecting in the following order: PERSISTANT and RETAIN followed by VAR_GLOBAL as scope.
OEM00074787	SysTimeRtc: The actual behavior of functions <code>SysTimeRtcConvertHighResToLocal</code> , <code>SysTimeRtcConvertLocalToHighRes</code> , <code>SysTimeRtcConvertUtcToLocal</code> and <code>SysTimeRtcConvertLocalToUtc</code> is compliant to the defined <code>TimezoneInformation</code> (struct) definition of member <code><iBias></code> (which itself is based on Windows Definition), where <code>UTC = localtime + bias</code> . Therefore, the bias for eastern longitude is negative and the bias for western longitude is positive.
OEM00076496	Project Compare: New menu command Project - Commit t accepted changes . The command is also available as toolbar button and allows to commit already accepted differences from the project comparison to the current project. Thus, you are no longer limited to committing differences accepted in one compare view only. Instead you can determine the time and extent of the Commit .
OEM00076869 / CDSYS-197	Project Export/Import: After exporting modules, when importing the modules are reordered alphabetically by module name.
OEM00071445 / CDSYS-76	ProfiNetIO-Controller (Master): New parameters on the General tab: I/O provider/ consumer status. Parameter Application stop > Substitute values : When the user stops the application, the provider state is set to BAD . The slaves then set the inputs and outputs to predefined substitute values. For more details refer to the Online Help.
OEM00074786	SFC - Init step: For the compiler version of EcoStruxure Machine Expert V1.1 or later the <code>Init</code> step counts from the program start moment (not from the system start moment. Additionally, triggering <code>SFCInit</code> or <code>SFCReset</code> flag resets the <code>Init</code> step time to zero.
SP12CDS-57549	Compiler, I/O Mapping: Task deployment for function blocks used in initial values. For the compiler version of EcoStruxure Machine Expert V1.1 or later: only these tasks will be used as update task for function block instances with I/Os, in which an access to the I/Os can be detected, or in which the instance is called directly. This behavior may lead to a smaller number of output updates. For example, if a function block instance is declared in a program, but there is no direct call of this instance, there will be no update in the task in which the program is called. Direct call means, that calls via interface are not considered. You can manually edit the tasks in which to update I/Os in the I/O configuration.
SP12CDS-56915	Compiler: A Bit-located Bool variable assigned to a <code>REFERENCE TO BOOL</code> variable generates a compiler error. For the compiler version of EcoStruxure Machine Expert V1.1 or later, a compiler error is generated when assigning a <code>BOOL</code> variable located on a bit address to a <code>REFERENCE TO BOOL</code> variable. Workaround: assign the bit located variable to a Boolean variable first and assign the latter to the <code>REFERENCE</code> variable.
SP12CDS-59141	Compiler: Unexpected online change related to the usage of the <code>PersistentVars</code> object with attributes. For the compiler version of EcoStruxure Machine Expert V1.1 or later, the order of attributes in a <code>PersistentVars</code> list object is always fix (sorted lexically). Opening projects without update, that contain a compiler version earlier than EcoStruxure Machine Expert V1.1 and attempting to login may request an online change in the above-mentioned case.

ID	Description
	<p>Project Archive: Sending a project archive via mail directly from the Save Archive dialog is not supported in EcoStruxure Machine Expert V1.1 (64-bit) due to MAPI limitations.</p>
SP11CDS-35119	<p>Trace: flexible assignment of variables to diagrams.</p> <p>EcoStruxure Machine Expertsupports configuring one or more diagrams within the trace and displaying one or more variables, allowing a flexible arrangement of these variables within the diagrams. All diagrams share the same time axis, but the appearance including the Y-axis can be configured separately for each diagram.</p> <p>Download and Upload diagram configurations to the PLC and Save and load diagram configurations in the trace.csv format are not supported.</p> <p>When opening projects containing Single-/Multichannel traces, they will be displayed in an equivalent way.</p> <p>The former menu command Multichannel (changing the view only) was replaced by two new commands Convert to Single/Multi Channel, which modify the configuration accordingly.</p>
SP11CDS-52137	<p>Compiler: Compiler Error message for libraries with invalid namespace.</p> <p>For the compiler version of EcoStruxure Machine Expert V1.1 or later, a compiler error will be generated for library namespaces that are not valid identifiers according to IEC 61131-3.</p>
SP11CDS-47465	<p>Runtime: Default values: STOP to STOP over Reset behaves differently than RUN to STOP over Reset.</p> <p>Default values for direct addressed outputs are set, if application is in stop, and a reset is executed. Previously, the direct addressed outputs were not reset in this scenario.</p>
SP10P10CDS-50882	<p>ScriptEngine: IronPython behavior regarding reading files.</p> <p>Within IronPython, Byte Order Marks (BOM) at the start of files are not implicitly skipped any more, which may lead to a different behavior of scripts parsing files, for example using the ConfigParser module. Open these files using <code>codecs.open()</code>.</p>
SP10CDS-43667	<p>Compiler: Initialization (order) of DUT structures</p> <p>For the compiler version of SoMachine Motion V4.4 or later, the initialization order of arrays of Data Unit Types..</p> <p>Example:</p> <pre>arr : ARRAY [0..1] OF DUT := [(a := 1), (a := 2)];") is: FOR i := 0 TO 1 DO arr[i].FB_Init; END_FOR arr[0].a := 1; arr[1].a := 2;</pre> <p>Where the order for compiler version < V4.4 Motion was:</p> <pre>arr[0].FB_Init(); arr[0].a := 1; arr[1].FB_Init(); arr[1].a := 2;</pre> <p>Additionally, if a DUT variable is initialized by assigning another variable, as in:</p> <pre>xx : DUT := yy;</pre> <p>with compiler version SoMachine Motion V4.4 or later, there will also be a <code>FB_Init</code> call in this case.</p>
SP10CDS-47295	<p>Compiler: C0405 multiple assignments to interfaces variables not allowed.</p> <p>For compiler versions of SoMachine Motion V4.4 or later, a compiler error is generated for constructs like:</p> <pre>itfVar1 := itfVar2 := 0;</pre>
SP10CDS-49943	<p>Symbol Configuration: Properties with monitoring type variable.</p> <p>For the compiler version of SoMachine Motion V4.4 or later, properties with monitoring type variable are exported read-only in the Symbol Configuration.</p>
SP10CDS-49852	<p>Project User Management: Settings: New hash format for passwords.</p> <p>Hashes for user passwords can now be stored with a new format, which supports salt and a new hash algorithm, improving the security of a password against guessing and brute-force. The password hash of a user is converted with the first login after the setting was changed.</p> <p>The project loses its backward compatibility with the conversion to the new password hashes. You can convert the new password hashes back by disabling the setting and re-login of every user, which logged in during the time the setting</p>

ID	Description
	was enabled. Another option is to set a new password for every user (that logged in while the setting was enabled).
SP10CDS-49093	<p>Online Change: Programming system with .Net 4.6 Framework.</p> <p>In projects using Webvisualization it might not be possible to login without an Online Change, if the project contains an Imagepool object, referencing the same image more than once.</p>
SP10CDS-25116	<p>Gateway, RTS: NodeName limitation to 50 characters:</p> <p>The NodeName of controllers (as displayed in the Communication Settings dialog) is now limited to 50 wide-char characters (including NULL termination).</p> <p>If a controller with a longer node name is updated to a SoMachine Motion V4.4 version or later, the node name is cut to this limit. Clients like PLCHandler or OPC Server cannot connect when using the old, longer NodeName. In this case, you need to update the connection parameters of the affected clients and/or rename your controller.</p>
SP9CDS-47453 / OEM00061201	<p>Online Change: Handle out of memory exception</p> <p>For compiler versions of SoMachine Motion V4.4 or later, in the case of memory outage during online change, a compiler error C0398 will be generated.</p>
SP9CDS-46022	<p>Compiler: AT declaration in VAR_TEMP, VAR_IN_OUT and VAR CONSTANT.</p> <p>For compiler versions of SoMachine Motion V4.4 or later, a compiler error C0392 is generated if an AT declaration is used inside one of the following blocks: VAR_TEMP, VAR_IN_OUT and VAR CONSTANT.</p>
SP9CDS-45977	<p>Compiler: Assignment of function block outputs to interfaces.</p> <p>For compiler versions of SoMachine Motion V4.4 or later, the assignment is not supported, a type mismatch error is reported for the following case:</p> <pre>fbUser(fbOut => iMain);</pre>
SP9CDS-43812	<p>Compiler: <code>__ISVALIDREF</code> returns TRUE for check of interface instance with value zero.</p> <p><code>__ISVALIDREF</code> is a special operator that can now only be used for checking references.</p> <p>A compiler error gets generated in case <code>__ISVALIDREF</code> is used with any other type than REFERENCE types.</p> <p>Interfaces and pointers can be checked via <code>interf <> 0, pointer <> 0</code>.</p>
SP9CDS-44576	<p>Compiler / Online Change: AT declarations</p> <p>If an address is moved from one variable to another variable, an online change will not be possible; a compiler error will be generated.</p> <p>Example:</p> <pre>var1 : BYTE; -> var1 AT %MB0 : BYTE; var2 AT %MB0 : BYTE; var2 : BYTE;</pre>
SP9CDS-45776	<p>Compiler: Array with length 0.</p> <p>For compiler versions of SoMachine Motion V4.4 or later, a compiler error will be generated for arrays like:</p> <pre>arr[0..unsigned_const-1], if the unsigned_const is 0.</pre> <p>The upper limit is evaluated as an unsigned operation and would result in a too large number for any signed array limit.</p> <p>Use a signed constant instead, or cast the constant to a signed type:</p> <pre>arr[0..TO_INT(unsigned_const)-1]</pre>
SP9CDS-45575	<p>Compiler: PRIVATE, PROTECTED not allowed for FB_Init, FB_Exit, FB_ReInit.</p> <p>For compiler versions of SoMachine Motion V4.4, a compiler error will be generated, if an <code>FB_Init</code>, <code>FB_Exit</code> or <code>FB_ReInit</code> method is declared as PRIVATE or PROTECTED.</p>

ID	Description
SP9CDS-45684	<p>Compiler: Writing to %I* input variables.</p> <p>For compiler versions of SoMachine Motion V4.4, a compiler error will be generated, when writing to variables located at %I* addresses</p>
SP9CDS-383	<p>Compiler: FB_Exit is called to destroy local instances.</p> <p>For compiler versions of SoMachine Motion V4.4, FB_EXIT is now called for instances allocated on the stack before the owning scope returns. A warning informs you about the changed semantics in these cases. In order to suppress the warning, decorate the POU declaring the local instance with the warning disable macro for warning code C0394 (<code>{warning disable C0394}</code>).</p>

NOTE: If you are extracting a project archive in EcoStruxure Machine Expert that has been created with SoMachine or SoMachine Motion, and **Options** are selected in the **Extract Project Archive** dialog box, your EcoStruxure Machine Expert installation may be altered and it may appear the devices are missing.

⚠ CAUTION

INOPERABLE EQUIPMENT

When you extract a project archive that has been created with a different programming software, deselect the **Options** check box in the **Extract Project Archive** dialog box.

Failure to follow these instructions can result in injury or equipment damage.

To restore your EcoStruxure Machine Expert installation, execute the **Tools > Options** command and select the **Directories (Devices, Libraries,...)** option. From the **Directories (Devices, Libraries,...)** dialog box, click the **Reset repository locations** button and the devices are restored.

NOTE:

- If a SoMachine or SoMachine Motion project with HMIs is loaded, it may occur that Vijeo-Designer must be started by the update. In this case, it may occur that Vijeo-Designer is only started in the background.
Vijeo-Designer must be opened manually to continue the update.
- If a SoMachine or SoMachine Motion project with obsolete HMIs is loaded, it may occur that Vijeo-Designer is started and you are prompted to enter a reference number.
If the reference number is not available, click **No** and the device is updated automatically to a preprogrammed type.
- If a SoMachine or SoMachine Motion project with obsolete HMIs (with control) is loaded, the HMI is converted in Vijeo-Designer to a supported HMI.

Compatibility EcoStruxure Machine Expert - Safety

Overview

Former SoSafe Programmable versions cannot be started from EcoStruxure Machine Expert environment anymore and can only be installed and used if the related SoMachine Motion version is installed.

However, the former SoSafe Programmable projects - starting from V2.1 - can be imported, re-used, and updated in EcoStruxure Machine Expert - Safety V1.1.

In almost all cases, the update works without impact on the overall safety application and the resulting project CRC (cyclic redundant checksum) value stays the same and there is no recertification needed.

However, EcoStruxure Machine Expert - Safety with this release does not support reusing a project built on EcoStruxure Machine Expert - Safety with LMCx01 system to EcoStruxure Machine Expert - Safety with M262 system or vice-versa.

Identified Incompatible Project Updates

The CRC of the safety project done before SoSafe Programmable V2.21 is changed if the old project contains the following safety devices:

- TM5SAI4AFS
- TM5STI4ATCFS

In this case, the safety project must be compiled again and downloaded to the TM5CSLCx00FS and the related safety function must be validated and recertified.

It is still possible to install former SoSafe Programmable versions in parallel to EcoStruxure Machine Expert - Safety as long the compatible SoMachine Motion package is available on the PC. Thus, you can maintain old projects using previous compatible engineering tool chains.

Overview of the validated safety-related software with the appropriate safety-related firmware.

Device	Safety-related firmware version for SoSafe Programmable version				
	1.0	2.0	2.1	2.2	2.21 ⁽¹⁾
TM5CSLC100FS	1.10	2.36	2.41	2.44	2.47
TM5CSLC200FS	1.10	2.36	2.41	2.44	2.47
TM5SAI4AFS	–	–	302	302	322
TM5SDC1FS	–	–	302	302	302
TM5SDI20DFS	–	–	301	305	305
TM5SDI2DFS	281	281	301	305	305
TM5SDI4DFS	281	281	301	305	305
TM5SDM4DTRFS	281	281	301	305	305
TM5SDM8TBFS	–	–	301	305	305
TM5SDO2DTRFS	–	–	300	300	300
TM5SDO2TAFS	280	280	280	280	280
TM5SDO2TFS	280	280	280	280	280
TM5SDO4TAFS	280	280	280	280	280
TM5SDO4TFS	280	280	280	280	280
TM5SDO6TBFS	–	295	295	295	295
TM5SPS10FS	–	–	320	320	320
TM5STI4ATCFS	–	–	–	–	322
TM7SDI8DFS	–	–	301	305	305
TM7SDM12DTFS	280	280	301	305	305

(1) EcoStruxure Machine Expert - Safety V1.1 is compatible with the same component versions as SoSafe Programmable V2.21.

Mitigated Anomalies

Machine Expert Installer

ID	Description
OEM00073838	SoMachine Motion installation on a Windows system with Turkish language is operational.

Online Help

ID	Description
OEM00060935	Missing information on the safety-related characteristics of the Safe Logic Controller TM5CSLCx00FS and the TM5/TM7 I/O safety-related modules added in the Online Help.
OEM00067912	Missing information on the safety-related parameters in the configuration window of safety-related drives added in the Online Help.
OEM00069590	In the German Online Help, the links of the chapters <i>Lexium 62 Single/Double Drive Embedded Safety</i> and <i>Lexium 62 ILM Safety Option Module</i> are operational.
OEM00069710	In the Online Help, the link to the <i>PacDrive TM5/TM7 Safety System Planning and Installation Guide</i> is operational.
OEM00070505 OEM00070510	In the Online Help, the description of some LED indicators of the TM5CSLCx00FS is present. The following was enhanced: <ul style="list-style-type: none"> • Missing module detected. • Boot phase. • Debug state (RUN, STOP, HALT).
OEM00070844	In the Online Help, the parameter information on the encoder resolution of motors (<i>EncoderResolutionRotary</i>) is present.
OEM00071262	In the Online Help, the description for the TM5CSLCx00FS cycle time parameter provides sufficient information.

EcoStruxure Machine Expert

ID	Description
OEM00055804	In simulation mode, you can assign the application to the same node name as the Soft PLC. The Vijeo-Designer Simulation Runtime on the same Windows PC will connect to the simulated PLC.
OEM00061672	The diagnostic message <i>Program name or function block instance expected instead of IoMgr...</i> no longer is displayed at the first login or after the Update > Build > Generate code procedure.
OEM00067034 / SI-5218	When converting an M251 controller to an M241 controller, the modules of an Ethernet OTB slave are no longer arranged in reverse order.
OEM00067403 / SI-3320	In online mode, the parameters for Modbus TCP servers can no longer be edited or modified.
OEM00068030 / SI-1116	It is now possible to install Sercos III EtherCAT bridge devices without losing parameters in the device description.
OEM00070178 / SI-1069	McAfee security analysis no longer incorrectly declares the <i>Clean_all.exe</i> files as Trojans.
OEM00071130 / SI-5252	In the Add Device dialog box, the iPC Series is now available.
OEM00071816 / SI-5259	The <i>SiteManagerEmbedded.exe</i> file (used for Vijeo-Designer) is available in the <i>Tools</i> folder.
OEM00062595 / MS-1605	Motion Sizer: In the Device selection dialog, the Inertia ratio column can be sorted.
OEM00006868	Smart Coding no longer displays incorrect icons for POU's or actions in the SFC (Sequential Function Chart) editor.
OEM00010333	GlobalImagePool : After embedding an image into a project, the image has become part of the project and the referenced file is no longer needed. The embedded image without referenced file is no longer displayed in red.
OEM00012125	Source Download : If you execute the Source Download command, your project is no longer automatically saved without first prompting you to confirm.
OEM00016215	Variable declaration: The declaration of variables in the tabular declaration editor no longer automatically adds an additional pair of keywords (<i>VAR</i> , <i>END_VAR</i>) to the textual declaration editor.

ID	Description
OEM00019426	For Visualization elements, user-defined colors are retained.
OEM00022360 OEM00033901	The size of project files no longer increase over time due to precompile and auxiliary files for shared strings.
OEM00025211	When there is no memory space available on the file system of the controller, the <code>Create boot application</code> application command can not be executed successfully, but no message is displayed indicating the reason. Workaround: The message can be created by the function <code>CAL_SysFileWrite</code> with the return value <code>ERR_DISK_FULL</code> .
OEM00026350	Behavior of outputs for <i>STOPPED</i> state (from Addendum SoM V3.1): All outputs initially assume their configured state (Keep current values or Set all outputs to default). The subsequent state of the outputs depends on the value of the Update IO while in stop setting, or the state dictated by output forcing if used and on commands received from remote devices. NOTE: The initial assumption of state of the outputs is for the equivalent of one controller cycle. After this, the subsequent state takes effect. For detailed information, refer to the <i>Programming Guide</i> specific to your controller, chapter <i>Controller States Description</i> .
OEM00027910	Opening the preview of project documentation no longer leads to overflow of GDI (Graphics Device Interface) objects.
OEM00028990	When function <code>DirList</code> out of the CAA File library was used to read files and folders from the controller file system the first file/folder is no longer missing.
OEM00030446	When the Tools > Options dialog box was closed with the X button, the settings are no longer saved (as if the OK button was clicked).
OEM00030618	Variable declaration: The order of the variables copied from one GVL to another GVL is correct.
OEM00031906	CANopen, DTM: If the CANopen option Block SDO, DTM and NMT access while application is running is set, after the application is running and subsequently stopped, the DTM (Device Type Manager) can be synchronized.
OEM00035324	Case sensitive renaming a POU is possible.
OEM00035704	In online mode, you can no longer add a POU to the MAST task by drag-and-drop in the Device Editor .
OEM00035785	Library Manager > Add Library > Placeholder : Placeholders defined in the library profile (like for the Standard** library) are present in the placeholder list.
OEM00037183	Addressing bits in variables: Compiler error message is now generated indicating that bit access is only possible on integer variables.
OEM00038122	A cut-and-paste operation is now possible for a POU in an application if a device with the same name exists.
OEM00038656	When adding a POU to the MAST task by using the contextual menu, the entered comment is now taken into account.
OEM00038866	Creating an <i>ARRAY OF BOOL</i> located on a bit address, Build > Generate Code no longer generates an internal error message.
OEM00039266	Adding an FB (function block) to an LD (Ladder Diagram) no longer results in an undefined FB when clicking outside the FB edit dialog box instead of confirming the name with the Enter key.
OEM00041670	Downloading a project which included a visualization trace for which a DWORD variable was specified in the Load trace from a file > FileName property, no longer cause connection issues.
OEM00041917	If you used the 3S CanOpenStack library in your project, a build error is no longer generated when using a POU named <i>START</i> or <i>STOP</i> .
OEM00042160	If you disconnect an Ethernet cable from a device for a short time and reconnected it, is now recognized that the device was reconnected.
OEM00042331	The <i>%I</i> and <i>%Q</i> addresses of a project are organized during code generation. Less time is required to manage a large number of <i>%I/%Q</i> addresses existing in a project, when the option Always update variables is activated.
OEM00042591	The correct message is now displayed when trying to connect to a device with an incompatible firmware version.
OEM00042732	Symbol Configuration: The symbols from Symbol Configuration can now be exported to Vijeo-Designer after a second modification.

