Altivar Process ATV600
Variable Speed Drives for Asynchronous and Synchronous Motors
POWERLINK Manual - VW3A3619

09/2018
The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein. If you have any suggestions for improvements or amendments or have found errors in this publication, please notify us.

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All pertinent state, regional, and local safety regulations must be observed when installing and using this product. For reasons of safety and to help ensure compliance with documented system data, only the manufacturer should perform repairs to components.

When devices are used for applications with technical safety requirements, the relevant instructions must be followed.

Failure to use Schneider Electric software or approved software with our hardware products may result in injury, harm, or improper operating results.

Failure to observe this information can result in injury or equipment damage.

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Safety Information

Important Information

NOTICE

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, service, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.

⚠️ The addition of this symbol to a “Danger” or “Warning” safety label indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed.

⚠️ This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

⚠️ DANGER

DANGER indicates a hazardous situation which, if not avoided, will result in death or serious injury.

⚠️ WARNING

WARNING indicates a hazardous situation which, if not avoided, could result in death or serious injury.

⚠️ CAUTION

CAUTION indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.

⚠️ NOTICE

NOTICE is used to address practices not related to physical injury.

PLEASE NOTE

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

Qualification Of Personnel

Only appropriately trained persons who are familiar with and understand the contents of this manual and all other pertinent product documentation are authorized to work on and with this product. In addition, these persons must have received safety training to recognize and avoid hazards involved. These persons must have sufficient technical training, knowledge and experience and be able to foresee and detect potential hazards that may be caused by using the product, by changing the settings and by the mechanical, electrical and electronic equipment of the entire system in which the product is used. All persons working on and with the product must be fully familiar with all applicable standards, directives, and accident prevention regulations when performing such work.
### Intended Use

This product is a drive for three-phase synchronous, asynchronous motors and intended for industrial use according to this manual. This product is a safety module, which supports various device safety functions and intended for industrial use according to this manual. The product may only be used in compliance with all applicable safety standard and local regulations and directives, the specified requirements and the technical data. The product must be installed outside the hazardous ATEX zone. Prior to using the product, you must perform a risk assessment in view of the planned application. Based on the results, the appropriate safety measures must be implemented. Since the product is used as a component in an entire system, you must ensure the safety of persons by means of the design of this entire system (for example, machine design). Any use other than the use explicitly permitted is prohibited and can result in hazards.

### Product Related Information

Read and understand these instructions before performing any procedure with this drive.

#### DANGER

**HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH**

- Only appropriately trained persons who are familiar with and understand the contents of this manual and all other pertinent product documentation and who have received safety training to recognize and avoid hazards involved are authorized to work on and with this drive system. Installation, adjustment, repair and maintenance must be performed by qualified personnel.
- The system integrator is responsible for compliance with all local and national electrical code requirements as well as all other applicable regulations with respect to grounding of all equipment.
- Many components of the product, including the printed circuit boards, operate with mains voltage.
- Only use properly rated, electrically insulated tools and measuring equipment.
- Do not touch unshielded components or terminals with voltage present.
- Motors can generate voltage when the shaft is rotated. Prior to performing any type of work on the drive system, block the motor shaft to prevent rotation.
- AC voltage can couple voltage to unused conductors in the motor cable. Insulate both ends of unused conductors of the motor cable.
- Do not short across the DC bus terminals or the DC bus capacitors or the braking resistor terminals.
- Before performing work on the drive system:
  - Disconnect all power, including external control power that may be present. Take into account that the circuit breaker or main switch does not de-energize all circuits.
  - Place a **Do Not Turn On** label on all power switches related to the drive system.
  - Lock all power switches in the open position.
  - Wait 15 minutes to allow the DC bus capacitors to discharge.
  - Follow the instructions given in the chapter "Verifying the Absence of Voltage" in the installation manual of the product.
- Before applying voltage to the drive system:
  - Verify that the work has been completed and that the entire installation cannot cause hazards.
  - If the mains input terminals and the motor output terminals have been grounded and short-circuited, remove the ground and the short circuits on the mains input terminals and the motor output terminals.
  - Verify proper grounding of all equipment.
  - Verify that all protective equipment such as covers, doors, grids is installed and/or closed.