ID	Description
OEM00043711	When outputs have default values configured and are driven by an external task and the external task has not been executed at least once, the default values are now not applied when the controller mode changes from RUN to STOP.
OEM00043954	WebVisualization: The configured background color is now used for the complete website.
OEM00044255	In EcoStruxure Machine Expert Logic Builder under Project > Project Settings > Security > Enable project file encryption > Password , you are no longer prompted for the present password and the new password if the security settings have never been enabled. You are now asked only for the new password.
OEM00044349	WebVisualization: The controller no longer transitions to STOP mode when you open a tab of the WebVisualization.
OEM00044785	WebVisualization: Connecting to WebVisualization with a tablet or a smartphone now consistently returns the addressed page.
OEM00044844	CAA_File.library: The function <i>FILE.DirList</i> now provides information about the file size and date when <i>xDone=TRUE</i> and the directory is empty.
OEM00045192	Resolution of a DTM (Device Type Manager) communication issue now allows FDT (Field Device Tool) information to be saved.
OEM00045337	SysDir Library: <i>CreateFolderTransfer</i> now calls <i>CAL_SysDirClose</i> when the directory is invalid.
OEM00045442	The Symbol Configuration object can now be used/configured for a Turkish localization.
OEM00045474	Symbols created with the Symbol Configuration editor can now be shared with the Vijeo-Designer after upgrading the programming software.
OEM00045495	When you cancel the closing of a project, the message: <i>Could not save project. Object reference not set to an instance of an object.</i> is no longer presented and you can login to the controller.
OEM00045521	An unhandled exception no longer occurs during Project > Export when changing the message categories.
OEM00046210	Variables of large POUs in a CFC program can now be monitored online.
OEM00046215	If you attach two addresses to one contact/coil, a build error message is displayed.
OEM00046286	In the communication elements list of the Add Device dialog box, one version is now displayed for the Modbus devices.
OEM00046718	The message <i>Assertion Failed</i> is no longer displayed during the build process when you use a function of the Conveying library or the Conveying Templates library and afterwards remove the libraries from the project.
OEM00046780	A runtime system shutdown during operation no longer occurs when using a large number of network adapters.
OEM00046838	Toolbar and toolbox no longer disappear while using drag-and-drop of elements/operators in an undocked POU editor.
OEM00047072	Elements of an <i>ARRAY [x..y] OF STRUCT</i> can now be read by Vijeo-Designer.
OEM00047248	In EcoStruxure Machine Expert Logic Builder under Tools > Options > International Settings , the option to select English as language appears now only once in the list.
OEM00047320	Online with an extensive WebVisualization: you can now run an additional stand-alone visualization in parallel.
OEM00047399	In the Tools tree and the Applications tree, the green (+) button is now visible when the width of the Tools tree or the Applications tree is small.
OEM00047586	In the GUI of the programming software, some French translations are no longer missing and French characters are now displayed correctly.
OEM00047786	If you now reduce the size of the Visualization Manager dialog box, buttons are displayed proportionally, and can now be read.
OEM00047962	If you now delete an operator or function block from the LD or FBD editor, and attempt to drag-and-drop another, different element, the correct element will appear as opposed to the element which was deleted.
OEM00048174	The Modbus channel dialog of the Modbus I/O scanner is now translated to Italian.

ID	Description
OEM00048226	The removing of the CANopen connection cable from an Altivar drive (ATV61/ATV71) is now detected.
OEM00048337	<i>SysSockGetRecvSizeUdp</i> now returns <i>ERR_FAILED</i> if a timeout occurs.
OEM00048341	In the Project > Project Settings dialog box, some Italian words were not translated.
OEM00048342	The Tools > Library Repository dialog is now translated to Italian.
OEM00048605	When clicking the Export groups for global visualization button in the Visualization Manager > User Management > Groups tab), the error message <i>Unhandled exception</i> is no longer displayed.
OEM00049190 / PLAT-109	In the GUI of the programming software, there is no longer some Chinese translations missing.
OEM00049405	By converting an XBTGC HMI Controller to an HMISCU Controller, the build error message <i>Out of code memory</i> is no longer displayed.
OEM00049576	The operating modes Circular and Stop when full for the log file of the data log manager now operate correctly. The entries are added at the correct position and the log file is not limited to a fixed size.
OEM00050567	When you add a Visualization to a project and perform an Undo and then a Redo , the navigators (Devices tree, Applications tree, ...) of the programming software now continue to operate correctly.
OEM00050997	DTM dialog message boxes now display the correct icons.
OEM00051067	Index variable values are now displayed correctly when the index variable is of type UINT.
OEM00051333	WebVisualization: When you modified the WebVisualization property Best Fit from Use specified client size to Best fit in online mode , this modification is now taken into account.
OEM00051955	Lexium 23 (LXM23) drive: It is no longer necessary to execute the <i>MC_Reset</i> function block twice to bring the status (PLCopen) from <i>ErrorStop</i> to <i>StandStill</i> when a limit switch (AI14, AI15) is released.
OEM00052042	WebVisualization: The displayed content is now more consistent depending on the browser or smartphone used.
OEM00052458	Performance has been improved when opening a project which includes a CANbus network.
OEM00052907	Now you can close the editor of drive DTMs which control and run a motor, or go offline before the motor is stopped.
OEM00053685	NVL (Network Variables List): During creation of an NVL receiver list, it is now possible to add NVL senders to NVL receiver lists.
OEM00053715	The FDT (Field Device Tool) frame application now verifies whether a DTM (Device Type Manager) is in state <i>Configured</i> before executing import/export and copy/paste operations.
OEM00053859	The time to perform the Build > Clean All command is now more consistent across projects.
OEM00053917 / IECLIB-1423	Unsupported libraries are no longer delivered in the Category: Test Versions .
OEM00054730	Configuring the hotkeys in the VisualizationManager window now operates correctly.
OEM00055008	It is now possible to import a device to a connector which is configured with the attribute <i>explicit=true</i> .
OEM00055516	In a project which contains the Lexium 32i library and the Lexium 28 library, the structured view in the Input Assistant now displays the correct sorting of the function blocks.
OEM00055707	You can now attach several Groups to the same position in your visualization, select the groups, and move them to a new position without an error message being displayed.
OEM00057166	Using the Input Assistant in a visualization no longer causes a shutdown of the programming software.
OEM00057461	When a contact or a coil was added to an LD network and you attempt to attach a variable, the Input Assistant now proposes a BOOL instead of an INT.

ID	Description
OEM00057572	When using Project > Compare , a null reference exception message is no longer displayed and the compare feature operates.
OEM00057670	The attempt to edit the HMI Application object of a Vijeo-Designer device while the Cross Reference List is open no longer causes a shutdown of the programming software.
OEM00058078	If you select several function blocks in an FBD (Function Block Diagram) and delete them, all of them are now deleted.
OEM00058877 / IECLIB-1006	For a PGN (Parameter Group Number) inserted into a J1939_ECU device (CANbus), all the parameter values are now sent.
OEM00059249	The attempt to open Project > Project Information , no longer results in the errant display of the message: <i>Object reference not set to an instance of an object.</i>
OEM00059361	After importing an EDS file (device description), the Hardware Catalog is now updated and the added device is available.
OEM00059847	WebVisualization: When you modify the WebVisualization settings, the settings are now taken into account for download.
OEM00059965	After deleting the first TX Signal of a J1939_ECU device (CANbus), the I/O mapping of the associated PGN (Parameter Group Number) is now correct.
OEM00060184	SVN: Modifications on a CANopen node in the first instance of a project are recognized by SVN and are now also taken into account for the second instance of the project.
OEM00060617 / IECLIB-1006	After saving and reopening a project, the I/O Mapping tab of a J1939_ECU device now displays the Unit column for the TX/RX signals.
OEM00060712	SVN: The time stamps now displayed by SVN provide the local time of the computer running the programming software.
OEM00061003	Replacing an element in an LD network by drag-and-drop from the ToolBox now operates correctly.
OEM00061075	Devices can now be added, copied and pasted, and then deleted from a project without provoking an error message when you execute the Build command.
OEM00061639	SVN: Modifications on the first instance of a project are now taken into account by SVN for the second instance of the project.
OEM00062014	After executing the Convert Device command, a GVL (Global Variable List) is no longer missing in the project.
OEM00062211	Using Project > Export , the prompt to overwrite the already existing project now appears only once.
OEM00062593	Trying to log in to a controller no longer results in an internal error message displayed and the need to execute the Clean all command in order to log in.
OEM00063335	After disconnecting the CANbus connection of a J1939_ECU device, all devices in the Devices tree now display the appropriate color and the status of the J1939_ECU device is now displayed correctly.
OEM00063354	The status LEDs (CAN_R , CAN_E) of the J1939_ECU device are no longer turned off in all operating modes.
OEM00063414	SVN: Under Project Settings > Security > Enable project file encryption > Password , you can add a password to your project. After checking in the project to SVN and checking it out again, the password is now retained.
OEM00063623	SVN: After checking out a project from SVN, save the project and then reopen it again, objects are now highlighted or not as is appropriate.
OEM00063640	In a Ladder Diagram, inserting a function block into a parallel contact branch is now possible.
OEM00063811	SVN: After checking out a project from SVN, the time stamps are now synchronized with the working copy.
OEM00065365	Using the Input Assistant to attach a global variable out of the TcpUdpCommunication library to an application, the name space is now only added once (<i>TCPUDP.GVL.G_stDefault</i>).
OEM00065836	Unforce and Restore all Selected Values now affects %QX0.0 outputs.
OEM00065955	Performance was improved when mapping variables to bits using Modbus TCP servers.

ID	Description
OEM00066218	In connected mode, the tooltip of a variable with mapping to %/X is now correct.
OEM00066295	Variable address mapping can now be deleted in the table view of the declaration section.
OEM00066930	IntelliSense now operates for actions.
OEM00067143	SVN: Performance improvement when calculating the <i>SVN_Version_INFO</i> .
OEM00067152	AS-i Sercos Gateway: During an update procedure, the configured non-safety-related submodules are no longer replaced by default modules.
OEM00067216 / IECLIB-670	Clicking the Ignore button to the error message <i>Out of global data memory</i> no longer causes a shutdown of the programming software when logging in to a controller.
OEM00067283	After performing multiple online changes on a project with an HMISCU Controller, the connection to the controller is no longer interrupted.
OEM00067382	PLCopenXML import: Importing files (Sercos slaves) exported from projects created with earlier software versions is improved.
OEM00067384	PLCopenXML import: Importing files (controllers) exported from projects created with earlier software versions is improved.
OEM00067452	Whenever a Source Upload (after an upload and download of Users and Groups) is performed, a user logon is no longer displayed.
OEM00067621	VisualizationManager > User Management : After deleting a RemoteTargetVisualization or a WebVisualization , a build error message is no longer displayed when activating the user rights.
OEM00067743	An incorrect declaration of the initial value of an INT variable no longer causes a shutdown of the programming software.
OEM00067888	Using the Cut command in an FBD (Function Block Diagram) no longer causes a shutdown of the programming software.
OEM00067935	Modifications in the Recipe Manager are now managed correctly during Online Change .
OEM00068130	SVN: Each server polling no longer increases the number of available updates.
OEM00068211	SVN: Server polling now updates the locked-by-other-user icon.
OEM00068219	In an FBD (Function Block Diagram), it is now possible to search for a variable used in an Execute box.
OEM00068229	Symbol Configuration : Modifying the access rights of an object in the Symbol Configuration Editor no longer causes a shutdown of the programming software.
OEM00068383	SVN: Including external objects (<i>svn.include_external(URL)</i>) is now compatible with Python scripting.
OEM00068449	OPC DA (Open Platform Communications Data Access): The communication between OPC clients and the OPC server of controllers no longer stops after one of the OPC clients sends a request for one or more variables of a <Controller> PLCSystem library.
OEM00068458 / IECLIB-1446	Running a Trend Recording and starting and stopping the application no longer results in a watchdog exception.
OEM00068537 / CDSYS-50	Symbol Configuration : The variable list of the Symbol Configuration Editor is now updated correctly.
OEM00068562 / CDSYS-51	The Diff Viewer no longer displays misleading information on unmodified objects.
OEM00068649 / CDSYS-52	In the Diff Viewer , it is now possible to accept the detected modifications with the related button. The new command Project > Commit accepted changes , was added. This command is also available as a button in the toolbar.
OEM00068767	Auto Declare no longer proposes a Type without namespace.
OEM00068847	Program simulation is now possible when a POU contains ARRAY variables and where a variable and an arithmetic operator are used for addressing the ARRAY (Example: <i>slider[sli_index+1]:=55</i>).
OEM00068853	Python Scripting: Setting a new value via <i>IScriptDriverInfo.always_update_variables</i> now operates correctly.

ID	Description
OEM00068954	PLCopenXML import: Some objects, such as <code>SoftMotionGeneralAxisPool</code> , can now be imported.
OEM00068970	PLCopenXML import: Some objects, such as <code>PowerDistribution</code> , <code>DM72F0</code> , <code>DM72F1</code> , and <code>TM5_Manager</code> , can now be imported.
OEM00069258	SVN: A CANbus device is no longer erroneously highlighted as modified.
OEM00069291 / SI-1107	SVN: Each instance of the application now independently updates the parameter values without first being closed.
OEM00069359	In an LD (Ladder Diagram), inserting a function block into a contact branch no longer causes an incorrect diagram.
OEM00069424 / SI-656	It no longer takes long time to close a project while View > Hardware Catalog > Devices & Modules was open.
OEM00069603	Updating the programming software to the latest version: During update, implicit tasks (related to modules) are no longer added to the application when they are already available in the application.
OEM00069634	PLCopenXML import: All importable objects can now be imported.
OEM00069976	Tables in Visualization objects have been made more stable.
OEM00070615	When sending a UDP packet of size 0 to destination port 1740, the communication with the controller is no longer stopped.
OEM00071356	PLCopenXML import: After an import and an export, an output of <code>SR_Main</code> is no longer missing.
OEM00071386	Cross References (locations where variables are used within a project) now operates without generating spurious error messages.
OEM00071389	Using Auto declare for commands in an FBD network no longer cause an unhandled exception.
OEM00071445 / CDSYS-76	PROFINET I/Os are now updated when the application program is stopped.
OEM00071842	Dynamically created recipes are now loaded during download.
OEM00071886	It is now possible to edit parameter lists of libraries in the Library Manager of the POUs tree.
OEM00072172	If an edge detection is used at an output of an object in FBD, this edge detection is now retained after PLCopenXML export and PLCopenXML import of the POU.
OEM00072392	Using Auto declare for an Execute box in an FBD network no longer causes an unhandled exception.
OEM00072417	Using Refactoring > Rename (project-wide renaming of object names and variable names) no longer results in the message: <i>Index was outside the bounds of the array.</i>
OEM00072810	If you select a visualization style that differs from the default, the programming software no longer requests an online change at login after the programming software has been closed and reopened.
OEM00073327	Copy-and-paste of variables in the trace configuration, no longer causes an unhandled exception.
OEM00073465	SVN: The time it takes to update a function block to the latest revision of SVN has been improved.
OEM00073690 / SI-2292	The default resolution of the following placeholders is now correct: <code>SysSocket2</code> , <code>CmpTls</code> , <code>CmpX509Cert</code> .
OEM00074493	As the compile process consumes a large amount of memory size, a download or online change is now performed after the compile process has been finished.
OEM00074646	A Clean all operation led to a peak in memory usage and kept the automatic memory management from collecting garbage memory.
OEM00074872	Access to the filesystem no longer negatively influences the real-time behavior of the system.
OEM00075100 / SI-3324	Comparing different versions of a project is now improved.
OEM00075449	PLCopenXML import: After a PLCopenXML export and subsequent import, an additional output (<code>Out1</code>) is no longer added to an action.

ID	Description
OEM00075456	PLCopenXML import: If a function (FC) with assignment but without variable is exported, the assignment is no longer lost after import.
OEM00075518	Go To Definition command: The command now operates correctly for enumerations in the online view.
OEM00075789	Selecting a variable in the Trace Configuration dialog no longer "freezes" the application.
OEM00075950	Python Scripting: <i>ScriptDriverInfo.driver_info</i> now operates correctly for fieldbus devices.
OEM00069264 / SI-3430	SVN: Reverting project modifications on a controller now operates correctly.
OEM00075591	Opening a SoMachine Motion V4.41 project with EcoStruxure Machine Expert, the correct visualization profile is used now.
OEM00070437 / SSP50-4194	Tying to export the SafeLogger messages to a storage device (for example, an USB device) that does not provide enough memory space, no longer causes a shutdown of the programming software.
OEM00070681 / SI-2262	In the Dependency View of the Code Analysis Manager , the German translation is corrected for specific objects.
OEM00071201	The French and German localization of the User Management dialog (Visualization Manager) has been adapted to the English version.
OEM00072358 / SI-2490	The Vijeo-Designer no longer shuts down with HMI Connection Mode > IP Address (Fast TCP) .
OEM00072397 / LMCFW-1000	The Controller Assistant now loads the firmware of drives. Thus, FDR (Fast Device Replacement) may now operate for drives.
OEM00073151 / SI-2037	SVN: There is now an option to revert a complete project to a specific revision.
OEM00073371 / SI-2254	Firmware update with the Controller Assistant: The Sercos device firmware version dialog was improved. Now the Sercos files from the selected firmware version are used.
OEM00073417 / SI-2466	The programming software no longer shuts down after opening and closing a project several times.
OEM00075268	An unhandled exception is no longer caused by copying and pasting a variable inside the trace configuration.
OEM00075412	Graphics added to the WebVisualization in the programming software are now displayed in the web browser.
OEM00075624 / SI-3446	<i>CheckLRangeSigned</i> and <i>CheckLRangeUnsigned</i> (<i>CheckLibs</i> = POU for implicit checks) now trigger a reaction on PacDrive controller.
OEM00074309 / LMCFW-1154	If you modify the Logic Motion Controller settings or the fieldbus device settings, the fieldbus now continues to operate after a program download.
OEM00075265 / LMCFW-1468	The CanL2 communication now operates even after performing several project downloads.
OEM00070192	NetManager Server service no longer causes communication traffic issues. The automatic refresh behavior was modified.
OEM00076105	Using the Project > Convert Device command to convert the Magelis GTUX HMIG3X device to an HMIG2U device, the screen resolution is now adapted correctly.
OEM00074658 / SI-3196	DTM - TM5/TM7: Using an *.eds file for a TM5/TM7 island without activating the Create all SDOs check box no longer results in an incorrect I/O mapping.

EcoStruxure Machine Expert - Safety

ID	Description
OEM00063913 / LMCFW-577	Applications with an LMC Pro2 controller and many safety-related devices no longer have safety-related axes reporting incorrect reference values which lead to Sercos issues and system shutdown.
OEM00070603 / LMCFW-1973	Phase-up of Sercos with the largest possible safety-related application and a specific device sequence is now possible.

ID	Description
OEM00068174 / SSP50-6797	STO (Safe Torque Off) is stabilized and a communication error is no longer detected.
OEM00069176	A web-based installation of the EcoStruxure Machine Expert - Safety is now available.
OEM00071263	In the Online Help, the description for the TM5CSLCX00FS cycle time has been enhanced and more detailed information is provided.
OEM00072267	In the SafeLogger, a safety-related message is not displayed if the TM5CSLCx00FS is not in operational state due to an incorrect encoder resolution.

Known Operational Anomalies

Limitations for the Release of TM262M••

- Disabling of Safety slices is not supported.
- There are restrictions on the simulation feature of devices in some use cases for machine options.
- The Safety Logic Controller will switch to SafeOS state SAFERUN in case Sercos state NRT is active. This is normal behavior and is used to debug the Safety Logic Controller application in case no TM262M is connected.
- Validation of file name is not performed when a new application file is saved in the local directory: If a file with the same name is in a folder and the user confirms to save in dialog, then the existing file is overwritten without further notification to the user.

Limitations for the Release of TM262••

The minimum required firmware version is 5.0.2.1. If the product has an earlier firmware version, firmware update is mandatory. Update can be executed via SD-card or the Controller Assistant.

Limitations for the Release of PacDrive Controllers

Validation of file name is not performed when a new application file is saved in the local directory. If a file with the same name is in a folder and the user confirms to save in the dialog, then the existing file is overwritten without further notification to the user.

Immediate Addressing

EcoStruxure Machine Expert allows you to program instructions using either a direct or indirect method of parameter usage. The direct method is called Immediate Addressing where you use direct address of a parameter, such as %IWx or %QWx for example. The indirect method is called Symbolic Addressing where you first define symbols for these same parameters, and then use the symbols in association with your program instructions.

Both methods are valid and acceptable, but Symbolic Addressing offers distinct advantages, especially if you later make modifications to your configuration. When you configure I/O and other devices for your application, EcoStruxure Machine Expert automatically allocates and assigns the immediate addresses. Afterward, if you add or delete I/O or other devices from your configuration, EcoStruxure Machine Expert will account for any changes to the configuration by reallocating and reassigning the immediate addresses. This necessarily will change the assignments from what they had once been from the point of the change(s) in the configuration.

If you have already created all or part of your program using immediate addresses, you will need to account for this change in any program instructions, function blocks, etc., by modifying all the immediate addresses that have been reassigned. However, if you use symbols in place of immediate addresses in your

program, this action is unnecessary. Symbols are automatically updated with their new immediate address associations provided that they are attached to the address in the I/O Mapping dialog of the corresponding Device Editor, and not simply an 'AT' declaration in the program itself.

▲ WARNING

UNINTENDED EQUIPMENT OPERATION

Inspect and modify as necessary any immediate I/O addresses used in the application after modifying the configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

NOTE: Systematically use symbols while programming to help avoid extensive program modifications and limit the possibility of programming anomalies once a program configuration has been modified by adding or deleting I/O or other devices.

EcoStruxure Machine Expert - Safety

ID	Description
OEM00060343 / SSP50-6783	In the SafeLogger you can read that the status of an input/output of a safety-related module has changed. Detailed information on the reason can be decoded out of the additional <i>info0</i> and <i>info1</i> information. (Refer to the SafeLogger User Guide).
OEM00060774	The communication state between the Safe Logic Controller TM5CSLCx00FS and a drive is not indicated by a message in the SafeLogger: Under certain conditions, a drive is treated as a non-working drive but this is not recognized by the SafeLogger or by the drive. You have to restart the Safe Logic Controller TM5CSLCx00FS to recover.
OEM00068735 / SSP50-6800	If you set the <i>MaxDataTransportTime</i> and <i>CommunicationWatchdog</i> parameters to significantly greater values than proposed by the calculator (for example, 6500 ms), this can result in an unstable system because these parameters influence the timeouts and restart timing of the safety-related system. In this case, the <i>ModuleOK</i> status for some safety-related modules is not reached or is unstable. Use the values calculated by the Response Time Calculator . Do not increase the parameters by more than factor two.
OEM00068980 / SSP50-6805	If you set the value for <i>MinDataTransportTime</i> to a value less than the value calculated by the Response Time Calculator , a build error message may be displayed. The <i>MinDataTransportTime</i> must be set to the calculated value.
OEM00069079	System limitation on number of drives with 1 ms Sercos time setting: With TM5CSLCx00FS firmware version 2.47 and earlier, up to 22 safety-related drives can be handled with 1 ms Sercos time setting. The maximum number of slaves depends on different factors: <ul style="list-style-type: none"> • The number of physical connected devices. • The configured additional real-time parameters. • The data exchanged between LMC and TM5CSLCx00FS. • The number of additional safety-related devices (I/O modules, safety-related gateways...). Workaround: When the error message <i>C1D 0x010A</i> is displayed, the system limit is reached. In this case, the system must be optimized on the influencing factors. Another possibility to increase the number of supported safety-related drives is to split the machine into several modules, with each one having a TM5CSLCx00FS and an LMC inside.
OEM00069082 / SSP50-6808	TM5CSLCx00FS displays the internal error message <i>BF86</i> : This occurs when <i>SafeModuleOK</i> parameter is not used in all safety-related modules in the system. Workaround: Use the <i>SafeModuleOK</i> parameter in all safety-related modules.
OEM00070294 / SSP50-6812	The channel of a safety-related module goes to FALSE if an unsuitable cycle time value is configured: The <i>CycleTime</i> value must be greater than the processing time for the safety-related application. If the <i>CycleTime</i> parameter value is less than or too close to the processing time, a cycle time violation may occur.

ID	Description
	<p>The cycle time configured for TM5CSLCx00FS must be an integer multiple of the Sercos cycle time.</p> <p>You must configure an appropriate TM5CSLCx00FS cycle time:</p> <ul style="list-style-type: none"> • Set a greater cycle time value for the TM5CSLCx00FS. • Download and run the safety-related application. • Open the SafePLC control dialog and click the info button: The present processing time is displayed. • Set the TM5CSLCx00FS cycle time to a value \geq processing time + 1 ms.
OEM00070390	<p>No information could be found for the SafeLogger entry <i>0x9406</i>.</p> <p>This entry indicates a cross communication issue in the network processing engine.</p>
OEM00070466 / SSP50-4192	<p>When the <i>MaxDataTransportTime</i> value is set to a value that is too small, the <i>TM5CSLCx00FS</i> does not change its status to RUN.</p> <p>Workaround: Use the value from the Response Time Calculator. If this value does not work, increase the <i>MaxDataTransportTime/CommunicationWatchdog</i> in small steps up to a maximum of two times the calculated value.</p>
OEM00070475	<p>TM5CSLCx00FS does not change its status to RUN and stays in <i>PreOp</i> mode. Possible reasons:</p> <ul style="list-style-type: none"> • For one or more drives, the safety-related parameters are not valid. • <i>OutputActiveSet</i> value is missing. • <i>AutoRun</i> is not activated. • Safety response time relevant parameters are not set to appropriate values.
OEM00070493 / SSP50-6817	<p>Sporadically, safety-related modules do not go to operational state: After the restart of an LMC (Logic Motion Controller), the TM5CSLCx00FS goes to operational state but the safety-related modules stay in pre-operational state.</p> <p>Workaround: Restart the entire system.</p>
OEM00071897 / SSP50-6831	<p>In the SafeLogger, some issues are displayed as non-safety-related messages, whereas they should be safety-related messages.</p> <p>Known issues:</p> <ul style="list-style-type: none"> • <i>0x9414 Cross communication error</i> • <i>0x960B Internal error cross communication</i> • <i>0xD126 Execution differences processes</i> • <i>0x8609 Supply voltage error</i> <p>Use the latest firmware versions for the safety-related components in your system.</p>
OEM00077282 / SSP50-6867	<p>In one special tested system configuration, running with 1 ms Sercos cycle time the state of <i>SafeModulOK</i> parameter of one safety-related module changes from TRUE to FALSE. This does not occur with 2 ms and 4 ms as Sercos cycle time in the same configuration.</p> <p>Workaround: Use 2 ms or 4 ms as Sercos cycle time if applicable for your application or slightly adjust the safety-related timing parameters (for example <i>maxDataTransportTime</i>).</p>
OEM00052480	<p>Support of special characters (German umlauts) in variable names in ST: An error is detected if a special character is entered as part of the naming of a variable in EcoStruxure Machine Expert - Safety. It is not possible to ignore or cancel this exception. The program must be terminated by the windows task manager. After restarting EcoStruxure Machine Expert - Safety, the special character can be deleted.</p> <p>Workaround: Do not use special characters in variable names.</p>
OEM00073379 / SSP50-6844	<p>TM5CSLCx00FS stays in boot state after MXCHG confirmation for drives: TM5CSLCx00FS indicates MXCHG after the drive has been replaced. To confirm drive replacement, MXCHG ask for confirmation twice. After the second MXCHG confirmation, TM5CSLCx00FS reboot its-self and stays in bootphase (FIL leds light) until it is physically restarted.</p> <p>Workaround: Switch off and on the control voltage.</p>
OEM00070117 / SSP50-6811	<p>Number of possible safety-related axes varies between ring and line topology.</p>
OEM00077251 / SSP50-6866	<p>TM5 modules switch <i>SafeChannelOK</i> state to FALSE during Sercos ring break.</p>

Documentation - Mitigated Anomalies

Documentation

ID	Description
OEM00061702	In the German Online Help, the section headers of some TM5/TM7 safety-related modules are now translated.
OEM00061925	Some information on using SELV/PELV for TM5 safety-related modules is no longer missing in the Online Help.
OEM00062559	In the Online Help, the SVN icons are now documented.
OEM00063454	In the Online Help, the description for <i>ErrorState_2</i> and <i>ModuleOK</i> of the TM5SDM8DTS module is no longer missing.
OEM00065214	Multiple download: An information was added to the Online Help to deselect the Start all applications after download option to help prevent the targeted controllers from restarting in the <i>RUNNING</i> state.
OEM00072124	Hanging and Pulling Loads (<i>Lexium 52 drive - Product manual</i>): A misleading reference to Lexium 62 variants E/F was removed.

EcoStruxure Machine Expert V1.1 SP1

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M241	5.0.7.23
M251	5.0.7.23
M262	5.0.3.2
TMSES4	1.0.0.8
TM3BCEIP	1.2.1.1
TM3•HSC202•	2.0
TM3DI16	2.0
TM3DI16G	2.0
TM3DI16K	2.0
TM5NS31	2.74
LXM32S•••M2 drive	1.06.03
LXM32S•••M2 Sercos	1.08.04
LXM32S•••N4 drive	1.06.03
LXM32S•••N4 Sercos	1.08.04
LXM52•••C•••••	1.54.26.0
ILM•••••••••••	1.54.26.0
LXM62••••C•••••	<ul style="list-style-type: none"> • 1.60.0.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62••••D•••••	<ul style="list-style-type: none"> • 1.60.0.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62••••E•••••	1.54.27.0
LXM62••••F•••••	1.54.27.0
LXM62••••G•••••	1.60.1.0
LMC Eco	1.61.0.1
LMC Pro	1.61.0.1
LMC Pro2	1.61.0.1

Description	Safety-Related Firmware Version
LXM62••••E•••••	1.2.4.0
LXM62••••F•••••	1.2.4.0
VW3E702200000 safety option module	1.2.4.0
TM5CSLC100FS	2.52
TM5CSLC200FS	2.52
BWU2984 SWID	134253
BWU2984 Safe CPU A	135115
BWU2984 Safe CPU B	135116
ASIMON360	3.2.6.7

Contact your local Schneider Electric representative in case you need specific information for your intended machine architecture.

Mitigated Anomalies

PacDrive LMC Controls & I/Os

ID	Description
OEM00078652 / OEM00077643 /LMCFW-1524	The function <code>SystemInterface.FC_DrvEncSetPosition</code> cannot write the encoder position of an ILM.

M241/M251

ID	Description
OEM00076481	Crafted HTTP request on web visualization could lead to information leakage or unintended controller behavior.
OEM00078382	Missing input validation in Web interface.
OEM00078535	Crafted HTTP request on web visualization could lead to unintended controller behavior.
PEP0536708R	ASCII frames dropped when serial connection was configured with low baudrate and disturbances were applied on the line.

M262

ID	Description
OEM00078089	After several hundred of 'Reset Cold', an error could appear. Internal error was detected on the controller, the ERR LED fast flashing and the application removed.
OEM00078072	Some controller tasks were stopped without information (no error detected) in debug mode.
OEM00078057	SSI encoder: Value was temporarily outdated (each 20 ms) - same value during two SSI cycle times.
OEM00077980	M262: Unintended stop of operation under specific denial of service, causing internal error on controller with the ERR LED fast flashing and the application removed.
OEM00077977	When the connection was interrupted during the transfer phase download FTP over TLS, the controller task stopped without information (no error message).
OEM00077909	If a TMSES4 was configured and available, approximately every 6 s the serial communication was interrupted for approximately 3 s.
OEM00077889	When access to variables not available in the controller was requested through Machine Expert Protocol, an internal error was detected on the controller with 'Led ERR Fast flashing' and the application was removed.

ID	Description
OEM00076813	No hardware fallback if the controller was non-responsive after a watchdog Hardware timeout (1.6 s).
OEM00074451	After one week of operation, the controller time was ahead of local time (approximately 4 s).

M262 - Motion

ID	Description
MK-833	Lexium 32S <code>CaptureEdge</code> (Cap1, Cap2, and Cap3) offline parameter value was not applied after download.
MK-817	Controller task suspended after a reset of the encoder error.
MK-804	The Sercos service channel stopped operating after several hours.
MK-790	Unstable SSI encoder movement of Position/Vel/Acc.
MK-778	Safety Logic Controller integration - parameter editor: The information about which function blocks to use was incorrect.
MK-767	An axis with <code>CustomJob</code> without master could not be master for another axis.
MK-764	<code>MC_Power</code> error did not reset properly in some special cases.
MK-734	It was not possible to reach Sercos phase 4 when Sercos bus coupler TM5NS31 with safety slices was set to simulated working mode.
MK-699	<code>xIsHomed</code> flag was not reset properly on encoder axis.
MK-631	Improved performance while performing Sercos phase up.
MK-249	<code>SLC.OutputActiveSet</code> offline parameter value was not applied after download.
MK-223	Sercos master <code>DesiredPhase</code> offline parameter value was not applied after download.

Known Operational Anomalies

PacDrive LMC Controls & I/Os

ID	Description
OEM00054944	It is not possible to establish an EtherNet/IP connection when the EtherNet/IP device (ATV32/IL*) is connected directly to the controller. Workaround: You must add a switch between the controller and the EtherNet/IP device.
OEM00070704 / LMCFW-1976	If EcoStruxure Machine Expert and previous SoMachine Motion versions are installed in parallel on the local PC, the Controller Assistant provides a firmware version for selection that does not match.
OEM00076369 / SI-3444	Modifications are detected for persistent variables, although the persistent variables were not modified. This occurs if a 128 Mb Compact Flash (CF) memory card is used.
OEM00076650 / LMCFW-2023	Too many fieldbus participants with too much data can lead to the following error message: <i>EtherCAT Master: Download busconfiguration to NetX...</i>

Lexium 52 / 62 / 62 ILM

ID	Description
OEM00063956	ILM motor: If the Kendrion brake is used, the voltage value for the holding brake is set to the minimum value required by the brake. This minimum value is monitored. Deviations during measuring can cause malfunctions of the brake. NOTE: See important hazard message after the table.
OEM00065793	If you use a Lexium 62 drive (LXM62) in open-loop control and set <i>RefVelocity = 0</i> , a current value is displayed in the monitoring trace diagram, even though no current value was expected in open-loop control.
OEM00069062 / SSP50-7128	Diagnostic code 8123 is reported for one of the axes at standstill: An application containing a master axis with a Cam and other axes at standstill reports the diagnostic code 8123 when testing under specific conditions.
OEM00069830	A Sercos run-up with a double-line topology is not possible for Lexium 62 drives.
OEM00070988	The Lexium 52 drive does not boot after firmware update (version 1.54.10 -> 1.54.23).
OEM00072092	Your application contains a Lexium 62/ILM 62 drive with safety-related modules (LXM62/ILM62 Safety Module). If you reboot the Sercos network, the diagnostic message <i>8169 Sercos Slave comm. disturbance detected</i> is displayed in the message logger.
OEM00073627	Using an MH3 motor with a Sinus/Cosinus encoder connected to a Lexium 52/62 drive triggers the diagnostic message <i>8908 Unintended motor operation detected</i> .
OEM00074275	Lexium 62 Plus: After online modification of parameters and then a phase down and phase up in a different topology, modification of parameters of type ES is no longer possible.
OEM00075885	Lexium 62 Plus: Flashing of state LED during device identification on single drives and advanced drives is slower (2 Hz) than on double drives.
OEM00077378 (OE-M00073129)	Lexium 62 Plus: A sequence of Sercos topology modifications may lead to a Sercos error message.
–	Lexium 62 Plus: The diagnostic message <i>8503 Service service channel error detected</i> is triggered at phase up if one of the following parameters is configured as a real-time parameter: <i>UserDefinedStopJerk</i> , <i>UserDefinedStopDeceleration</i> , <i>TrackingDeviationLimit</i> .
–	Lexium 62 Plus: Firmware update using the device assistant inside virtual machines may not update all drives. Repeated updates may be required.
–	Lexium 62 Plus: Writing the motor type plate for sensorless motors into advanced drives (variant G) triggers an error message, that type plate has not been written. Nevertheless the type plate is available after a reboot of the drive.
–	Lexium 62 Plus: Machine encoder data is not actualized after change of encoder and reinitialization. A power cycle is required.
OEM00078751	If Lexium 62 Advanced is configured to use machine encoder and no machine encoder is connected, no diagnostics message is triggered.
OEM00078419	For asynchronous motors used in combination with Lexium 52 / Lexium 62, the sign of the current value does not match with the direction of the motor.
OEM00078784	Changing the filter time in combination with torque limitation triggers a Sercos parameter channel error.

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION

- Verify that movements without braking effect cannot cause injuries or equipment damage.
- Verify the function of the holding brake at regular intervals.
- Do not use the holding brake as a service brake.
- Do not use the holding brake for safety-related purposes.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

M241/M251

ID	Description
OEM00074655 / PLAT-524	M241/M251: The Online > Multiple Download command is not performed correctly for Modicon M241 / M251 Logic Controllers: When an application with two controllers has been modified and the Multiple Download command is executed, the application is not downloaded to one of the controllers. Workaround: Execute the Build > Clean All command before executing the Online > Multiple Download command.
OEM00074733 / PLAT-525	The default values of cartridge outputs are not applied in the same way during RUN->STOP and RUN->RESET WARM transitions.
OEM00077573 / PLAT-556	An error message is displayed for the TM4PDPS1 library (Profibus) after opening a project archive generated with SoMachine V4.3. Workaround: Set the correct version (legacy version) manually in the Library Manager .
OEM00072286 / PLAT-490	Default values remain enabled during RUN->STOP transition even if removed from the application.
OEM00077925 / PLAT-563	During migration of an application from SoMachine V4.3 (with user rights enabled) to EcoStruxure Machine Expert, the user rights are not automatically converted before being downloaded to controller. You cannot log in into the controller. Workaround: Use a script stored on the SD card executing the command <code>delete /usr/*</code> or performing a firmware update from the SD card.

M262

ID	Description
OEM00077150 / IECLIB-2031	TopUdpCommunication library: At first startup after firmware update, the certificate store is not ready. An application that includes TLS communication needs a second startup.
OEM00071051	Tasks of type Freewheeling must have a minimum cycle time of 3 ms.
OEM00073787	WebVisualization with trace objects significantly increases the processor load.
OEM00074101	The Sercos master does not provide network configuration parameters for Sercos slaves (IP address, subnet mask, gateway).
OEM00074841	SSL connection is noticeably slow if client has chosen a cipher suite that uses DHE/ECDHE key exchange.
OEM00075485	Adding a TM5NS31 and I/O modules to a Sercos network impacts the M262 cycle task.
OEM00075670	WebVisualization: SelfAwareness variables cannot be used directly inside a WebVisualization.
OEM00076315	The diagnostic structures of PLCSystem/PLCSystemBase library (for example <code>PLC_R</code>) cannot be accessed directly from external monitoring devices through the Symbol Configuration . They first must be copied to local variables.
OEM00076939	All nodes in a ring topology need to support RSTP (rapid spanning tree protocol).
OEM00076940	EtherNet/IP Scanner: A "stateful" firewall keeps in its memory the connections flow. If such a firewall is defined, the EtherNet/IP traffic from slaves sending their assemblies in multicast may be blocked. So this firewall mode must not be used in this case.
OEM00077157	OTB devices may not respect the scanner RPI (Requested Packet Interval) when TM3 analog modules are configured.
OEM00077199	After transferring an application using an SD card, a TM3XHSC module may restart with an error message. A power cycle restores the correct operation.
OEM00077280	Using the <code>PLCO.MC_TouchProbe</code> with an invalid argument for <code>ifTrigger</code> is not managed as expected.
OEM00077663	If a firmware update using an SD card completes with a steady yellow SD card LED, repeat the firmware update operation.
OEM00077713	When you are modifying the user rights, ensure that no external equipment are trying to access M262 variables with former credentials.
OEM00077807	TM3 bus cycle time must not be set to a value greater than 200 ms when TM3XHSC modules are configured.