Failure to follow these instructions will result in death or serious injury.

Drive systems may perform unexpected movements because of incorrect wiring, incorrect settings, incorrect data or other errors.

#### WARNING

**UNANTICIPATED EQUIPMENT OPERATION**

- Carefully install the wiring in accordance with the EMC requirements.
- Do not operate the product with unknown or unsuitable settings or data.
- Perform a comprehensive commissioning test.

Failure to follow these instructions can result in death, serious injury, or equipment damage.
Damaged products or accessories may cause electric shock or unanticipated equipment operation.

⚠️ ⚠️ DANGER

ELECTRIC SHOCK OR UNANTICIPATED EQUIPMENT OPERATION

Do not use damaged products or accessories.

Failure to follow these instructions will result in death or serious injury.

Contact your local Schneider Electric sales office if you detect any damage whatsoever.

⚠️ ⚠️ WARNING

LOSS OF CONTROL

- The designer of any control scheme must consider the potential failure modes of control paths and, for critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop, overtravel stop, power outage and restart.
- Separate or redundant control paths must be provided for critical control functions.
- System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link.
- Observe all accident prevention regulations and local safety guidelines (1).
- Each implementation of the product must be individually and thoroughly tested for proper operation before being placed into service.

Failure to follow these instructions can result in death, serious injury, or equipment damage.


NOTICE

DESTRUCTION DUE TO INCORRECT MAINS VOLTAGE

Before switching on and configuring the product, verify that it is approved for the mains voltage.

Failure to follow these instructions can result in equipment damage.

The temperature of the products described in this manual may exceed 80 °C (176 °F) during operation.

⚠️ ⚠️ WARNING

HOT SURFACES

- Ensure that any contact with hot surfaces is avoided.
- Do not allow flammable or heat-sensitive parts in the immediate vicinity of hot surfaces.
- Verify that the product has sufficiently cooled down before handling it.
- Verify that the heat dissipation is sufficient by performing a test run under maximum load conditions.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

This equipment has been designed to operate outside of any hazardous location. Only install this equipment in zones known to be free of a hazardous atmosphere.

⚠️ ⚠️ DANGER

POTENTIAL FOR EXPLOSION

Install and use this equipment in non-hazardous locations only.

Failure to follow these instructions will result in death or serious injury.
Machines, controllers, and related equipment are usually integrated into networks. Unauthorized persons and malware may gain access to the machine as well as to other devices on the network/fieldbus of the machine and connected networks via insufficiently secure access to software and networks.

**WARNING**

**UNAUTHORIZED ACCESS TO THE MACHINE VIA SOFTWARE AND NETWORKS**

- In your hazard and risk analysis, consider all hazards that result from access to and operation on the network/fieldbus and develop an appropriate cyber security concept.
- Verify that the hardware infrastructure and the software infrastructure into which the machine is integrated as well as all organizational measures and rules covering access to this infrastructure consider the results of the hazard and risk analysis and are implemented according to best practices and standards covering IT security and cyber security (such as: ISO/IEC 27000 series, Common Criteria for Information Technology Security Evaluation, ISO/IEC 15408, IEC 62351, ISA/IEC 62443, NIST Cybersecurity Framework, Information Security Forum - Standard of Good Practice for Information Security).
- Verify the effectiveness of your IT security and cyber security systems using appropriate, proven methods.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

**WARNING**

**LOSS OF CONTROL**

Perform a comprehensive commissioning test to verify that communication monitoring properly detects communication interruptions

Failure to follow these instructions can result in death, serious injury, or equipment damage.
About the Book

At a Glance

Document Scope

The purpose of this document is to:
- show you how to install the POWERLINK module on your drive.
- show you how to configure the drive to use POWERLINK fieldbus.

NOTE: Read and understand this document and all related documents (see below) before installing, operating, or maintaining your drive.

Validity Note

Original instructions and information given in this manual have been written in English (before optional translation).

This documentation is valid for the Altivar Process drives.

The technical characteristics of the devices described in the present document also appear online. To access the information online:

<table>
<thead>
<tr>
<th>Step</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Go to the Schneider Electric home page <a href="http://www.schneider-electric.com">www.schneider-electric.com</a>.</td>
</tr>
</tbody>
</table>
| 2    | In the Search box type the reference of a product or the name of a product range.  
- Do not include blank spaces in the reference or product range.  
- To get information on grouping similar modules, use asterisks (*). |
| 3    | If you entered a reference, go to the Product Datasheets search results and click on the reference that interests you.  
If you entered the name of a product range, go to the Product Ranges search results and click on the product range that interests you. |
| 4    | If more than one reference appears in the Products search results, click on the reference that interests you. |
| 5    | Depending on the size of your screen, you may need to scroll down to see the data sheet. |
| 6    | To save or print a data sheet as a .pdf file, click Download XXX product datasheet. |

The characteristics that are presented in the present document should be the same as those characteristics that appear online. In line with our policy of constant improvement, we may revise content over time to improve clarity and accuracy. If you see a difference between the document and online information, use the online information as your reference.

Related Documents

Use your tablet or your PC to quickly access detailed and comprehensive information on all our products on [www.schneider-electric.com](http://www.schneider-electric.com).