ID	Description
OEM00077830	<i>NbOfIncs</i> and <i>NbOfUnits</i> values must be < 2,147,483,647 (2 ³¹), else the capture is invalid.
OEM00077839	The boot time of a controller increases when the number of files increases.
OEM00077915 / BOC-304	The PWR LED turns to red when the internal temperature is > 80° (instead of > 100°).
OEM00076745	If EcoStruxure Machine Expert is running in a Virtual Machine (VMware), M262-USB may conflict with the VMware: <ul style="list-style-type: none"> USB communication is inoperable. The controller is not discovered in: <i>My Controller/Communication setting</i>. Install EcoStruxure Machine Expert directly on the PC or use Ethernet for PC connection to the controller.
OEM00077894	If SoMachine V4.3 or an earlier version was installed on the computer, the IP address used by the PC is not correct. Thus, the USB communication is not operational. Workaround: You have to select the network interface SE RNDIS PSX M262 connection under <i>Control Panel/Network and Internet/Network and Sharing Center</i> and set the IP address manually to 192.168.200.2.
OEM00077911	An M262 is not discovered by USB and cannot be connected to EcoStruxure Machine Expert. Workaround: You have to restart the USB by the gateway. Select the gateway tray application and restart the gateway.
OEM00077737	When unplugging and plugging an M262 cable (Eth2-RJ45), there was Modbus IO-scanner application loss on the ATV340.

M262 - Motion

ID	Description
MK-823	When working with 16 LXM32S and 23 TM5 BC and 1 SLC with multiple <i>MC_CamIn</i> running on all LXM32S, and when using a MAST task at 5 ms, the controller reports an overload of the task. Workaround: When working with big configurations, ensure that you use a proper cycle time for your controller task by verifying the load of your task during commissioning. Also, configure a Watchdog on your task to ensure that there is no overload during run time.
MK-835	<i>MC_TouchProbe</i> reports no error when the drive is disconnected. When you execute an <i>MC_TouchProbe</i> on an LXM32S and you disconnect the drive, the function block does not report an error. The output <i>Busy</i> stays active. Workaround: Make sure to cancel the running <i>MC_TouchProbe</i> using <i>MC_AbortTrigger</i> .
MK-847	Starting <i>MC_CamIn</i> with non-connected SSI-encoder as master results in the <i>ErrorID: Unexpected Feedback</i> . Workaround: If starting an <i>MC_CamIn</i> with an SSI-encoder as master, and this SSI-encoder is not connected to the M262, the <i>ErrorId</i> reported is <i>Unexpected Feedback</i> when it should be <i>MasterDataInvalid</i> .

HMISCU Controllers

ID	Description
OEM00077527 / SI-4094	The EcoStruxure Machine Expert Logic Builder command Refactoring > Rename is not available for HMISCU controllers. You must rename HMISCU controllers manually without the Refactoring feature.

Library Information

Version Identification

Description	Version
ApplicationLogger	1.1.2.0
AsyncManager	1.0.5.0
AutoTune	1.3.14.0
Booster Pumping	5.0.0.5
CommonMotionTypes	1.0.1.0
CrankModule	1.3.4.0
EMailHandling	2.0.4.0
EtherNetIP Explicit Messaging	1.1.7.0
EtherNetIP Remote Adapter	1.0.10.0
FileFormatUtility	1.2.6.0
FtpRemoteFileHandling	1.2.4.0
GMC Independent Altivar	1.2.4.0
GMC Independent Lexium	1.1.7.0
GMC Independent PLCopen	1.2.3.0
HttpHandling	1.0.11.0
M262 Encoder	1.0.0.2
M262 PLCSystem	1.0.0.19
M262Diagnostics	1.0.1.0
MotionInterface	1.1.75.12
MqttHandling	2.0.6.0
PackML	1.2.3.0
PD_AxisModule	1.6.2.0
PD_EDesignAxisModule	2.3.2.0
PD_EdesignCore	2.2.6.0
PD_EdesignCrankModule	1.5.2.0
PD_ETest	1.3.6.0
PD_GlobalDiagnostics	1.3.1.0
PD_MultiBelt	1.4.3.0
PD_MultibeltModule	1.4.1.0
PD_PacDriveLib	1.8.7.0
PD_SmartInfeed	1.4.3.0
PD_SmartInfeedModule	1.3.1.0
PD_SoMotionGenerator	1.5.1.0
PD_Template	1.6.1.0
PLCopen MC part 1	1.1.69.12
PreventaSupport	1.1.1.0
Robotic	2.12.1.0
RoboticModule	2.8.0.0
SchneiderElectricRobotics	2.8.0.0
SchneiderElectricRobotics Parameters	2.9.0.0

Description	Version
SchneiderElectricRobotics Toolbox	1.2.0.0
SercosCommunication	1.0.1.0
SercosDriveUtility	1.1.1.0
SercosMaster	1.1.75.12
SlcRemoteController	1.3.6.0
SnmpManager	1.2.1.0
SqlRemoteAccess	1.1.2.0
TcpUdpCommunication	2.0.11.0
TeSys island	1.1.0.0
TimeSync	1.1.2.0
Toolbox	3.0.1.0
TwidoEmulationsupport	1.2.2.0
Unwinder	1.2.3.0
UnwinderModule	1.1.0.0
UserMotorTypePlate	1.3.9.0
UserTorqueFeedForward	1.1.2.0

Version Identification Safety Libraries

Description	Version
EnableSwitch_SE_SF	V0.99 from 10/28/15
PLCopen_SF	V1.00 from 09/14/07
Preventa_SafeMotion	V0100.0100 from 02/08/16

Mitigated Anomalies

Libraries

ID	Description
OEM00077455 / IECLIB-2072	<i>FB_FtpClient</i> : Communication interruption during file transfer is now detected.

Known Operational Anomalies

Libraries

ID	Description
OEM00056474 / IECLIB-94	<p>AxisModule library: The command <i>ET_Cmd.StartTrigWaitInPos</i> is sent to the <i>FB_AxisModule</i> to perform a positioning while the command is active, the input <i>iq_diCmd</i> is overwritten by the value 0.</p> <p>In this situation, the <i>FB_AxisModule</i> triggers the diagnostic message <i>UnexpectedProgramBehavior (DiagExt = UnknownCase)</i>.</p> <p>Workaround: Re-enable the function block to quit the diagnostic message.</p>
OEM00072319 / IECLIB-1966	SmartInfeed library: Using the <i>ET_TargetGeneratorMode.External</i> in combination with the <i>FB_VelocityRatioAlgorithm</i> and defining an invalid target position triggers a <code>page fault</code> exception.
OEM00073262 / IECLIB-2427	MultiBelt library: If the start station is defined as a <i>PassBy</i> station, the second train remains in arriving state (<i>ET_TrainState.Arriving</i>).

ID	Description
OEM00073263 / IECLIB-2428	MultiBelt/MultiBeltModule library: Under certain conditions, after stop and warmstart of a <i>MultiBelt</i> module, the <i>ET_DiagExt</i> message <i>TrainMovesBackward</i> is displayed.
OEM00074810 / IECLIB-1739	Unwinder library, precontrol movement by an external master (bobbin radius changes): The <i>Setpos</i> value for this movement is incorrect if <i>DRV_WinderRight.Direction = left</i> .
OEM00075899 / IECLIB-2444	MultiBelt/MultiBeltModule library: The <i>q_xHomeOk</i> bit of all trains is set to TRUE in homing mode <i>HomeOnTp</i> , even if the homing procedure was stopped due to missing TouchProbe signals.
OEM00076350 / IECLIB-1883	Unwinder/UnwinderModule library: A basic load is required when the unwinder is empty. The basic load value is replaced by the calculated value but the calculated value should be added to the basic load value.
OEM00076417 / IECLIB-2448	MultiBelt/MultiBeltModule library: Under certain conditions, a train starts moving backwards after a coldstart, but is stopped immediately. An error message is displayed.
OEM00074744 / LMCFW-2010	SystemInterface library: Calling the <i>FC_TPEdge</i> triggers the diagnostic message <i>8902 Software error (page fault)</i> in the RTP (Real Time Process) task, and the controller displays a hardware watchdog message.
OEM00077150 / IECLIB-2031	TcpUdpCommunication library: At first startup after firmware update, the certificate store is not ready. An application that includes TLS communication needs a second startup.
OEM00078797	Writing a nameplate by use of <i>FB_InitMachineEncoder</i> results in high tracking deviation. Workaround: Restart Sercos bus after the nameplate is written.
OEM00078768 / IECLIB-2231	Leaving multibelt <i>OpMode</i> and restarting to automatic mode by executing a warm start may trigger a <i>page fault</i> .
OEM00078541 / ROB-94	Robotic: The EcoStruxure Machine Expert installation does not include the library <i>ARMIO</i> .

Software Information

Version Identification

Description	Version
Machine Expert Installer	11.19.16801
Diagnostics	18.1.1.0
Controller Assistant	18.1.1.0
Device Assistant	18.1.1.0
DiffViewer	18.1.1.0
Gateway	18.1.1.0
Launcher	18.1.1.0
OPCServer	3.5.12.70
SoftSPS	3.5.12.80
SVN	4.2.4.0
Logic Builder ⁽¹⁾	1.1
Vijeo-Designer	6.2.8.4008
CoDeSys	V3.5 SP12 Patch8 HF2
SQL Gateway	18.0.1.0
Motion Sizer	4.1.0.0
(1) If using a virtual machine, the download of the online help operates correctly only if the option Accelerate 3D graphics is deactivated in the VM settings.	

Compatibility EcoStruxure Machine Expert

Overview

EcoStruxure Machine Expert can be installed in parallel to other Schneider Electric software products, such as SoMachine and SoMachine Motion.

For general information on compatibility of EcoStruxure Machine Expert, refer to the Compatibility and Migration Guide (see EcoStruxure Machine Expert Compatibility and Migration, User Guide).

EcoStruxure Machine Expert V1.1 SP1 updates the existing EcoStruxure Machine Expert V1.1 installation.

Mitigated Anomalies

Controller Assistant

ID	Description
OEM00078093 / SI-4431	The command line from the Controller Assistant did not support a command to list the available Sercos slave versions.

EcoStruxure Machine Expert

ID	Description
OEM00078173 / TES-152	EcoStruxure Machine Expert did not stop monitoring from variables in online mode even if the variable was not visible. In some cases, this caused high memory load and slow down of online monitoring in specific or huge projects.
OEM00078040 / OEM00077799 / LMCFW-1302 / SI-4379	If Execute program was selected as the behavior for outputs in Stop mode and an exception occurred in the controller (e.g. a division by 0), the communication between EcoStruxure Machine Expert and the controller stopped if the POUs for implicit checks were active in the project and a new Application download was executed.
OEM00078036 / OEM00077749 / TES-152	In the event of some specific or huge projects it could happen that EcoStruxure Machine Expert froze periodically every few minutes. In these cases the used RAM from the EcoStruxure Machine Expert went from 6 GB to 4 GB.
OEM00077971 / OEM00077799 / SI-4379	The communication between EcoStruxure Machine Expert and the controller stopped with an error detected in <code>GlobalInit</code> if the function block input was assigned via direct addressing (AT%).
OEM00077962 / OEM00077791 / TES-152	In big projects expanding an array in online mode (watchlist, declaration editor) EcoStruxure Machine Expert could freeze for up to 10 seconds.
OEM00077833 / TES-152	It was not possible to execute an online change after modifying a variable of an FBD program which contains structs, arrays, etc.
OEM00076607 / OEM00077711 / TES-152	When modifying the trace configuration (insertion, deletion, display / hiding) of variables, the cursor went to the beginning of the configuration.
OEM00075276 / CDSYS-256	When a trace was shown in Logic Builder, the values were not displayed properly and the next value on the left-hand side was displayed. It was necessary to select the variable itself to see the exact value from the cursor.
OEM00077734 / OEM00074209 / PLAT-98	When using direct addressing in the EcoStruxure Machine Expert project, an advisory message was displayed everytime you performed a build (F11) of the project. This dialog box had to be confirmed by pressing Alt + F.
OEM00078553 / SI-4555	The sub-objects (Methods, Properties, ...) were locked in SVN when the parent object (POU) was modified.
OEM00078290 / SI-4457	The project update changed the offline parameter value of <code>ControlMode</code> .
SI-4261	Sometimes an unhandled exception occurred (...HWND...) in combination with DTMs.

ID	Description
SI-4514	EcoStruxure Machine Expert shell did sporadically not work with controllers in simulation mode (unsuccessful login).
SI-4652 / OEM00078509	EcoStruxure Machine Expert opened the SLC Remote Controller example instead of the Quick Motion Programming.
OEM00077162 / SI-3909	A CSV export did not contain all data in case of a 2-dimensional array of DUT.
OEM00078358 / SI-4571	LibDoc scripting transformation is not working
IECLIB-2187	Function Template for HttpClient has been implemented

Known Operational Anomalies

EcoStruxure Machine Expert

ID	Description
OEM00064709 / MS-1900	Motion Sizer: The torque/speed curve of the SH205/30360 with an external fan is calculated incorrectly.
OEM00067341 / MS-1898	Motion Sizer: The performance of the Motion Sizer with large projects is slow while entering axis names and descriptions (slow refreshing).
OEM00072759 / MS-1910	Motion Sizer: It is not possible to add Lexium 62 ILM drives of different sizes to the same connection module. The rounding operation for the cycle time does not provide suitable values.
OEM00069953 / BOC-550	To display different comments for libraries you can enter the key <i>LibDocContent</i> . Using <i>LibDocContent</i> with <i>DocsOnly</i> or <i>CommentsAndDocs</i> , the same results are displayed.
OEM00073945 / BOC-547	Accessing a variable name of the TM5 module I/O mapping is not possible with Python scripting using an ARRAY.
OEM00075351 / BOC-544	You log in to a project (FBD code) and put the focus on a network (which is not the last one) in an action/program. If you log out and log in again, the focus will be on the last network in the action/program. The same behavior is shown up, if you switch between two actions.
OEM00075726 / LMCFW-2016	A Cam switch task sporadically triggers the diagnostic message <i>8317 Program cycle time overrun</i> , although the Cam switch task is configured with a higher prior than the RTP (Real Time Process) cycle.
OEM00063214 / BOC-90	TCP socket communication is delayed sporadically when the programming software is connected to the controller.
SI-3439	While converting a device during Update Project , you may be asked to delete internal data of persistent variable lists. Depending on the number of devices to be converted, this question may occur several times. Confirming it will avoid asking again for devices of the same controller.
SI-3971	When you convert a controller, for example, an M262L20 to an M262M35, the module configuration of the TM5/TM7 interface is not converted and is no longer available after conversion. Workaround: <ol style="list-style-type: none"> 1. Export and remove the TM5_Interface before the conversion. 2. Start the conversion. 3. Import the TM5_Interface after the conversion.
SI-3727	For ATV-DTM with activated control panel, the Disconnect command does not have any effect when the motor accelerates (ACC), turns constantly (RUN) or decelerates (DEC). To stop the motor, press the Stop button. Nevertheless, the control panel is not updated and still displays the state that was active before. You can execute the Online > Logout command, but this may have the effect that EcoStruxure Machine Expert is being closed.
OEM00076442 / SI-3505	Context sensitive help (F1) is not available for POUs declared with namespace.
–	If you are using a Virtual Machine (VM) you must deactivate the option Accelerate 3D graphics in the VM settings before downloading the online help.
SI-4244	ATV340: The DTM is not available.

EcoStruxure Machine Expert - Safety

ID	Description
OEM00078801	Exchanging data between an M262 controller and an SLC is not operable if not both directions are configured. Workaround: Configure at least one exchange data in both directions, then the data exchange becomes operable.

Documentation - Mitigated Anomalies

Documentation

The online help is updated with the following documentation:

- M262 Diagnostics Library Guide
- M262 Logic/Motion Controller - Programming Guide
- M262 Logic/Motion Controller - Hardware Guide
- TM3 Expert Modules - Hardware Guide
- TMS Expansion Modules - Hardware Guide

ID	Description
OEM00077576 / BOC-276	M262 documentation of cloning procedure wrongly said that the ERR Led flashes at the end of successful cloning procedure.
OEM00077931 / BOC-288	Incorrect encoder transmission speed list and default value in M262 documentation.
OEM00077981 / BOC-291	M262 documentation must inform that the network name modification is applied at next power ON.
OEM00077984 / BOC-292	M262 industrial plug and work documentation did not include the information that the locate button must be used to well identify the target device.
OEM00077991	M262 documentation did not include an explanation on how to remove user rights using a script with command format .
OEM00078056 / BOC-297	M262 Programming Guide: Incorrect link to Modicon M262 Logic/Motion Controller Sercos Configuration.
OEM00078083 / BOC-298	TM3 Expert I/O Modules Hardware Guide: Incorrect description of LEDs state when a TM3X•HSC• module is not configured.
OEM00078297 / BOC-305	M262 Programming Guide contained several minor incorrect descriptions.
OEM00078298 / BOC-306	Incorrect ISO standard reference for CAN characteristics of the TMSCO1 module.
OEM00072944 / BOC-199	M262 documentation did not contain the information that Reset origin command makes the web visu files erased.

Documentation - Known Operational Anomalies

Documentation

ID	Description
OEM00032469	Detailed information required for WD (watchdog) of the logic motion controller LMC •01. Documentation needs to be enhanced.
OEM00045026	Some dimension values provided by the hardware guides and the CAD files on the Schneider Electric homepage are slightly different for LXM 52 drives, LXM 62 drives and LMC Eco Motion Controllers. Documentation needs to be enhanced.
OEM00058892	In the Online Help, the chapter <i>TM5 / TM7 System - Load Breaking (TM5/TM7 System Planning and Installation Guide)</i> needs to be enhanced.
OEM00071212	The Online Help for the TM5SEAI5G module (<i>Modicon TM5, Expansion Modules Configuration, Programming Guide</i>) provided incorrect ranges for the analog input register.

ID	Description
OEM00076210 / BOC-243	The information on the TM5SPS1 power supply module needs to be enhanced in the Online Help.
OEM00077834	Lexium 62 Plus: The encoder output frequency is limited to 1 MHz, interpolation factor is set to 16 increment cycles per Sinus/Cosinus period of the analog encoder.
—	<p>PLCopen MC part 1: The following text and warning need to be added to the library documentation.</p> <p>If the position value of the master leaves the defined cam position range, the cam signals that the end of the cam profile has been reached. This implies that a buffered job is activated, regardless of whether the master has left the cam position range in a positive or a negative direction. The master can also leave the cam position range as a result of jitter if the master is at a standstill at a position sufficiently close to the positive or negative limit of the cam position range.</p> <p>See important safety information at the end of this table.</p>
—	<p>PLCopen MC part 1: A hazard message needs to be added to the library documentation.</p> <p>See important safety information at the end of this table.</p>
OEM00077826 / BOC-285	Remove in the online help the statement that for the <code>AccelerationTorqueLimit</code> and <code>DecelerationTorqueLimit</code> parameters the value zero deactivates the torque limit.
OEM00078341 / BOC-315	Maximum number of files in the Message Logger must be documented.

⚠ WARNING
UNINTENDED EQUIPMENT OPERATION
<p>Implement all measures required to ensure that a job is only buffered if a sufficient distance from the position value to the end of the cam position range can be respected.</p> <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p>

⚠ WARNING
UNINTENDED EQUIPMENT OPERATION
<p>Implement a filter for the master velocity and acceleration if you have an axis that follows a feedback axis master.</p> <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p>

EcoStruxure Machine Expert V1.2

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M241	5.0.8.4
M251	5.0.8.4
M262	5.0.4.7
TMSES4	1.0.0.8
TM3BCEIP	1.2.1.2
TM3BCSL	1.0.15.11
TM3•HSC202•	2.0

Description	Firmware Version
TM3DI16	2.0
TM3DI16G	2.0
TM3DI16K	2.0
TM5NEIP1	1.07
TM5NS31	2.74
LXM32S***M2 drive	V1.10.01
LXM32S***M2 Sercos	V1.10.03
LXM32S***N4 drive	V1.10.01
LXM32S***N4 Sercos	V1.10.03
LXM52***C****	1.54.26.0
ILM*****	1.54.26.0
LXM62***C****	<ul style="list-style-type: none"> • 1.62.07.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62***D****	<ul style="list-style-type: none"> • 1.62.07.0 for hardware revision RS1• • 1.54.27.0 for hardware revision RS0•
LXM62***E****	1.54.27.0
LXM62***F****	1.54.27.0
LXM62***G****	1.62.07.0
LMC Eco	V1.62.05.07
LMC Pro	V1.62.05.07
LMC Pro2	V1.62.05.07
ATV340S	<ul style="list-style-type: none"> • Drive firmware: OPAL_V1.4IE09_B06 • Copla firmware: Sercos3_A1.2IE01_B00

Description	Safety-Related Firmware Version
LXM62***E****	1.2.4.0
LXM62***F****	1.2.4.0
VW3E702200000 safety option module	1.2.4.0
TM5CSLC100FS	2.52
TM5CSLC200FS	2.52
BWU2984 SWID	134253
BWU2984 Safe CPU A	135115
BWU2984 Safe CPU B	135116
ASIMON360	3.2.6.7

Contact your local Schneider Electric representative in case you need specific information for your intended machine architecture.