The internet site provides the information you need for products and solutions:
- The whole catalog for detailed characteristics and selection guides.
- The CAD files to help design your installation, available in over 20 different file formats.
- All software and firmware to maintain your installation up to date.
- A large quantity of White Papers, Environment documents, Application solutions, Specifications... to gain a better understanding of our electrical systems and equipment or automation.
- And finally all the User Guides related to your drive, listed below:
<table>
<thead>
<tr>
<th>Title of Documentation</th>
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</thead>
<tbody>
<tr>
<td>Catalog: Altivar Process ATV600 variable speed drives</td>
<td>DIA2ED2140502EN (English), DIA2ED2140502FR (French)</td>
</tr>
<tr>
<td>ATV600 Getting Started</td>
<td>EAV63253 (English), EAV63254 (French), EAV63255 (German), EAV63256 (Spanish), EAV63257 (Italian), EAV64298 (Chinese)</td>
</tr>
<tr>
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<td>EAV64300 (English)</td>
</tr>
<tr>
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<td>EAV64301 (English), EAV64302 (French), EAV64306 (German), EAV64307 (Spanish), EAV64310 (Italian), EAV64317 (Chinese), EAV64301PT (Portuguese)</td>
</tr>
<tr>
<td>ATV600 Programming Manual</td>
<td>EAV64318 (English), EAV64320 (French), EAV64321 (German), EAV64322 (Spanish), EAV64323 (Italian), EAV64324 (Chinese), EAV64318PT (Portuguese)</td>
</tr>
<tr>
<td>ATV600 Modbus Serial Link Manual (Embedded)</td>
<td>EAV64325 (English)</td>
</tr>
<tr>
<td>ATV600 Ethernet Manual (Embedded)</td>
<td>EAV64327 (English)</td>
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<tr>
<td>ATV600 Ethernet IP - Modbus TCP Manual (VW3A3720, 721)</td>
<td>EAV64328 (English)</td>
</tr>
<tr>
<td>ATV600 BACnet MS/TP Manual (VW3A3725)</td>
<td>QGH66984 (English)</td>
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<td>ATV600 PROFIBUS DP manual (VW3A3607)</td>
<td>EAV64329 (English)</td>
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<td>ATV600 DeviceNet manual (VW3A3609)</td>
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<tr>
<td>ATV600 PROFINET manual (VW3A3627)</td>
<td>EAV64331 (English)</td>
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<tr>
<td>ATV600 CANopen Manual (VW3A3608, 618, 628)</td>
<td>EAV64333 (English)</td>
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<tr>
<td>ATV600 Communication Parameters</td>
<td>EAV64332 (English)</td>
</tr>
<tr>
<td>ATV600 Embedded Safety Function manual</td>
<td>EAV64334 (English)</td>
</tr>
<tr>
<td>Altivar Process Drive Systems Installation manual</td>
<td>NHA37119 (English), NHA37121 (French), NHA37118 (German), NHA37122 (Spanish), NHA37124 (Italian), NHA37124 (Chinese), NHA37124 (Dutch), NHA37128 (Polish), NHA37127 (Portuguese), NHA37129 (Turkish)</td>
</tr>
<tr>
<td>ATV660 Handbook</td>
<td>NHA37111 (English), NHA37110 (German)</td>
</tr>
<tr>
<td>ATV680 Handbook</td>
<td>NHA37113 (English), NHA37112 (German)</td>
</tr>
<tr>
<td>ATV600F, ATV900F Installation Instruction sheet</td>
<td>NVE67369 (English)</td>
</tr>
<tr>
<td>ATV600, ATV900 ATEX manual</td>
<td>NVE42416 (English)</td>
</tr>
<tr>
<td>SoMove: FDT</td>
<td>SoMove_FDT (English, French, German, Spanish, Italian, Chinese)</td>
</tr>
<tr>
<td>ATV600: DTM</td>
<td>ATV6xx DTM Library_EN (English - to be installed first), ATV6xx DTM Lang_FR (French), ATV6xx DTM Lang_DE (German), ATV6xx DTM Lang_SP (Spanish), ATV6xx DTM Lang IT (Italian), ATV6xx DTM Lang_CN (Chinese)</td>
</tr>
<tr>
<td>Application Note: ATV600 Multi Drives Booster Control Optimized</td>
<td>QGH36060 (English)</td>
</tr>
<tr>
<td>Application Note: ATV600 Multi Masters Booster Control Pressure Feedback with Service Continuity</td>
<td>QGH36061 (English)</td>
</tr>
<tr>
<td>Application Note: ATV600 Multi Drives Standard Level Control</td>
<td>QGH36059 (English)</td>
</tr>
<tr>
<td>Application Note: ATV600 Multi-Masters with Optimized Level Control</td>
<td>EAV64367 (English)</td>
</tr>
</tbody>
</table>

You can download these technical publications and other technical information from our website at [www.schneider-electric.com/en/download](http://www.schneider-electric.com/en/download)
**Terminology**

The technical terms, terminology, and the corresponding descriptions in this manual normally use the terms or definitions in the relevant standards.

In the area of drive systems this includes, but is not limited to, terms such as **error, error message, failure, fault, fault reset, protection, safe state, safety function, warning, warning message**, and so on.

Among others, these standards include:

- IEC 61800 series: Adjustable speed electrical power drive systems
- IEC 61508 Ed.2 series: Functional safety of electrical/electronic/programmable electronic safety-related systems
- EN 954-1 Safety of machinery - Safety related parts of control systems
- ISO 13849-1 & 2 Safety of machinery - Safety related parts of control systems
- IEC 61158 series: Industrial communication networks - Fieldbus specifications
- IEC 61784 series: Industrial communication networks - Profiles
- IEC 60204-1: Safety of machinery - Electrical equipment of machines – Part 1: General requirements

In addition, the term **zone of operation** is used in conjunction with the description of specific hazards, and is defined as it is for a **hazard zone** or **danger zone** in the EC Machinery Directive (2006/42/EC) and in ISO 12100-1.

Also see the glossary at the end of this manual.