New Features

TM3 Serial Line Bus Coupler

TM3 Serial Line Bus Coupler is a distributed architecture solution. It allows you to create distributed islands of industrial TM3 I/O modules managed by a master controller M241, M251, or M262 via Modbus Serial Line fieldbus.

New features:

- Support of TM3 and TM2 I/O modules:
 - Up to 14 TM3 I/O modules.
 - Up to 7 TM2 I/O modules.

- Up to 7 TM2 I/O modules mixed with TM3 I/O modules.
- Embedded webserver supporting:
 - User rights management
 - Bus coupler maintenance such as speed configuration, firmware upgrade, and diagnostics logs.
 - Island I/O monitoring and control.
- Isolated RJ45 ports to support daisy chaining.

Limitations:

- The latch feature is not supported by TM3DI16, TM3DI16G, TM3DI16K.
- TM3 expert I/O modules are not supported.
- Only a single user can modify the firmware update or write values through the embedded webserver.
- The number of TM3 I/O modules is validated by the software. Depending on the number of analog I/O and/or safety modules used, the maximum number of TM3 I/O modules allowed may be reduced.
- Slave addresses are valid from 1...127.

TM5 EtherNet/IP Bus Coupler

TM5 EtherNet/IP Bus Coupler is a distributed architecture solution. It allows you to create distributed islands of industrial TM5/TM7 I/O modules managed by a master controller M241, M251, M262, or LMC controllers via Ethernet fieldbus.

New features:

- Support of TM5 and TM7 I/O modules.
- Embedded webserver supporting:
 - User rights management
 - DHCP, fixed IP configuration
 - Bus coupler firmware update
- Embedded switch with isolated RJ45 ports to support daisy chaining.
- ODVA (Open DeviceNet Vendors Association) certification

Limitations:

The following TM5 / TM7 modules are not supported:

- All TM5/TM7 safety I/O modules.
- TM5SE1RS2 RS232 Serial interface module
- TM5SE1MISC20005 Encoder output module
- TM5SDM8DTS 4DI/4DO Timestamp module

Plug&Work (Machine Assistant)

- PW2-4 Machine Instance Name: The controller name can be modified from the Machine Assistant. The IP address of the controller can be modified from the Machine Assistant.
- PW2-13 One Cable: You can create temporary routes to devices under another interface from the Machine Assistant.
- PW2-33 Bonjour Service: The M262 controller can be discovered using Apple devices.

PacDrive LMC Eco/PacDrive LMC Pro/Pro2 Cybersecurity Implementation

In PacDrive LMC Eco/PacDrive LMC Pro/Pro2 controllers IP forwarding is disabled using firewall settings.

NOTE: To help keep your Schneider Electric products secure and protected, it is in your best interest that you implement the cybersecurity best practices as indicated in the *Cybersecurity Best Practices* document provided on the Schneider Electric website.

PacDrive LMC Eco/PacDrive LMC Pro/Pro2 - ATV340S

It is a good practice not to connect more than the following number of ATV340S to the PacDrive LMC controllers:

PacDrive LMC controller	Maximum number of ATV340S
PacDrive LMC Eco	15
PacDrive LMC Pro/Pro2	25

M241 / M251 Logic Controllers

Support for the new TM3 high-speed counter modules:

- TM3XHSC202
- TM3XHSC202G

M262 Motion Controllers

- Encoder enhancements:
 - New object for LXM32S onboard PTI (Pulse Train In) encoder to be used as feedback axis with motion function blocks.
 - New object for LXM32S encoder option module (analog and digital) to be used as feedback axis with motion function blocks.
 - Filter parameter available for the encoder objects.
 - *DeadTimeCompensation* parameter available for the encoder objects.
- New object for direct support of ATV340S.

-	M262-15			M262-25			M262-35		
	1 ms	2 ms	4 ms	1 ms	2 ms	4 ms	1 ms	2 ms	4 ms
Sercos cycle time	1 ms	2 ms	4 ms	1 ms	2 ms	4 ms	1 ms	2 ms	4 ms
Total maximum number of Sercos devices allowed	8	16	16	12	16	24	16	24	40
Number maximum devices: TM5NS31 (TM5 range), TM5CSLCx00 safety controller, third-party devices	4	12	12	8	8	16	8	8	24
Number maximum devices: LXM32S, ATV340S	4	4	4	4	8	8	8	16	16

M262 Cybersecurity Implementation

In order to meet cybersecurity requirements, the Modicon M262 Logic/Motion Controller has been designed in accordance with the standard IEC 62443-3-3. As this standard constantly evolves, the Modicon M262 Logic/Motion Controller is compliant with a part of the 2019 standard.

To be compliant with the standard, the following modifications are implemented by default on the Modicon M262 Logic/Motion Controller:

Dialog box / Issue	Default setting / Solution
MyController > Ethernet Services > IP Routing	IP forwarding is disabled.
MyController > Ethernet _1 or MyController > Ethernet _2	Only the secured protocol is active.
The first access by webserver / FTP is denied.	Modify the default user name and password by using EcoStruxure Machine Expert.

For further information, refer to the *Cybersecurity Information for User Rights Management* chapter, page 10.

NOTE: To help keep your Schneider Electric products secure and protected, it is in your best interest that you implement the cybersecurity best practices as indicated in the *Cybersecurity Best Practices* document provided on the Schneider Electric website.

M262: TMSES4 Support

The capability to manage three TMSES4 modules on the left bus is embedded in version 5.0.4.7 of the following M262 platforms:

- M262L20MESE8T
- M262M25MESS8T
- M262M35MESS8T
- M262L10MESE8T
- M262M15MESS8T

NOTE: A maximum of three Ethernet or CANopen TMS modules is supported.

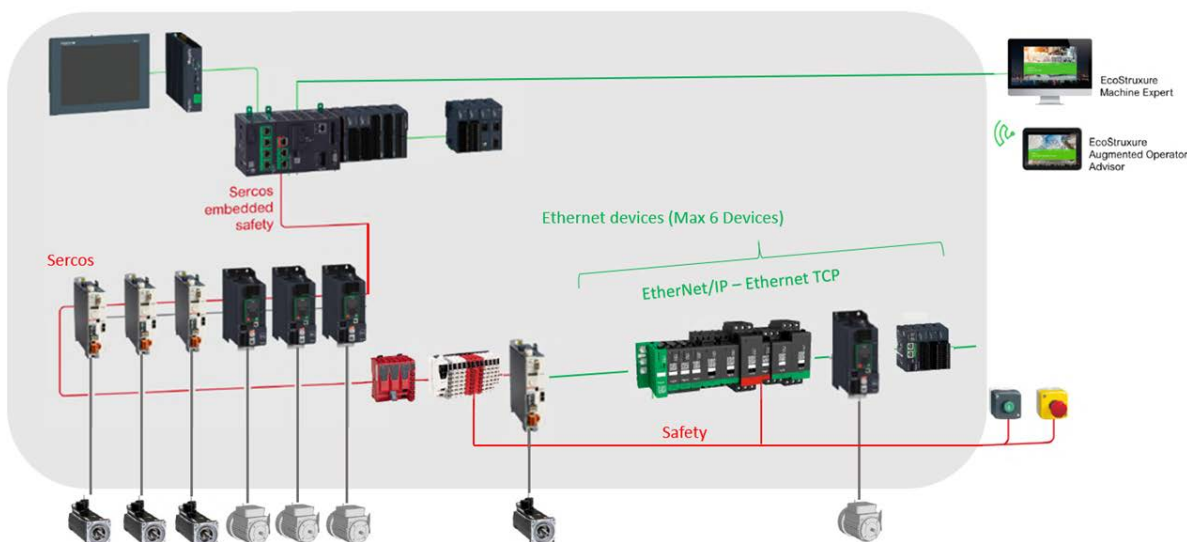
Examples:

- 2 TMSES4 modules and 1 TMSCO1 module
- 3 TMSES4 modules
- A maximum of one TMSCO1 module is supported.

M262: Single Wiring Coexistence (SWC) Architecture

In addition to real-time and safety-related data exchanged via Sercos, Sercos allows to transmit other Ethernet protocols, such as EtherNet/IP and TCP/IP in parallel.

The SWC architecture allows you to manage Sercos devices and EtherNet/IP or TCP/IP devices via a single cable.



An additional gateway is not required. Configuration is performed in EcoStruxure Machine Expert. Place the Ethernet device after the last Sercos device. The last Sercos device is used as a gateway. It must provide two Sercos connectors.

Considerations:

- Connect the Ethernet devices after the last Sercos device.
- Connect a LXM32S or ATV340S as last device on the Sercos bus.
- Connect a maximum of six Ethernet devices.
- Ethernet communication is operational when the Sercos bus is in phase 4.

NOTE: It is a good practice to stop the Ethernet communication when the Sercos bus is not in phase 4. To stop the EIP / TCP scanner, use the function blocks in the IEC application.

M262 Modifying the Default IP Address of the USB Port

By default, the IP address of the USB port is 192.168.200.1. Customers expressed the need to alter this address as it may conflict with their internal addressing schemes for existing Ethernet industrial networks. You are now able to change this address in the case that this IP address conflicts with the existing network configuration by modifying the address through the post configuration functions. Contact your local Schneider Electric service representative for more information on this expert topic.

Lexium 62 Servo Drives

Support of SH3 servo motors with Hiperface DSL-encoder and OneMotorCable connectivity.

Mitigated Anomalies

HMISCU Controllers

ID	Description
OEM00046432	HMISCU controller Panels: Sporadically, the communication between the HMI and the controller was interrupted without displaying an error message. You had to restart the HMISCU to re-establish the communication.

M241/M251 Controllers

ID	Description
OEM00072152 / PLAT-488	The termination of Modbus TCP connections was not handled correctly when the controller was acting as a Modbus TCP client.
OEM00077994 / PLAT-567	Using fast output operations in first application MAST cycle sometimes resulted in an exception.
OEM00070503 / PLAT-466	Sporadically, an error on a Modbus TCP IO scanner channel was not detected when the last one was not in error state.
PEP0541743R	Ethernet frames smaller than 60 bytes were not null byte padded.
PEP0545408R / BOC-350	Default range for M251 Ethernet port 1 and M241 TM4ES4 IP address has been changed to 10.11.x.y (x and y 5th and 6th bytes of interface MAC address) with a mask of 255.255.0.0.
OEM00074965	M251: Reading the <code>PLC_R</code> structure via the Symbol Configuration triggered a system watchdog error message.
OEM00075411 / PLAT-536	M251MESC: For Modicon M251MESC Logic Controllers, the cloning operation to an empty SD memory card (and other scripts like upload and download) did not operate.
OEM00078373 / PLAT-574	Insufficient session ID length in cookie.
OEM00078372 / PLAT-573	Sensitive information stored in cookie.

ID	Description
OEM00078369 / PLAT-572	Session password was transmitted in clear text.
OEM00078368 / PLAT-571	Webserver was vulnerable to cross-site request forgery attack.
PLAT-597	Entering incorrect credentials in the webserver was leading to a controller exception.

LXM32S

ID	Description
SER-VO00002939 / SERVO-251	The device MAC address was incorrectly displayed when read over the associated Sercos parameter.
SER-VO00002905	Position capture was not working when trigger was configured to record it on both signal edges.

Lexium 32

ID	Description
MK-733	Using the LXM32S did not map more than 6 additional IDNs to the cyclic data. NOTE: Lexium32S TouchProbe is counted as 4 IDNs and diagnostic message S-0-0390 is counted as 2 IDNs.

M262

ID	Description
OEM00076809	M262 Motion Controllers did not support the EtherNet/IP Scanner if used on the same port as the Sercos devices.
OEM00073473	TM5NS31 required the firmware version 2.74 or greater.
OEM00072876 / BOC-302	NVL/GVL (Network Variable List/Global Variable List) only worked if an Ethernet cable was plugged in the Ethernet port 1.
OEM00074106	TM5NS31 scan time on the TM5 bus was only taken into account after the next power cycle of TM5NS31.
OEM00076657	M262: When a network scan was performed, the EtherNet/IP connection to the Modicon M262 Logic/Motion Controller was sporadically disconnected without any message indicating the loss of connection.
OEM00076721	M262: If a Modicon M262 Logic/Motion Controller was connected via a USB interface, a restart was required to allow a connection to the controller after a network scan had been performed.
OEM00077207	M262: If an M262 was used as an EtherNet/IP Scanner and as an EtherNet/IP Adapter simultaneously, some devices could be temporarily disconnected.
OEM00077940	When OPC UA was configured in the application, the application had to be downloaded using the menu command Online > Login (instead of the menu command Online > Download).
M262- 4336	An anomaly was reported with the delivery of the Firmware V1.1 SP1 - V5.0.3.2. After every 24 days of consecutive operation of the controller, the controller would reboot automatically and restart as if without an application loaded. The issue, now resolved, required a work-around of cycling controller power prior to the expiration of the 24 day period.

PacDrive LMC Controls & I/Os

ID	Description
OEM00072576 / LMCFW-916	Both EtherNet/IP adapters are now operational when C2C master is enabled by default.
OEM00078575 / LMCFW-2076	C2C sometimes reported <code>sync failed</code> in combination with safety and a large number of Sercos slaves.

Known Operational Anomalies

ATV340S

ID	Description
GE-DEC00240596	When using PacDrive LMC Pro2 and ring topology, ring healing performed after the Sercos ring has been broken can result in the Sercos communication phase switching to phase 11 (error detected). Workaround: To be able to switch to phase 4, perform a <code>DiagQuit</code> .
GE-DEC00266016	In case ring healing is performed after the Sercos ring has been broken, the connection between the EtherNet/IP slaves and the master can be interrupted for a few seconds (communication state No Connection).

Lexium 32

ID	Description
SER-VO00002953 / SERVO-258	Sporadically, the drive advisory code is delayed from one Sercos cycle. The entry in the device logger displays <code>0x0000</code> instead of the drive advisory code.
SER-VO00002913 / SERVO-229	Sporadically, reading/writing manufacturer-specific parameters via SVC (Service Channel) leads to a timeout (error <code>0x7016</code>). NOTE: The issue is solved with Sercos3 module hardware having FPGA firmware V1.20.

Lexium 52 / 62 / 62 ILM

ID	Description
SERVOD-261	Lexium 62 Plus: If a download is not executed successfully and another attempt is performed by executing a firmware update, a misleading error message is displayed.
LMCFW-1616	Lexium 62 Plus: A parameter has been renamed in function <code>FC_BrakeCheckSet</code> .
SERVOD-163	Lexium 62 Plus: LEDs indicate that an error has been detected in communication phase CP0. Use case with Lexium BMP synchronous motor: Motor type plate to be configured in LXM62 drive.
SERVOD-147	Lexium 62 Plus: It is not possible to modify parameters of type <code>ES</code> . After an online change of the parameters, phase down and phase up is performed in different topology.
SERVOD-152	Lexium 62 Plus: Sporadic error is detected during phase up <code>0x2000B</code> : Phase up is not executed and machine operation is not possible.
LMCFW-1817	Lexium 62 Plus: Sercos phase up is not possible if devices are addressed with Identification mode = Application type .

M241/M251

ID	Description
OEM00079046	<p>When a TM3 HSC is be used together with TM2 modules, the system performances are impacted.</p> <p>When a Freewheeling task is defined, the task duration is increased. When the Cyclic mode is active, increase the MAST cycle time. Otherwise, a CPU load exception can occur.</p> <p>It is a good practice to configure a minimum MAST cycle time of 30 ms (or more), depending on the application size.</p>
OEM00079107	<p>On connecting using Connection mode = IP Address, the user is prompted to enter the credentials.</p> <p>Workaround:</p> <ol style="list-style-type: none"> 1. Use the Connection mode = IP address via NAT (Remote TCP). 2. Enter the controller IP address into the NAT Address field. 3. Click the Refresh button. 4. Double-click the controller from the controller list to establish a connection.
OEM00070134 / PLAT-459	Sporadic loss of controller IP address when power cycling the controller.

M262

ID	Description
OEM00079151	<p>Webvisualizaton: Each refresh of variable manages a communication access if the user rights are validated, a password will be requested for these actions.</p> <p>Username and password are requested each time a page refresh / online change/ application download is performed by the webvisualizaton.</p>
OEM00076931	In case an SLCx00 or TM5NS31 is the last Sercos device in the SWC architecture, the PhaseUp may be not possible.
OEM00079179 / PLAT-588	<p>The content of the object type ARRAY read for an <i>ETH_R</i> structure is not correct when displayed on an HMI.</p> <p>Workaround: Copy the value to an intermediate variable (not accessing <i>ETH_R</i> directly).</p>
OEM00079052 / PLAT-585	<p>The content of elements (<i>i_byFirmVersion</i>, <i>i_byFirmVersion</i>) in the <i>PLC_R</i> data structure is not correct when displayed on an HMI.</p> <p>Workaround: Copy the value to an intermediate variable (not accessing <i>PLC_R</i> structure elements directly).</p>
OEM00079223	An error is detected when rebooting projects with 4 KB retain variables.
SI-4694	<p>The download may be unsuccessful and the message <code>TLS_IO_Communication</code> is displayed.</p> <p>Workaround: Deselect the option Encrypted Communication in the Communication Settings tab in controller selection mode of the EcoStruxure Machine Expert Logic Builder.</p>

M262 - Motion

NOTE: The Modicon M262 Logic/Motion Controller does not support Advanced Message Queuing Protocol (AMQP).

TM3 Bus Coupler Serial Line TM3BCSL

ID	Description
OEM00078558	<p>When bus ownership is held by the webserver, the controller is blocked from retaking bus ownership but there is no notification of the reason in EcoStruxure Machine Expert.</p> <p>Workaround: Make sure that the bus ownership is released by the webserver before restarting operation between the controller and the TM3BCSL.</p>
OEM00079152	<p>In EcoStruxure Machine Expert, setting the Monitoring Timeout of the TM3BCSL to 0 also effectively prevents the webserver from taking bus ownership. There is no notification of this reason on the webserver.</p> <p>Workaround: Configure a Monitoring Timeout value that is appropriate for the intended system behavior.</p>
OEM00078760	<p>In EcoStruxure Machine Expert, you can manage a maximum of 10 TM3 safety-related modules on the same TM3 bus, either behind the M262 or the bus coupler.</p>

Library Information

Version Identification

Description	Version
ApplicationLogger	1.1.2.0
AsyncManager	1.0.5.0
AutoTune	1.3.14.0
Booster Pumping	5.0.0.5
CommonMotionTypes	1.0.1.0
CrankModule	1.3.4.0
EMailHandling	2.0.4.0
EtherNetIP Explicit Messaging	1.1.8.0
EtherNetIP Remote Adapter	1.0.10.0
FileFormatUtility	1.3.5.0
FtpRemoteFileHandling	1.3.0.0
GMC Independent Altivar	1.2.4.0
GMC Independent Lexium	1.1.7.0
GMC Independent PLCopen	1.2.3.0
Hoisting	5.0.0.1
HttpHandling	1.1.4.0
M262 Encoder	1.0.3.2
M262 PLCSystem	1.0.0.19
M262Diagnostics	V1.0.3.0
MotionInterface	1.1.75.21
MqttHandling	2.0.8.0
PackML	1.2.3.0
PD_AxisModule	1.6.2.0
PD_EDesignAxisModule	2.3.2.0
PD_EdesignCore	2.2.6.0
PD_EdesignCrankModule	1.5.2.0
PD_ETest	1.4.1.0

Description	Version
PD_GlobalDiagnostics	1.3.1.0
PD_MultiBelt	1.4.4.0
PD_MultibeltModule	1.4.1.0
PD_PacDriveLib	1.9.3.0
PD_SmartInfeed	1.4.4.0
PD_SmartInfeedModule	1.3.1.0
PD_SoMotionGenerator	1.5.1.0
PD_Template	1.6.1.0
PLCopen MC part 1	1.2.77.21
PreventaSupport	1.1.1.0
Robotic	2.14.0.0
RoboticModule	2.10.0.0
RoboticsAutoTune	2.0.0.0
SchneiderElectricRobotics	2.10.0.0
SchneiderElectricRobotics Parameters	2.11.0.0
SchneiderElectricRobotics Toolbox	1.5.0.0
SercosCommunication	1.0.1.0
SercosDriveUtility	1.1.1.0
SercosMaster	1.2.79.21
SlcRemoteController	1.3.6.0
SnmpManager	1.2.1.0
SqlRemoteAccess	2.0.1.0
TcpUdpCommunication	2.0.15.0
TeSys island	1.1.0.0
TimeSync	1.1.2.0
Toolbox	3.0.1.0
TwidoEmulationsupport	1.2.2.0
Unwinder	1.2.4.0
UnwinderModule	1.1.0.0
UserMotorTypePlate	1.3.9.0
UserTorqueFeedForward	1.2.2.0

Version Identification Safety Libraries

Description	Version
EnableSwitch_SE_SF	V0.99 from 10/28/15
PLCopen_SF	V1.00 from 09/14/07
Preventa_SafeMotion	V0100.0100 from 02/08/16

New Features

HttpHandling

New methods available:

- *Put*

- *Head*
- *Delete*

FileFormatUtility

The new function block *FB_XmlItemsUtility* provides a comprehensive set of utilities to get information from the data or to modify them. In addition, it is provided to create a complete new data set.

FtpRemoteFileHandling

The FTP client functionality supports asynchronous execution.

SqlRemoteAccess

The new function block *FB_SqlDbRequest* is used for secured/unsecured communication between the library and the SQL Gateway.

NOTE: Secured communication is only supported by M262 controllers.

TcpUdpCommunication

- The new method *SockOpt_EnableKeepAliveExtended* is used to configure the keep alive for TCP client and server to help detect communication interruption on M262 controllers.
- The *Close* procedure is processed in *Closing* state also by calling the method *State*.

RoboticsAutoTune

The RoboticsAutoTune library allows you to tune the Schneider Electric P-Series robot.

Hoisting

New function block *HoistDutyRating* collects run time data and calculates the actual mechanical class corresponding to the usage. This data can be used to identify whether the crane is being used according to its specification.

New function block *AdvancedPositionSync* can synchronize multiple linear axes with identical or different motors, gears, and encoders. The block can retain information about positions of synchronized axes and their synchronization status when the machine is switched off.

New function block *OperatingAreaRestrictionIC* helps to prevent a physical contact between the suspended load and obstacles located within the operating area of the crane. The restricted areas are defined in Cartesian coordinates. The function block supports definition of polygonal restricted areas.

Mitigated Anomalies

Libraries

ID	Description
OEM00078224 / IECLIB-2142	When disabling the MultiBelt in certain situations, a Set position command on the axis of a train was executed during the warm start. This resulted in an offset of the mechanical position of the train.
OEM00077558 / OEM00077938 / IECLIB-2121	SmartInfeed: During the correction movement of a SeriesBelt, an unintended error with <i>q_etDiag = Unexpected program behavior</i> , <i>q_etDiagExt = UnknownFeedback</i> , and <i>q_sMsg = 'NoJobWhileAxisMoving'</i> could be triggered.

ID	Description
OEM00071749 / IECLIB-2312	<i>PDL.FB_HomeAbs</i> and <i>PDL.FB_HomeSetPos</i> work correctly if a fraction of <i>UserPeriod</i> and <i>EncoderPeriod</i> cannot be represented exactly as a binary break.
OEM00073767 / IECLIB-2326	TcpUdpCommunication library: Method <i>SockOpt_EnableKeepAliveExtended</i> to configure the keep alive for the TCP client and server to detect communication interruption on the M262 controller.
OEM00067842 / IECLIB-2163	UserTorqueFeedForward: The function block <i>FB_TorqueFeedForwardConfigured</i> works correctly in case the SLC is on the first Sercos topology address.
OEM00077914 / PLAT-102	TcpUdpCommunication library: If more than one secured (Transport Layer Security) TCP server was active at the same time, a system watchdog could occur due to a higher system load. Therefore, only one instance of a secured (TLS) TCP server was allowed to be active.
–	Hoisting library: Function block <i>GrabControl</i> : Corrected close speed calculation during closing on stack. Calibration status information is kept in the status output even if the function block is disabled. Torque scaling is active even in disabled (cable change) state.

Known Operational Anomalies

Libraries

No known operational anomalies detected for EcoStruxure Machine Expert V1.2.

Software Information

Version Identification

Description	Version
Machine Expert Installer	12.20.01401
Diagnostics	19.0.11.0
Controller Assistant	19.0.11.0
Device Assistant	19.0.11.0
DiffViewer	19.0.11.0
Gateway	19.0.11.0
Launcher	19.0.11.0
OPCServer	3.5.12.83
SoftSPS	3.5.12.80
SVN	4.2.5.0
Logic Builder ⁽¹⁾	1.2
Vijeo-Designer	6.2.9.1008
CoDeSys	V3.5 SP12 Patch8 HF3
SQL Gateway	1.2.0.0
Motion Sizer	4.2.0.0
(1) If using a virtual machine, the download of the online help operates correctly only if the option Accelerate 3D graphics is deactivated in the VM settings.	

New Features for Machine Expert Installer

Machine Expert Installer

- Reduced Machine Expert Installer size.
- Faster installation.

- New improved user interface.
- Online help can be downloaded during standard installation.
- Select installation path.
- Improved offline medium.

New Features EcoStruxure Machine Expert

Motion Design Object

- New graphical interface to parametrize an axis.
- Displays the actual state of the axis.
- Support for M262.

SQL Gateway

- New with secured communication.
- Permitted clients (whitelist for controllers).

Cybersecurity Improvement

- Username and password for the controller mandatory.
- Controller Assistant, Diagnostic, and EcoStruxure Machine Expert extended user rights operations.

NOTE: To help keep your Schneider Electric products secure and protected, it is in your best interest that you implement the cybersecurity best practices as indicated in the *Cybersecurity Best Practices* document provided on the Schneider Electric website.

Code Analysis

- New Metric FBD Halstead Complexity (difficulty, length, max, consistency, average).

Python

- New functions, such as online change memory, user rights management.

New Project Dialog

- Search by controller or by example.

Browse Cross References

The contextual menu of a selected structured variable (`myVar.Elem`) now contains two commands below the **Browse** command:

- **Browse > Cross References** `<myVar.Elem>`: Searches for all usages of the variable instance. (This is the existing command that is also executed by default when selecting a variable when the **Cross Reference** dialog box is open.
- **Browse > Cross References** `<DUT.Elem>`: Searches for all usages of `<DUT.Elem>`, where `Elem` is the subelement of the structured type `DUT` of the variable `myVar`.

New Features for EcoStruxure Machine Expert - Safety

Overview

- **Machine Safety Set** selection in Machine Expert Installer now automatically installs the components needed to program safety-related applications.
- Support for LXM62 Standard Plus Safety drives in PacDrive systems.
- Enhancements performed on the safety-related user guides and the help management. Updated offline safety-related help.
- Diagnostic: Safe logger time stamp harmonization in accordance with IEC format.
- Cybersecurity feature support improved (user management, licensing, IP forwarding). Also refer to the hints below and to the chapter *Cybersecurity Information for User Rights Management*, page 10.
- Quality improvements.

NOTE: To help keep your Schneider Electric products secure and protected, it is in your best interest that you implement the cybersecurity best practices as indicated in the *Cybersecurity Best Practices* document provided on the Schneider Electric website.

Cybersecurity Information for Safety-Related Use Cases

User management activation on standard controllers (non-safety-related controllers) sometimes needs/requests login credentials also for some safety-related use cases.

With the new M262 default setting for IP forwarding (disabled) and the new LMC default setting for firewall management, a connection to the SLC (Safety Logic Controller) can no longer be established without dedicated user interactivity.

To establish a connection to an SLC during a commissioning phase by using the EcoStruxure Machine Expert - Safety programming tool, for example, for application download, the IP forwarding/firewall have to be configured accordingly on the related standard controller. Refer to the PacDrive LMC Eco, PacDrive LMC Pro/Pro2, M262 Programming Guides for further information.

In general, it is a good practice to disable IP forwarding / enable firewall on standard controllers for the machine operation phase.

The *SLCremotelibrary* functions for SLC control are not impacted by the enhanced cybersecurity mechanisms.

Compatibility EcoStruxure Machine Expert

Overview

EcoStruxure Machine Expert V1.2 can be installed in parallel to EcoStruxure Machine Expert V1.1 or V1.1SP1.

EcoStruxure Machine Expert can be installed in parallel to other Schneider Electric software products, such as SoMachine and SoMachine Motion.

For general information on compatibility of EcoStruxure Machine Expert, refer to the Compatibility and Migration Guide (see EcoStruxure Machine Expert Compatibility and Migration, User Guide).

Compatibility EcoStruxure Machine Expert - Safety

Overview

Former SoSafe Programmable versions cannot be started from EcoStruxure Machine Expert environment anymore and can only be installed and used if the related SoMachine Motion version is installed.

However, the former SoSafe Programmable projects - starting from V2.1 - can be imported, re-used, and updated in EcoStruxure Machine Expert - Safety V1.2.

In almost all cases, the update works without impact on the overall safety application and the resulting project CRC (cyclic redundant checksum) value stays the same and there is no recertification needed.

However, EcoStruxure Machine Expert - Safety does not support reusing a project built on EcoStruxure Machine Expert - Safety with LMCx system to EcoStruxure Machine Expert - Safety with M262 system or vice-versa.

Identified Incompatible Project Updates

The CRC of the safety project done before SoSafe Programmable V2.21 is changed if the old project contains the following safety devices:

- TM5SAI4AFS
- TM5STI4ATCFS

In this case, the safety project must be compiled again and downloaded to the TM5CSLCx00FS and the related safety function must be validated and recertified.

It is still possible to install former SoSafe Programmable versions in parallel to EcoStruxure Machine Expert - Safety as long the compatible SoMachine Motion package is available on the PC. Thus, you can maintain old projects using previous compatible engineering tool chains.

Overview of the validated EcoStruxure Machine Expert - Safety version with the appropriate safety-related firmware.

Device	Safety-related firmware version for EcoStruxure Machine Expert - Safety version	
	1.1	1.2
TM5CSLC100FS	2.52	2.52
TM5CSLC200FS	2.52	2.52
TM5SAI4AFS	322	322
TM5SDC1FS	302	302
TM5SDI20DFS	305	305
TM5SDI2DFS	305	305
TM5SDI4DFS	305	305
TM5SDM4DTRFS	305	305
TM5SDM8TBFS	305	305
TM5SDO2DTRFS	300	300
TM5SDO2TAFS	280	280
TM5SDO2TFS	280	280
TM5SDO4TAFS	280	280
TM5SDO4TFS	280	280
TM5SDO6TBFS	295	295
TM5SPS10FS	320	320
TM5STI4ATCFS	322	322
TM7SDI8DFS	305	305
TM7SDM12DTFS	305	305

For a list of safety-related firmware versions for SoSafe Programmable legacy versions, refer to the Release Notes History chapter, page 44.

Mitigated Anomalies

EcoStruxure Machine Expert

ID	Description
OEM00072313 / SI-4994	Project user management: Drag and drop from navigators of one project to another did not follow cut/copy permissions (of the source project).
OEM00078934 / CDSYS-255	Trace: For the case of a pinned cursor, variable values were not displayed correctly (value of the previous time stamp was displayed) when the cursor was dragged from left to right.
OEM00078819 / CDSYS-252	OPC DA server: For a variable that was registered for data-change callbacks but was deactivated the following occurred: In case of writing the variable followed by activating it, the previous written value was sent to the client before sending the present value. (This use case is only possible for some special OPC DA clients.)
OEM00075185	When you attempted to upload a Harmony ZBRN1 DTM running under Modbus TCP IO Scanner , EcoStruxure Machine Expert was no longer operational.
OEM00077196 / HMI-21	Vijeo-Designer: The communication between an M262 controller and the Vijeo-Designer HMI was interrupted after several days.
OEM00070927 / SI-1087 / SI-1088	Depending on the circumstances, when the project was connected to SVN, it was no longer possible to save (autosave included). The message the process cannot access the file...because it is being used by another process appeared.
OEM00078357 / IECLIB-1707	Control_ATV - Drive moved on if controller was in stop.
OEM00078790 / SI-4745	Machine Expert Installer closed unexpectedly during modification of an existing installation. The modification was not completed.
OEM00078543 / CDSYS-247	When searching for an element of the structure, the <code>CrossReferenceList</code> did not search in the complete project.
OEM00079022	When DTM components are installed, Logic Builder prompted for importing the installed DTMs. Sometimes Logic Builder stopped operating during this import procedure.
SI-5043	Exporting an imported cam diagram resulted in an exception from EcoStruxure Machine Expert. The export was canceled.
OEM00078812 / SI-4732	EcoStruxure Machine Expert stopped operating when modifying the IEC structure of a cam diagram in specific projects.
OEM00078386 / SI-4429	Update Device: It is no longer allowed to update an interface device (such as Ethernet Network, Serial Line) or a protocol manager (such as Industrial Ethernet Manager) into a device of another type.
OEM00076949 / MS-1927	Motion Sizer: When exporting a cam diagram into an .asc file, the starting point was missing. It was added to the end of the points table.
OEM00077970 / PLAT-565	OPC UA Configuration editor: When opening a project where this editor had been open before the project was closed, variables from Global Variables Lists (GVL) were not always displayed consistently.
OEM00062678 SI-605	Issue has been solved with the new feature implemented in Machine Expert Installer allowing to select the installation path.

EcoStruxure Machine Expert - Safety

ID	Description
OEM00078219 / SSP50-4519	For TM7SDI8DFS and TM5SDI20DFS It was not possible to map a variable for <i>SafeTwoChannelOkxyy</i> channel from EcoStruxure Machine Expert Logic Builder to EcoStruxure Machine Expert - Safety. If the variable was added in Logic Builder, the Safe Configuration Change window was displayed in EcoStruxure Machine Expert - Safety but the variable was not displayed in the parameter grid after the confirmation.
OEM00074304 / SSP50-4508	Project Compare in EcoStruxure Machine Expert - Safety did not display a message when an attempt was made to compare a safety-related with a non-safety-related project.

ID	Description
OEM00078024 / SSP50-4503	Floating license server configuration that was not fully cleaned up caused a long start time (>30 min) of EcoStruxure Machine Expert - Safety.
OEM00066284 / SSP50-6928	The online help did not provide information about the maximum configurable amount of variables for LMC2SLC or SLC2LMC.

Known Operational Anomalies

EcoStruxure Machine Expert

ID	Description
OEM00069862 / MS-1969	Motion Sizer: While displaying a Crank mechanic with Motion Sizer, the position curve is incorrect (different to EcoStruxure Machine Expert). The label of the curve is also incorrect.
OEM00076614 / MS-1967	Motion Sizer: A cam profile (.asc file) exported from Motion Sizer has one cam point less than the exported file from ECAM.
OEM00070100 / MS-1963	Motion Sizer: With special mechanical parameters and a BMH1903P + LXM32xD85N4 bundle, the maximum required motor speed is 2250 rpm. Motion Sizer indicates the incorrect message that the maximum motor limit has been exceeded.
OEM00079146 / MS-1960	Motion Sizer: Input of a negative mechanic parameter for Crank is not possible.
OEM00078318 / MS-1947	Motion Sizer: ILM140 motor and drive type do not match.
OEM00071717 / MS-1946	Motion Sizer: Not possible to select a minimum supply voltage for ILM.
OEM00078190 / MS-1944	Motion Sizer: Torque characteristics are not updated.
OEM00076612 / MS-1943	Motion Sizer: Incorrect jerk is displayed for motion law mod sin .
OEM00071728 / MS-1938	Motion Sizer: Projects that contain a calculated cycle time that is not an INTEGER value cannot be reopened.
OEM00064125 / MS-1902	Motion Sizer: If only Lexium 62 ILM servo drives are included in a power circuit, the limits of the power supply for the maximum DC bus current and the effective DC bus current are not evaluated.
OEM00064415 / MS-1901	Motion Sizer: Power calculations do not consider the limits from the connection module.
–	Motion Sizer: Incorrect motion profile for motion Dwell when the Y values of the startpoint and endpoint are equal and m and k are not zero.
OEM00077539 / MS-1945	Motion Sizer: After creating a new motor, an error exception was detected.
SI-3117	When a library is only referenced by another library, the referenced library is not updated during a project update. Workaround: Execute the automatic update in the Library Manager .
SI-5150	Machine Expert Installer: After an update from EcoStruxure Machine Expert V1.1 to EcoStruxure Machine Expert V1.2, the ATV320 DTM is displayed as not imported and is not available. Workaround: Remove and reinstall the ATV320 DTM by using the Modify Installed Software option of the Machine Expert Installer.
SI-4893	Motion Sizer: When you open the Help > About dialog box, open the system explorer, select a system project, and click Add current project , then an exception can occur in the Motion Sizer.
OEM00078429 / BOC-558	Relocation Table: The Length of ARRAY variables containing structures with elements of type DATE, TIME, DATE_AND_TIME is not correctly displayed.

EcoStruxure Machine Expert - Safety

ID	Description
OEM00079205 / SSP50-6903	The message logger of an M262 controller can be flooded with a lot of messages in case an optional safety-related module configured in the system becomes defective. Workaround: Consult the message logger and replace the defective module that has been identified.
OEM00078271 / SSP50-4523	The TM5SPS10FS module does not differentiate if the user parameter centralcontrol is set to Central or Direct . In both cases you must set the parameter for the output in addition to the safety-related parameter in the SLC to get the output powered.

Documentation - Mitigated Anomalies

Documentation

ID	Description
OEM00077321 / BOC-264	Event Task: A remark was needed that only internal IEC variables and values of onboard touchprobes and digital inputs (controller) are permitted.
SI-4252	The project update with HMI has been changed, as some HMI devices are not supported by Machine Expert.
IECLIB-2162	HttpHandling library guide: An example was needed on how to send an HTTP <code>Get</code> request using the property <code>State</code> as state variable of the state machine.
OEM00074603 / IECLIB-1713	TcpUdpCommunication library guide: An example was needed on how to implement <code>UDPMulticast</code> with <code>FB Method JoinMulticastGroup</code> in the <code>TcpUdpCommunication</code> library.
OEM00078342 / BOC-316	M262 Programming Guide: Incorrect information for Reset origin command. It removes part of the system logs.
OEM00078593	M262 Hardware Guide: Contained a not accurate graphic: the size of M262 controller was different to TM3 size.
OEM00078594	M262 Hardware Guide: Missing link to the TM5 fieldbus interface Hardware Guide.
OEM00078595	M262 Hardware Guide: Incorrect link for <code>SetRTCDrift</code> documentation.
OEM00078598	M262 Hardware Guide: Incomplete description of Run/Stop sources.
OEM00078607	M262 Hardware Guide: Incorrect links to I/O status LEDs.
OEM00078608	M262 Hardware Guide: No description about LED of SL yellow blink.
OEM00078610	M262 Hardware Guide: Incorrect links for Ethernet 1 and Ethernet 2 ports of <code>TM262M15MESS8T/TM262M25MESS8T/TM262M35MESS8T</code> .
OEM00078629	The memory size of M262 was different between Programming Guide and Hardware Guide.
OEM00078630	M262 Programming Guide: Item 4 was not included in Files Transfers in Memory graphic.
OEM00078691 / BOC-327	Missing note on <code>TMSES4</code> not to interconnect embedded Ethernet port and <code>TMSES4</code> (or interconnect <code>TMSES4</code> module).

Documentation - Known Operational Anomalies

Documentation

ID	Description
OEM00079053 / BOC-351	Incorrect module size of the <code>TM3AQ2/TM3AQ2G</code> in the <i>TM3 Analog I/O Modules Hardware Guide</i> : <ul style="list-style-type: none"> Incorrect: 14.6 mm Correct: 18 mm
TM3BC-556	Incorrect graphic in the section <i>Ethernet Port</i> of the <i>TM3 Bus Coupler Hardware Guide</i> : The orientation of the RJ45 plugs must be reverted.

EcoStruxure Machine Expert V1.2.1

Hardware/Firmware information

Version Identification

Description	Firmware Version
TM3BCCO	1.0.16.1

New Features

TM3 CANopen Bus Coupler is a distributed architecture solution. It allows you to create distributed islands of industrial TM3/TM2 I/O modules managed by a master controller M241, M251, or M262 via CANopen fieldbus.

- Support of TM3 and TM2 I/O modules:
 - up to 14 TM3 I/O modules
 - up to 7 TM2 I/O modules
 - up to 7 TM2 I/O modules mixed with TM3 I/O modules
- Embedded webserver supporting:
 - user rights management
 - bus coupler maintenance such as speed configuration, firmware upgrade, and diagnostics logs
 - island I/O monitoring and control
- Isolated RJ45 ports to support daisy chaining

Limitations

- The latch feature is not supported by TM3DI16, TM3DI16G, TM3DI16K.
- TM3 expert I/O modules are not supported.
- Only a single user can modify the firmware update or write values through the embedded webserver.
- HMISCU is not supported as CANopen Master for TM3BCCO.