**Contact Us**

Select your country on:

[www.schneider-electric.com/contact](http://www.schneider-electric.com/contact)

Schneider Electric Industries SAS

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92500 Rueil-Malmaison

France
Overview

Description

The VW3A3619 fieldbus module enables the integration of an Altivar variable speed drive into an Ethernet POWERLINK fieldbus system specification V1.1.

Software and Protocols Supported

The VW3A3619 POWERLINK module is compliant from the version (V2.2) of Altivar Process ATV600 drive.

If this requirement is not respected, a [Internal Error] INF6  error is triggered.
Chapter 2
Hardware Setup

What Is in This Chapter?

This chapter contains the following topics:

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</tr>
</tbody>
</table>
Hardware Presentation

POWERLINK Fieldbus Module

The following figure shows the **VW3A3619** POWERLINK module with 2 RJ45 connectors.

![POWERLINK Fieldbus Module](image)

Firmware and Description File

**Downloading the XDD File**

The associated XDD file is named as the following example:

0800005A_ATV600XXXXXX.xdd

The files are available on [www.schneider-electric.com](http://www.schneider-electric.com).
Installation of the Module

Before Starting

Check that the module catalog number marked on the label is the same as that on the delivery note corresponding to the purchase order.

Remove the fieldbus module from its packaging and check that it has not been damaged in transit.

Insertion of the Fieldbus Module

The table provides the procedure for insertion of the POWERLINK option module in the drive:

<table>
<thead>
<tr>
<th>Step</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Ensure that the power is off.</td>
</tr>
<tr>
<td>2</td>
<td>Locate the fieldbus module slot (A).</td>
</tr>
<tr>
<td>3</td>
<td>Insert the module.</td>
</tr>
<tr>
<td>4</td>
<td>Check that the module is correctly inserted and locked mechanically in the drive.</td>
</tr>
</tbody>
</table>

| 1 | Slot A |

Removal of the Fieldbus Module

The table provides the procedure for removal of the POWERLINK option module from the drive:

<table>
<thead>
<tr>
<th>Step</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Ensure that the power is off.</td>
</tr>
<tr>
<td>2</td>
<td>Press the strip.</td>
</tr>
<tr>
<td>3</td>
<td>Remove the module while maintaining the strip pressed.</td>
</tr>
</tbody>
</table>
Electrical Installation

Pin Layout of the VW3A3619

The VW3A3619 option module is equipped with 2 RJ45 female sockets for the POWERLINK connection. The following table describes the pin out of the VW3A3619 RJ45 connector.

<table>
<thead>
<tr>
<th>Interface</th>
<th>Pin Assignments</th>
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</thead>
<tbody>
<tr>
<td>Application interface POWERLINK</td>
<td>PIN</td>
</tr>
<tr>
<td>1</td>
<td>RxD</td>
</tr>
<tr>
<td>2</td>
<td>RxD\</td>
</tr>
<tr>
<td>3</td>
<td>TxD</td>
</tr>
<tr>
<td>4</td>
<td>Termination</td>
</tr>
<tr>
<td>5</td>
<td>Termination</td>
</tr>
<tr>
<td>6</td>
<td>TxD\</td>
</tr>
<tr>
<td>7</td>
<td>Termination</td>
</tr>
<tr>
<td>8</td>
<td>Termination</td>
</tr>
</tbody>
</table>

Cable Specifications

- Connection accessories may be ordered separately (consult our catalog).
- Use the Schneider Electric cable with two pairs of shielded twisted conductors (reference: TSXCSA100, TSXCSA200, TSXCSA500).
- Keep the Modbus cable separated from the power cables (30 cm (11.8 in.) minimum).
- Make any crossovers of fieldbus cable and the power cables at right-angles, if necessary.

For more information, refer to the TSX DG KBL E manual: “Electromagnetic compatibility of industrial networks and fieldbusses”.
Chapter 3
Software Setup

What Is in This Chapter?

This chapter contains the following topics:

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<thead>
<tr>
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<tbody>
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</tr>
<tr>
<td>[Address] $ABCD$</td>
<td>20</td>
</tr>
<tr>
<td>[MAC@] $ABCD$</td>
<td>20</td>
</tr>
<tr>
<td>Limitation</td>
<td>20</td>
</tr>
<tr>
<td>IO Scanner</td>
<td>21</td>
</tr>
</tbody>
</table>
Configuring the Communication Parameters

Overview

The parameters described in this chapter are accessible with the Graphic Display Terminal or with SoMove software. The parameters are visible only if a POWERLINK module is plugged in the drive.

Access

The configuration of the POWERLINK communication parameter is reachable with the drive menu:

- [Communication] \( \mathcal{C} \ a \mathcal{N} \rightarrow \mathcal{C} \ \text{Comm Parameters} \ \mathcal{P} \ \mathcal{P} \rightarrow \mathcal{C} \ \text{Comm Parameters} \ \mathcal{P} \ \mathcal{P} \rightarrow \text{Powerlink} \ \mathcal{E} \ \mathcal{P} \ \mathcal{L}

The monitoring parameters of the POWERLINK communication is reachable with the drive menu:

- [Display] \( \mathcal{N} \ a \mathcal{N} \rightarrow \mathcal{C} \ \text{Communication Map} \ \mathcal{P} \ \mathcal{P} \rightarrow \mathcal{N} \ \text{Powerlink Diag} \ \mathcal{P} \ \mathcal{W} \ \mathcal{L} \)

For the monitoring parameters, see Diagnostics and Troubleshooting (see page 27).

[Address] \( \mathcal{C} \ \mathcal{A} \ \mathcal{L} \ \mathcal{C} \)

About This Parameter

This parameter defines the address of the drive on the network.

Access

This is a read/write parameter.
This parameter can only be modified when the motor is stopped and the drive stopped.
The parameter number is 6601.

Possible Settings

The table presents the parameter settings:

<table>
<thead>
<tr>
<th>Settings</th>
<th>Code</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[0 to 239]</td>
<td>0...239</td>
<td>0...239</td>
<td>POWERLINK address of the drive.</td>
</tr>
<tr>
<td>Factory Settings: 0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

[MAC@] \( \mathcal{C} \ \mathcal{N} \ \mathcal{A} \ \mathcal{C} \)

About This Parameter

This parameter displays the MAC address of the device.

Access

This is a read-only parameter.
The parameter number is 64267, 64268 and 64269.

Possible Settings

The table presents the parameter settings:

<table>
<thead>
<tr>
<th>Settings</th>
<th>Code</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[00-80-F4-XX-XX-XX]</td>
<td>00-80-F4-XX-XX-XX-XX</td>
<td>00-80-F4-XX-XX-XX</td>
<td>MAC address of the port.</td>
</tr>
<tr>
<td>Left port MAC address is +1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Right port MAC address is +2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Factory Settings: 0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Limitation

Minimum Time Cycle

The minimum time cycle to use POWERLINK fieldbus is 2 ms, otherwise the drive triggers a \( \mathcal{C} \ n \ \mathcal{F} \) error.
IO Scanner

Configuration I/O Scanning

The I/O scanning service is used to exchange periodic I/O data between:

- A controller or PLC (I/O scanner)
- Devices (I/O scanning servers)

I/O Scanner Setting

The communication scanner is accessible via the addresses.

The output variables to read into the drive (OMA1 up to OMA6) are available at the logic addresses 15401 up to 15406.

The input variables to write into the drive (OCA1 up to OCA6) are available at the logic addresses 15421 up to 15426.