Known Operational Anomalies

There are no known anomalies with this release.

EcoStruxure Machine Expert V1.2.2

Hardware/Firmware information

Version Identification

Description	Firmware Version
TM5NS31	2.75

Description	Safety-Related Firmware Version
TM5CSLC100FS	2.53
TM5CSLC200FS	2.53

NOTE: The other firmware versions remain as documented in the Release Notes History, page 83.

Quality Improvement for TM5 Sercos Bus Coupler and TM5 Safety Controllers

- TM5 Sercos Bus coupler (TM5NS31)
 - Cybersecurity: Unused Ethernet services are disabled
- TM5 Safety Controllers (TM5CSLC•00)
 - Cybersecurity: Unused Ethernet services are disabled

NOTE: For updating existing TM5NS31 and TM5CSLC•00 devices in your M262 and PacDrive system use the Device Assistant tool as usual. For more information refer to the M262 Embedded Safety - Integration Guide and the M262 Logic/Motion Controller - Programming Guide.

If you are using in PacDrive systems the Fast Device Replacement (FDR) function, then you have to create a new LMC controller flash card with exchanged firmware files with the Controller Assistant tool. Thereby you have new firmware releases for TM5CSLC•00 and/or TM5NS31 available on the controller to execute the FDR function correctly. For more information refer to the LMC Pro Device Objects and Parameters Guide.

Software Information

Version Identification

Description	Firmware Version
Machine Expert Installer	12.20.08301

New Features for EcoStruxure Machine Expert - Safety

The Safety offline help was updated with small corrections and additional translations.

Mitigated Anomalies - Machine Expert Installer

ID	Description
BOC-628 / SI-5608	Connection to Schneider Electric server is not possible in case default system proxy server with credentials (user and password) is configured.

Known Operational Anomalies - EcoStruxure Machine Expert

ID	Description
SI-5692	<p>Working with DTM device editors can cause an error message “Invalid window handle” occurs and the application crashes. This is caused by a combination of Windows .NET Framework and a custom scale factor in Windows Display settings.</p> <p>Workaround: On a Windows 10 PC go to Display settings and click on Turn off custom scaling and sign out.</p> <p>If this does not solve the issue modify the setting Change the size of text, apps and other items to 100%. Sometimes you have to change the Display resolution to a lower size to reach the goal. Then sign out the user if not done before.</p>

EcoStruxure Machine Expert V1.2.3

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M262	5.0.4.75
TM5NEIP1	3.10

New Features

Quality Improvement for TM5 Ethernet/IP Bus Coupler

- Cybersecurity: Unused Ethernet services are disabled.
- Enable/Disable webserver through Machine Expert configuration.

M262 - OPC UA Client

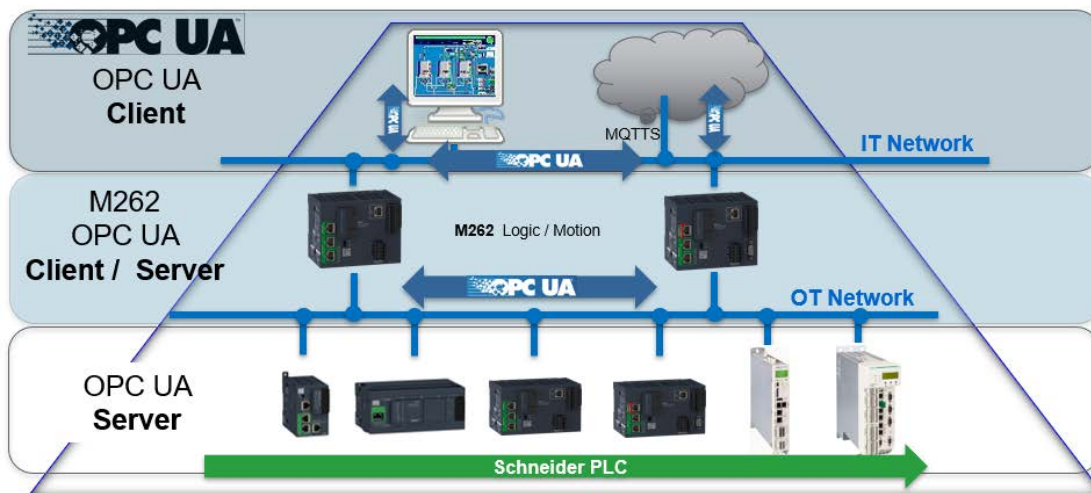
OPC Unified Architecture (OPC UA) is a vendor-independent communication protocol for industrial automation applications.

The client / server OPC UA capability of the following M262 controllers:

- M262L20MESE8T
- M262M25MESS8T
- M262M35MESS8T

The server OPC UA capability of the following M262 controllers:

- M262L10MESE8T
- M262M15MESS8T



OPC UA data exchange is performed using function blocks that are compliant with the PLCopen specification *PLCopen OPC-UA Client for IEC61131-3 version 1.1* and provide the following functions:

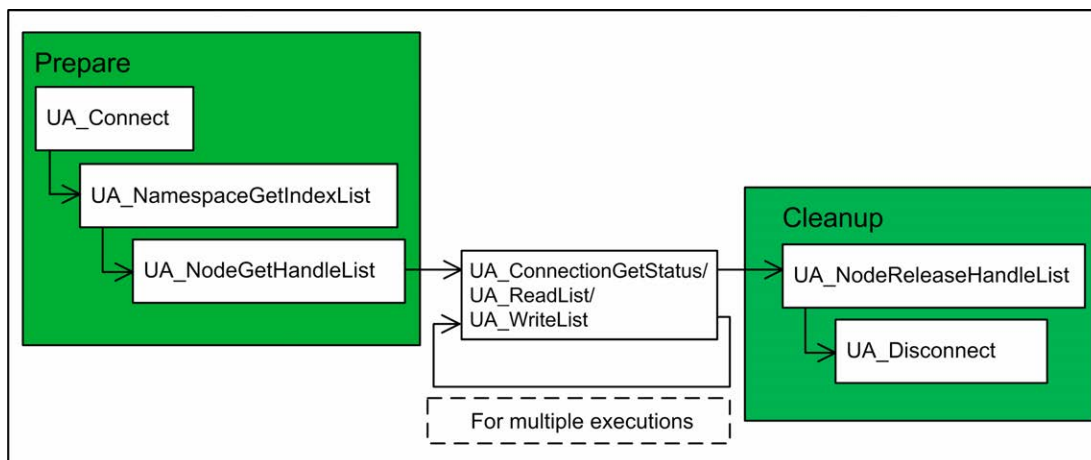
- Read/write of multiple items
- Diagnostics

The following function blocks are supported:

- *UA_Connect*
- *UA_ConnectionGetStatus*
- *UA_Disconnect*
- *UA_NamespaceGetIndexList*
- *UA_NodeGetHandleList*

- UA_NodeGetInformation
- UA_NodeReleaseHandleList
- UA_ReadList
- UA_WriteList

The graphic provides an example for managing the read/write list:



The table lists the OPC UA performance:

Performance	M262
Number of servers supported	5
Number of clients supported	1
Numbers of variables / connections	5,000
Numbers of variables / connections (total)	15,000

Mitigated Anomalies

M262

ID	Description
OEM00077237	User rights: You were asked twice to enter the default administrator credentials at activation.
OEM00079079	NVL did not start when ETH1 was not exchanging data.
M262-4953	M262 incorrectly displayed the error message "Values cannot be retrieved".

Known Operational Anomalies

M262 - Motion

ID	Description
MK-992	The Scaling library is removed. As a result, customer projects including this library (EcoStruxure Machine Expert V1.1) cannot be converted to EcoStruxure Machine Expert V1.1 SP1 or greater without the error message "Unhandled exception has occurred in your application". Workaround: Either do not convert or copy the application content instead of converting it.
MK-974	While enabling a vertical axis, a small drop of the axis can be observed. This results from the gravity effect on the motor load for the time it takes between requesting the enable and finalizing it.

Library Information

Version Identification

Description	Firmware Version
SqlRemoteAccess	2.0.2.0
TeSys island	2.0.3.0
OpcUaHandling	1.0.13.0

New Features

OpcUaHandling

- New library provides the OPC UA client functionality in order to exchange data with other devices through an independent communication protocol using the server - client model for M262.

TeSys island

- Added new function block supporting the new device avatars:
 - SwitchSILStopWCat3and4
- Added new function blocks supporting the new load avatars:
 - MotorOneDirectionSILStopWCat3and4
 - MotorTwoDirectionsSILStopWCat3and4
 - MotorTwoSpeedsSILStopWCat3and4
 - MotorTwoSpeedsTwoDirectionsSILStopWCat3and4
- Added new function blocks supporting the new application avatars:
 - Pump
 - ConveyorOneDirection
 - ConveyorOneDirectionSILStopWCat1and2
 - ConveyorTwoDirections
 - ConveyorTwoDirectionsSILStopWCat1and2
- Added new function blocks to read and set the system time of the bus coupler:
 - SystemTimeGet
 - SystemTimeSet
- Added new outputs supporting the new process variables of the avatars:
 - MotorOneDirection
 - MotorTwoDirections
 - MotorTwoSpeeds
 - MotorTwoSpeedsTwoDirections
 - MotorYDOneDirection
 - MotorYDTwoDirections
- Changes:
 - Changed the order of the function blocks inputs and outputs.
 - Moved the outputs `q_iMotorTemperature` and `q_usiSILGroup` from the dedicated control function blocks to the `EnhancedStatus` function block.
 - Added the output `q_wPredictiveAlarmsStatus` to the `EnhancedStatus` function block.
 - Added the outputs `q_uiVRMSL1L2`, `q_uiVRMSL2L3` and `q_uiVRMSL3L1` to the `SystemVoltageBasic` function block.

- Renamed the term safety into SIL (Safety Integrity Level) on the elements of the library.
- Renamed the term warning in alarm on the elements of the library.
- Renamed the term error in event on the elements of the library.

Project Example

- Added OPC UA client project example for M262.
- Update of the Machine Advisor project example with management of user rights and secure access to the web visualization server.

Mitigated Anomalies

ID	Description
IECLIB-2556	SqlRemoteAccess: Limitation issue after 9999 read or write execution is solved.

Known Operational Anomalies

ID	Description
M262-5106	Changing the cycle time of a task might cause an exception during download of the application using OPC UA.
M262-5092	Downloading large and complex applications may cause an exception during download of the application.
M262-5080	While rebooting, the controller may detect an error if the cycle time of the application is too low.
M262-5072	Using multiple OPC UA clients and a large number of nodes may result in a long execution time and consequently in a watchdog exception.
M262-4248	OPC UA client: <code>UA_ReadList</code> using a pointer in persistent variables may lead to an exception error. An advisory is already present during the build: "Do not use POINTER in persistent variables, since addresses will change at download."

Software Information

Version Identification

Description	Firmware Version
SQL Gateway	1.2.3.0

New Features

SQL Gateway

- It is possible to protect the configuration/user interface from the Gateway via a password.
- Usability improvement for client certificates: The handling of permitted client certificates has been simplified by showing received but rejected certificates. These rejected certificates can be used to simply add them to the permitted certificates.
- Cybersecurity improvements such as encrypted configuration file.

TeSys island DTM

- Update of avatars with process variable inputs and advanced control modes. See also the section [Library Information](#), page 92.
- Added predictive alarms for avatars.
- Upstream voltage detection is improved.

- Custom avatar configurations can be saved for re-use in individual DTM libraries.
- Factory reset allowed in any system state.
- Dynamic port mapping guide added to ease wiring of digital and analog inputs and outputs.
- Support of PTC binary sensor added.
- Predictive alarms data exchange with EcoStruxure Machine Expert added.

Mitigated Anomalies

EcoStruxure Machine Expert

ID	Description
OEM00076873 / SI-5770	During convert from a M241, the ATV320 DTM was deleted.
BOC-741 / SI-5743	Controller Assistant: Writing image to flash disk was unsuccessful with message "Formatting failed".
SI-5741	SQL Gateway: After importing the configuration, the content of permitted clients lists was not updated.
SI-5736	Import of DTMs may render Machine Expert inoperable.
SI-5718	Controller Assistant reports that a version of Machine Expert is already installed on a clean system after program start.
SI-5717 / BOC-395	Calling online help via F1 button is inoperable when using function block name space.
SI-5716 / SI-3684 / SI-5710	Conversion of ATV32 leads to deletion of I/O mapping.
SI-5715	Controller Assistant: Issue on resetting user rights when writing image to M262.
SI-5713	It is not possible to synchronize more than one cam diagram between Motion Sizer and Machine Expert.
SI-5711 / BOC-36	When using the Chinese character set in the Windows operating system, the button inside the user cyclic data configuration is not visible if the screen size is > 100%.
SI-5708	Device Assistant: Incorrect DSM-FW for LXM62+ is displayed.

EcoStruxure Machine Expert - Safety

ID	Description
SSP50-7148 / BOC-763	<p>For new safety projects created with Machine Expert - Safety V1.2, V1.2.1 and V1.2.2, it is not possible to use POUs with structured text (ST) language. Machine Expert - Safety is closed immediately after inserting a POU for ST programming.</p> <p>Workaround: Projects created with these versions and which use ST in a POU have to be recreated with V1.2.3 to avoid this issue.</p> <p>NOTE: Projects upgraded from any version before V1.2 to the mentioned versions are not impacted and can add and use POUs with structured text without re-creation.</p>

Known Operational Anomalies

EcoStruxure Machine Expert

ID	Description
SI-5714 / BOC-467	CamEditor: Editor view allows to configure an invalid value for the "C" parameter for motion profile ModAccTr or ModSin.

EcoStruxure Machine Expert V1.2.4

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M262	5.0.4.81
TM3BCEIP	2.1.50.2
TM3BCSL	2.0.50.2
TM3BCCO	2.0.50.2
TM3DI8	2.0
TM3DI8G	2.0
TM3DI32K	2.0
TM3DM8R	2.0
TM3DM8RG	2.0
TM3DM24R	2.0
TM3DM24RG	2.0

New Features

Lexium LXM28S

The device LXM28S is available in the **Hardware** catalog. It can be used to control the drive LXM28S.

Modicon TM3 Bus Coupler

- TM3 CANopen Bus Coupler (TM3BCCO) is supported by Harmony SCU HMI Controller.
- Support for the new Modicon TM3 I/O modules with the filter and fallback function:
 - TM3DI8
 - TM3DI8G
 - TM3DI32K
 - TM3DM8R
 - TM3DM8RG
 - TM3DM24R
 - TM3DM24RG

Modicon TM3 Standard I/O

New hardware revisions for TM3DI8, TM3DI8G, TM3DI32K, TM3DM8R, TM3DM8RG, TM3DM24R and TM3DM24RG.

NOTE: The new features are available only with the new firmware provided with EcoStruxure Machine Expert V1.2.4.

These new TM3 I/O modules are supported by M241, M251, M262 and TM3 Bus Couplers, and support new features:

- Configurable input filter
 - The input acquisition time filter can be adjusted to allow fast input signals (0.3 - 12 msec.).
- Input latch function
 - The input latch function allows to capture input signals with short durations and memorize the state till the next controller task execution.
 - This feature is not supported by the TM3 Bus Couplers.

- Output fallback function
 - The output of the TM3 I/O modules will apply fallback values configured by user after an elapsed delay, when the I/O bus is lost.
- Firmware upgrade
 - The firmware of the TM3 I/O modules can be updated by the controller. (New features only configurable with modules of software version 2 or greater.)

M262 - Motion

- Cam slave start mode Absolute
 - Mode Absolute is now available, which can be chosen as an alternative to the already existing slave start modes Relative and RampIn when starting a cam.
 - Mode Absolute starts the new cam directly at the position, velocity and acceleration according to the new cam profile (like Relative/unlike RampIn) and without performing any ramp-in movement (unlike RampIn).
 - Mode Absolute cannot be started on a slave axis configured to modulo. This will result in the error output of MC_CamIn function block being set.
- Interpolated cam (straight/poly5)
 - As an alternative to using segment-defined cam profiles, a cam profile can now also be interpolated between a list of points.
 - Up to 10,000 points are supported. In the case of straight interpolation, these points are Y coordinates, which are equidistant on the X axis. Interpolation between two points is straight (same as straight cam segment law).
 - Alternatively, a 5th degree polynomial interpolation can be used between the given points. In this case, the user also has to input slope and curvature in addition to the corresponding slave position.
- Real-time Task
 - The real-time task is a task for the user application that synchronized with the fieldbus and the internal motion calculation. This task will be scheduled to be executed after motion calculation and data transfer from/to devices. Please ensure that this task is executed immediately by setting its priority to the highest priority (lowest number) in your application.
 - The intended use case is to read inputs or axes positions as soon as they are available, create branch logic based on them, trace, etc.
 - Be aware that it is not intended for Motion function blocks.
 - Be aware that digital outputs set in this task will only be sent to the device after 2 cycles.

Documentation

The online help is updated with the following new documentation:

- [How to Configure the Firewall for PacDrive LMC Controllers](#)

Mitigated Anomalies

M262

ID	Description
M262-5074	WebVisualization: Credential page is reloading on an Apple iPad. Allow Apple iPad for WebVisualization.
M262-5218	OPC UA server is able to read the M580 certificate.
M262-5230	OPC UA server: The display name of variables has been modified in order to provide a "Flat" view of the array's structure. The view is modified to show the complete node name of the variable.
M262-5233	M262: The LED is aligned with the state of the output when the default value is requested.

M262 - Motion

ID	Description
MK-939	An unnecessary ramp-in movement no longer occurs, when an <code>MC_CamIn</code> function block is executed with slave start mode <code>RampIn</code> but no ramp-in movement is necessary because the axis already starts in the correct position according to the cam profile definition.
MK-967	Discrete motion jobs no longer finish with the final axis position merely very close to the commanded target position (e.g. 10^{-32} instead of 0.0), but instead with the axis exactly in the target position.
MK-975	Resolved an issue whereas Sercos on M262 Logic controller stops working and the drive displays error B103, or that on a subsequent attempt M262 Logic controller crashes, when executing any Motion Control FB in buffered mode while it is already active.
MK-1005	An unnecessary ramp-in movement, leading to a jump in axis velocity, no longer occurs when an <code>MC_CamIn</code> function block is executed with slave start mode <code>RampIn</code> and buffer mode <code>Aborting</code> , with identically parameterized cam profile as the previously running cam. Linked to MK-939.
MK-1017	A very high velocity and acceleration of the drive shortly before reaching the target, caused by a sudden jump in axis position for one cycle, no longer occurs after <code>MC_MoveAbsolute</code> function block with jerk has been used to abort itself with a new target position further away.
MK-1021	Configuring the axis with a position resolution of 1.0 no longer leads to an unexpected sudden jump from zero velocity to target velocity. Instead the axis now accelerates with the defined ramp, as expected.
MK-1033	The value of an axis <code>stMotionOfMaster.lrPosition</code> is no longer set to zero for one cycle when the active cam is changed (buffered or aborted) and the new cam is started with slave start mode <code>RampIn</code> . Instead, this property now shows the expected value.

Known Operational Anomalies

M262

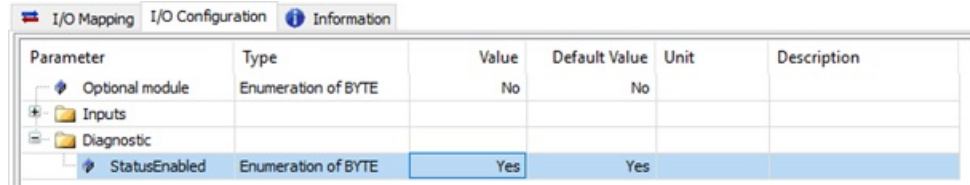
ID	Description
BOC-537	Sercos bus: Unable to disable/enable the TM5 slices of Sercos III via IEC program with the M262 Logic Controller.
BOC-751	Modbus serial: Serial IO scanner sends FC15 while FC05 is configured.
M262-5137	<code>SysTimeRtcSet</code> : After a power OFF the real time clock (RTC) of the controller get lost if it is set by the <code>SysTimeRtcSet</code> function. Workaround: Set the real time clock by the software.

M262 - Motion

ID	Description
MK-1016	Online status of bit <code>InvertDirection</code> is not displayed in the encoder configuration window. The pre-configured value is shown instead.
MK-1048	SLC remote controller shows phase -1 when trying to set Sercos phase to 0 and it shows phase 0 when trying to set Sercos phase to -1.
MK-1073	Real-time task configuration - Watchdog precision cannot be set to microseconds.

Modicon TM3 Bus Coupler

ID	Description
M262-5335	When in a distributed architecture, with TM3BCEIP, if the diagnostic for the analog modules TM3AQ2 and TM3AQ4 is disabled, CPU exception occur , after the download of the application. Workaround: The diagnostic is activated by default - do not change the diagnostic setting for these both modules: TM3AQ2 and TM3AQ4.
-	Always use the value Yes for the variable StatusEnabled in the analog modules, see screenshot below. When it is set to No the values of the analog inputs will make a shift in the read data buffer, causing wrong data value read in the software or controller.



Library Information

Version Identification

Description	Version
CommonMotionInterface	1.4.1.0
CommonToolbox	1.0.1.0
Mathematics	1.0.0.0
PD_PacDriveLib	1.9.4.0

New Features

Project Example

Update of the Safety Logic Controller (SLC) project template for PacDrive 3 to allow connection between EcoStruxure Machine Expert - Safety and TM5CSLC•00FS.

CommonToolbox

The new library provides a collection of additional functions and function blocks:

- **FC_CloseSlcCommunication**: Deactivates the standard port rules for the controller firmware which allow a connection from the programming tool to the TM5CSLC•00FS through the controller.
- **FC_LrealToString**: The function converts any numerical value to a STRING with freely defined format.
- **FC_MultiConcat**: The function concatenates the 4 input strings according to their sequence.
- **FC_OpenSlcCommunication**: Activates the required port rules for the controller firmware to allow a connection from the programming tool to the TM5CSLC•00FS through the controller.
- **FB_HeatingControl**: Function block for monitoring and controlling heating systems.
- **FB_RandomGenerator**: This function creates a random number.
- **FB_RuntimeMeasurement**: Runtime measurement of program code.

Mathematics

- **ST_Vector3D**: Represents a Cartesian vector in a three-dimensional space.

Mitigated Anomalies

There are no additional mitigated anomalies with this release.

Known Operational Anomalies

NOTE: If you are using templates and examples which are not updated with the update of EcoStruxure Machine Expert V1.2.4, you may be presented the **Update Project** dialog. If you are opening an example or template for the first time, you should update to have the correct and corresponding libraries and other necessary support.

Software Information

Version Identification

DTMs

Description	Version
Advantys OTB	11.1.0.0
ATV320	1.2.6.0
ATV340	1.7.0.0
ATV6xx	2.5.1.0
ATV9xx	2.2.1.0
Harmony XB5R	1.0.41
Lexium 28 A	1.6.00.07
Lexium 28 S	1.6.12.00
Lexium 32 A	1.20.02.01
Lexium 32 C	1.20.02.01
Lexium 32 i	1.20.02.01
Lexium 32 M-S	1.20.02.01
Modbus Serial Communication DTM	2.6.12
Modbus TCP Communication DTM	2.6.12
TeSys island	2.2.1.0
TeSysT	2.12.0.0
TeSysU	2.8.0.0
TM5-7 CANopen Interface DTM	1.1.8
TM5-7 Expansion Module DTM	1.1.8

New Features

Quality improvement for Lexium 32 DTM

- Cybersecurity: No UMAS transfer for MotionSequenceMode download.

EcoStruxure Machine Expert - Safety

- Safety System communication management improvement. New standard controller firmware handling functions available. For details see chapter Library Information, page 98.

Mitigated Anomalies

DTMs

ID	Description
LXM32DTM-4	Resolution of the issue with the downloading of an old SoMove file into a new LXM32 drive.
190220	TeSys island: Could not select 22 kW power rating from combo box.

Known Operational Anomalies

There are no additional known anomalies with this release.

EcoStruxure Machine Expert V1.2.5

Hardware/Firmware Information

Version Identification

Description	Firmware Version
TM258LD42DT	5.0.4.11
TM258LD42DT4L	5.0.4.11
TM258LF42DT	5.0.4.11
TM258LF42DT4L	5.0.4.11
TM258LF66DT4L	5.0.4.11
TM258LF42DR	5.0.4.11
LMC058LF42	5.0.4.11
LMC058LF424	5.0.4.11

New Features

Modicon M258 Logic Controllers and Modicon LMC058 Motion Controllers

- Support of Codesys 3.5 SP12
- Migration of a project from SoMachine V4.3 to Machine Expert V1.2.5 (with the limitation of devices in Machine Expert)
- User Right password has to be changed at first login to the controller
- Default administrator password change on first login

Mitigated Anomalies

ID	Description
PLAT-718	M258: High Speed Counter (HSC) in Period Meter Mode with resolution = 0.1 μ s is available.
PLAT-730	M258: Function blocks with the input of type ANY are not generating an internal error anymore.
PLAT-901	M258: Size of Union variables is correctly sized when variables are mapped to a Relocation Table .
BOC-319 / PEP0533758R	Documentation: Maximum frequency of Expert I/O is 200 kHz instead of 100 kHz.
BOC-507 / CDSYS-191 / PLAT-879	LMC058: The Modicon LMC058 Motion controller was stopped during an online change with some projects.
BOC-512 / CDSYS-55 / PLAT-879	M258: We triggered an issue if <code>MC_GearIn.RaionNumerator = 0</code> was used and during this state <code>MC_SetPosition</code> on the Master drive was executed.
BOC-514 / CDSYS-40	LMC058: <code>SMC_Limitdynamics</code> did not limit Z-axis with some G-code files.

ID	Description
BOC-515 / CDSYS-34	LMC058: There was a jump in position on quick stop.
BOC-517 / CDSYS-14	LMC058: <code>SMC_Limitdynamics</code> did not limit the acceleration and deceleration values in some G-code files.
BOC-518 / CDSYS-11	LMC058: Using M-functions inside a G-code file the interpolator output containing the M-function number showed sometimes incorrect values (65533 and 65534).
BOC-519 / CDSYS-8	LMC058: If <code>SMC_Interpolator2Dir</code> was started (set <code>bExecute=TRUE</code>), then the output "busy" of this function block remains FALSE (but should become TRUE).
BOC-520 / CDSYS-6	LMC058: <code>SMC_BlockSearch</code> to restart a aborted CNC G-code file from a specific point did not start correctly in certain situations.
BOC-521 / CDSYS-17 / PLAT-879	LMC058: In a special case of G-code, the ToolCorrection did not work correctly (there occurs a jump on the path and target position was not correct).
BOC-557 / SI-5735	LMC058: Input parameter from <code>MC_GearIn</code> was too small and is changed to DINT and UDINT.
BOC-588 / CDSYS-364	LMC058: CNC decoder did not detect syntax error.
BOC-590 / CDSYS-366	LMC058: <code>MC_GearInpos</code> did not behave correctly when changing the ratio in negative direction. If the ratio was changed from -1/1 to -1/2 then a full turn in opposite direction was executed.
BOC-592 / CDSYS-367	LMC058: When the master was in standstill, <code>MC_GearIn</code> was started correctly, but if then <code>MC_GearOut</code> was started, axis reported an error "Axis not ready for motion".
BOC-594 / CDSYS-368	LMC058: When velocity ramp type of slave axis was set to Quadratic and the <code>MC_GearIn</code> was executed with <code>Jerk=0</code> (FB input), then the controller stopped with exception.
BOC-597 / CDSYS-370	LMC058: If tappets are defined in a CAM, the CAM application needs about 3 times more CPU power (measured in MotionTask) than the same application without tappets in the CAM. Additionally, when CAM tappets are configured, the <code>MC_CamIn</code> was demonstrating an incorrect behavior after one running CAM cycle.
BOC-599 / CDSYS-371	LMC058: In a LMC058 CNC application, the reset of H-functions by programming "H-2 L-10" did not work.
BOC-913 / PLAT-1090	TM2/TM3: When using a TM2 analog module, it was not possible to edit the minimum/maximum of the scope.
CVE-2019-13532	Security update for CODESYS V3 web server
CVE-2019-13548	Security update for CODESYS V3 web server

Known Operational Anomalies

ID	Description
PLAT-943	LMC058/M258: When migrating a project from SoMachine V4.3 to Machine Expert V1.2.5, default value of input/outputs of TM5 are lost. Default value must be re-affected.
PLAT-958	M258: Embedded, local and remote TM5 on M258/LMC058 cannot be directly duplicated on a TM5 bus coupler.
PLAT-1007	M258: In simulation mode, the icon of Can0 and Can1 is green instead of red. No CAN traffic will be generated.
PLAT-1025	M258: In case of converting a controller application from M258 to M241, the WebVisualization protocol option is reset. Verify the option in your converted application.
PLAT-1089	LMC058/M258: In case of an upgrade from a firmware version older than 4.0.3.6 or 2.0.31.40 having "option bit(s)" activated, the migration to this newer version will deactivate them.

ID	Description
PLAT-1194	LMC058/M258: When using LMC058**S0 (legacy hardware version of LMC058), downloading the application via USB key is not functional. Using Machine Expert solves this anomaly.
PLAT-1217	LMC058/M258: After changing the alarm output configuration and downloading the new configuration, perform a reset warm to ensure the alarm output is correctly set.
PLAT-1229	LMC058/M258: When deleting CAN motion configuration from CAN1 when CAN0 is also configured may lead to spurious error on CAN0 when generating code. Perform a Clean all in order to remove these spurious errors.
PLAT-1257	<p>LXM28A: When homing is interrupted by limit switch, LXM28A drive state does not change to error stop.</p> <p>Workarounds to clear error AL015:</p> <ul style="list-style-type: none"> Execute P0-01 (CANopen object 4001h) by CANopen communication. Execute reset command on SoMove or on board HMI. Execute MC_ReinitDrive (error AL015 still reports), then execute MC_Reset. Reset LMC058 controller (error changes to AL3E1), then execute MC_Reset (AL3E1 is cleared), then execute MC_Enable (error AL015 is reported again), then execute MC_Reset.
PLAT-1259	<p>LXM28A: Executing MC_Touchprobe will automatically set trigger edge to rising edge.</p> <p>Workaround: Reconfigure the touch probe signal in the drive after executing the FB (setting execute to TRUE): P5-39 (16#4527).</p>
SI-6608	<p>LMC058/M258: The SoftMotion version is not automatically updated after an project update from SoMachine to Machine Expert. This leads to missing libraries in some project.</p> <p>Workaround: The SoftMotion version has to be set manually in the Project Settings > SoftMotion.</p>

Library Information

Version Identification

Description	Version
LMC058 Expert IO	1.0.2.3
LMC058 Motion	1.0.2.1
LMC058 PLCSystem	1.0.3.6
M258 Expert IO	1.0.2.3
M258 PLCSystem	1.0.3.6
FtpRemoteFileHandling	1.3.3.0

Mitigated Anomalies

There are no additional mitigated anomalies with this release.

Known Operational Anomalies

ID	Description
IECLIB-2909	FtpRemoteFileHandling: On LMC058 and M258 the LIST command for servers which sends the data in several frames sometimes does not work correctly if the FB_FtbClient was previously connected to another FTP server.

NOTE: If you are using templates and examples which are not updated with the update of EcoStruxure Machine Expert V1.2.5, you may be presented the **Update Project** dialog. If you are opening an example or template for the first time, you should update to have the correct and corresponding libraries and other necessary support.

Software Information

Version Identification

Description	Version
Controller Assistant	19.2.3.0

New Features

Documentation

The online help is updated with the documentation for:

- SoftMotion (the included chapter for Robotics is not valid as EcoStruxure Machine Expert V1.2.5 do not support this feature)
- Modicon LMC058 Motion Controller
- Modicon M258 Logic Controller

Mitigated Anomalies

ID	Description
CVE-2020-11896	Treck IP stack (Ripple 20)
CVE-2020-11898	Treck IP stack (Ripple 20)
CVE-2020-7520	URL redirection to untrusted site
CVE-2020-7523	Modbus serial driver
BOC-310	Documentation: CTS Inversion was described with "Insert CTS (Clear To Send) level" and is corrected with "Invert CTS (Clear To Send) level" in the TM5 Programming Guide.
BOC-311	TM5 Strain Gauge IoDrvTM5SEAISG Library Guide: In the Related Documents table the incorrect part numbers of the TM5 Programming Guide are corrected.
PLAT-704	Translation of the module TM5SDM12DT description is corrected: 8DO 4DO (incorrect) -> 8DI 4DO (correct)
BOC-326 / HMI-45	Documentation: Legacy information about ModbusTCP Slave was visible in the help.
BOC-488 / SI-6501 / SI-5766	TcpUdpCommunication.library was generating spurious compiler warnings.
BOC-586 / CDSYS-362	Online change was triggered after reopen of a project with G-code.
BOC-638 / SI-6365 / SI-5565	Sporadically it was not possible to create an image from the Project menu (Build > Create image...)
BOC-732 / SI-6364 / SI-6597	The retain file was deleted with a compatible update of the LMC image in the controller assistant.
BOC-772 / SI-5809	The Customize menu was deleted with a Logic Builder update or reinstallation.
BOC-777 / SI-6345 / SI-5803	The Controller Assistant is sometimes not able to format the CF card of a PacDrive M controller (Win10).
BOC-782 / SI-5847	Documentation: There was a translation error for QUERYINTERFACE in the Machine Expert Programming Guide.
BOC-799 / SI-6361 / SI-5884	Sometimes the Device tree was deleted after an convert from TM241CE40T to TM251MESE.

ID	Description
BOC-873 / SI-6354 / SI-5944	Machine Expert was losing user-defined repository path information on closing.
BOC-854 / PLAT-981	A call from the method <code>generate_code</code> which has no arguments was generating an error.
BOC-888 / SI-6353 / SI-6106	The Project update dialog was updating the device version unnecessarily.
BOC-902 / ROB-111	Documentation: RoboticAutoTune library help was not included with the application libraries.
BOC-936 / PLAT-1107	The connection path from some EthernetIP.eds files was marked as invalid.
BOC-1029 / IECLIB-2905	Documentation: The variable from the SmartInfeed product generation simulation was <code>xProductLenghtVariance</code> instead of <code>xProductLengthVariation</code> in the Online Help.
SI-6031	Documentation: The firmware function <code>FC_MAreaCommunicationServiceEnable</code> was not documented.
SI-6248	Documentation: The error message 8342 "On/OffPos inverted (On/OffDelay ok?)" was not listed in the online help.

Known Operational Anomalies

ID	Description
BOC-861 / SI-5984	ApplicationLogger: The text size of the Applicationlogger filter is not sufficient to read the complete text.
BOC-945 / SI-6329	Trace editor buffer size for Device Trace cannot be changed. Trace recording time limited to 01h 11min.
BOC-946 / IECLIB-2840	Using the SmartInfeed outside PacDrive templates and using functions/methods from the <code>IF_Infeed</code> results in a PageFault if AutoRunning is not active, respectively the <code>FB_Infeed</code> is not in the state "Working".
BOC-971 / SI-6376	Smpb file is proposed as supported file, but when opening such a file an error occurs.
BOC-980 / CDSYS-529	Generate code leads to an AssertionFailed exception in some projects using function blocks which use arrays with a variable size.
BOC-982 / IECLIB-2873	Exception 8105 - Encoder Signal out of Range does not reset the flag HomeOk for an axis in the template.
BOC-992 / CDSYS-527	Array online monitoring range does not work properly and allow more than 1000 REFERENCE TO ARRAY elements for online monitoring.
BOC-1000 / SI-6472	The communication parameters of a Profinet device are not displayed correct in the PDI file.
BOC-1002 / SI-6473	Converted an LMC Pro to an LMC Eco, the PLC Settings were changed unintentionally.
BOC-1003 / SI-6474	No messages are shown about changed library version after converting a controller.
BOC-1017 / SI-6542	Device addressing in the popup menu points an incorrect PacDrive controller.
BOC-1072 / CDSYS-552	Smart coding does not work on alias from a library of type ARRAY OF STRUCTURE.
SI-5988	No information at start up when the new installed version/addon contains new Device Type Managers (DTMs).
SI-6029	When using the function Save As Function Template a negative value for a numeric parameter is not possible. The minus is not considered as part of the value.
SI-6125	When using the command Show update dialog it is always shown, that an upgrade for the project version is needed.
SI-6483	Performance issue in CompileMessage convention with some big projects.
SI-6443	Generic Ethernet/IP object is available for PacDrive, but it does not work.
PLAT-991	Reopening a just saved project may lead to non real build errors on serial line. Perform a Clean all in order to remove these spurious errors.

EcoStruxure Machine Expert V1.2.6

Hardware/Firmware Information

Version Identification

Description	Firmware Version
M262	5.0.4.83

Modicon M262 Motion Controller

The Modicon M262 Motion Controller supports the Robotic library. For details see the section Library Information, page 106.

OPC UA Client

NOTE: The OPC UA Client is usable only if the OPC UA Server is enabled. For that, open in Machine Expert the **MyController** window, then **OPC UA Server Configuration > General settings** and select **OPC UA Server** enabled.

Mitigated Anomalies

M262 Motion

ID	Description
MK-1106	Axis jumped on MC_CamIn - rampin - positive or negative direction.

Known Operational Anomalies

M262 Motion

ID	Description
MK-1118	Robotic - Variables of ARRAY OF PDL.ST_Vector3D marked as undefined.
MK-1109	MC_MoveAbsolute - with modulo axis and small ramps.
MK-1097	Negative velocity MC_MoveAdditive.

Library Information

Version Identification

Description	Version
FileFormatUtility	1.4.15.0
FtpRemoteFileHandling	1.3.6.0
Robotic (PacDrive)	2.16.0.0
Robotic (M262)	3.0.3.0
RoboticModule	2.12.0.0
SchneiderElectricRobotics	2.10.0.0
SchneiderElectricRobotics Parameters	2.13.0.0
SchneiderElectricRobotics Toolbox	1.5.0.0
RoboticsAutoTune	2.0.0.0

New Features

FileFormatUtility

Added new function block `FB_JsonUtilities` supporting the parsing of JSON formatted data.

Robotic

For limitations with M262 refer to the *Robotic Library Guide*.

Mitigated Anomalies

ID	Description
BOC-1122 / IECLIB-3436	FtpRemoteFileHandling required TcpUdpCommunication library V2.0.17.0 which was not available.

Known Operational Anomalies

ID	Description
IECLIB-3417	FileFormatUtility: Precompiler error C0358 occurs if an ENUM <code>ET_JsonValueType</code> is been used for verifying "Type of Selected" property.
BOC-1107 / IECLIB-3420	<code>MC_Power</code> timeout is insufficient when used with an LXM32M with 3rd party motor.
BOC-1117 / IECLIB-3437	The function block <code>MC_Power</code> does not enable the power stage in combination with Lexium_IL*2 drives.
BOC-1118 / IECLIB-3438	Motion Control Library Guide: It is not clearly described which stop ramp is used by the function block <code>MC_Stop</code> .
BOC-1119 / IECLIB-3440	CrankModule Library: The crank module warm start can be executed before the transformation is active.
BOC-1120 / IECLIB-3439	<code>MC_ReadAxisInfo</code> : The outputs <code>LimitSwitchPos</code> and <code>LimitSwitchNeg</code> are not correct when Safe Torque Off (STO) inputs are FALSE.
BOC-1123 / ROB-124	In case of an emergency stop (E-Stop) the use of the variable <code>rstRefOrientationTCP</code> inside of <code>FB_AdditionalTransformationTCP</code> triggers a watchdog.

NOTE: If you are using templates and examples which are not updated with the update of EcoStruxure Machine Expert V1.2.6, you may be presented the **Update Project** dialog. If you are opening an example or template for the first time, you should update to have the correct and corresponding libraries and other necessary support.

Software Information

Mitigated Anomalies

There are no additional mitigated anomalies with this release.

Known Operational Anomalies

ID	Description
BOC-1086 / SI-5669	The functionality of Add function from Template does not take over the used IP address from the template to the device.
BOC-1089	The PreCompiler creates an error if a project with M262M controller is used where the <code>ARRAY OF PLCO.MC_CAM_ID</code> is used in the code.
BOC-1100 / CDS-64615	An application with two function blocks <code>FB_1</code> and <code>FB_2</code> where <code>FB_1</code> has two methods that it provides to <code>FB_2</code> . A call of <code>FB_2</code> generates the advisory message C0298 "Calculation of stack usage incomplete because of recursive calls: <code>SR_Main () -> FB_2 () -> FB_1.METH_1 () -> FB_1.METH_2 () -> FB_1.METH_2 ()</code> ".

ID	Description
BOC-1103 / PLAT-1278	The Download App macro does not contain the command to download the WebVisualization files.
BOC-1109 / SI- 4922	Activation of Code Analysis trial is unsuccessful.

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