They are six output variables and six input variables available.
Chapter 4
Diagnostics and Troubleshooting

What Is in This Chapter?
This chapter contains the following topics:

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fieldbus Status LEDs</td>
<td>24</td>
</tr>
<tr>
<td>Diagnostics</td>
<td>27</td>
</tr>
</tbody>
</table>
Fieldbus Status LEDs

LED Indicators

<table>
<thead>
<tr>
<th>Figure</th>
<th>LED</th>
<th>Color</th>
<th>Status</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>L/A1</td>
<td>Green</td>
<td>On</td>
<td>A link to the remote station has been established.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Blinking</td>
<td>A link to the remote station 1 has been established. The LED blinks when Ethernet activity is present on the bus.</td>
</tr>
<tr>
<td>2</td>
<td>S/E</td>
<td>Green / red</td>
<td>–</td>
<td>Status/Error LED. See Status (see below) in the next table.</td>
</tr>
<tr>
<td>3</td>
<td>E</td>
<td>Green / red</td>
<td>On</td>
<td>Used to indicate an internal error between the drive and the communication module.</td>
</tr>
<tr>
<td>4</td>
<td>L/A2</td>
<td>Green</td>
<td>On</td>
<td>A link to the remote station has been established.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Blinking</td>
<td>A link to the remote station 2 has been established. The LED blinks when Ethernet activity is present on the bus.</td>
</tr>
</tbody>
</table>

The status/Error LED is green/red dual LED
### Status/Error LEDs Description

The status/error LED is a green/red dual LED. The color green (status) is superimposed on the color red (detected error).

<table>
<thead>
<tr>
<th>Color</th>
<th>Figure</th>
<th>Description</th>
</tr>
</thead>
</table>
| Green | OFF NOT_ACTIVE | The bus is monitored for POWERLINK frames. If a frame is not received within the configured time window (timeout), the drive switches directly into BASIC_ETHERNET status (flickering). If, however, POWERLINK communication is detected while in this status, the control node switches directly into the PRE_OPERATIONAL_1 status (single flash). **Flickering green (approx. 10 Hz)**  
**BASIC_ETHERNET**  
The drive is in BASIC_ETHERNET status, and is operated purely as an Ethernet TCP/IP device. If POWERLINK communication is detected while in this status, the control node switches directly into the PRE_OPERATIONAL_1 status (single flash). A red LED activated in this state indicates a communication error. |
| Red   | Blinking (approx. 2.5 Hz) STOPPED | The drive status is STOPPED. No output data is produced and no input data is received. Only the appropriate command from the network manager can enter or leave this state. |
| Red   | Off | No error detected. |
System Interruption Indication

Incorrect configuration or hardware can trigger an error. The detected error is displayed via the red error LED using four switch-on phases. The switch-on phases are either 150 ms or 600 ms long. Error code outputs are repeated cyclically after 2 seconds.

<table>
<thead>
<tr>
<th>Description</th>
<th>Code Display by the Red Status LED</th>
</tr>
</thead>
<tbody>
<tr>
<td>RAM error</td>
<td>X X X – Brake X X X – Brake</td>
</tr>
<tr>
<td>Bus error</td>
<td>– X X X Brake – X X X Brake</td>
</tr>
<tr>
<td>Invalid POWERLINK station number has been configured</td>
<td>X – – – Brake X – – – Brake</td>
</tr>
</tbody>
</table>

Legend:
- X...150 ms
- –...600 ms
- Brake...2 s delay
### Diagnostics

#### Diagnostics Menu

<table>
<thead>
<tr>
<th>Code</th>
<th>Name / Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>( d \cdot R \cdot )</td>
<td>[Diagnostics] This menu can only be accessed with the graphic display terminal. It displays detected errors and their cause in plain text and can be used to carry out tests, refer to the programming manual of the drive.</td>
</tr>
</tbody>
</table>

#### Error Code

Errors that can be cleared with the automatic restart function after the cause has been removed. These errors can also be cleared by applying power ON/OFF cycle or with a digital input or control bit ([Fault reset] \( r \cdot S \cdot F \)), refer to the Programming Manual.

#### Cause and Remedy

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Name / Description</th>
<th>Probable Cause</th>
<th>Remedy</th>
</tr>
</thead>
</table>
| \( C \cdot n \cdot F \) | [Com. network] Communication interruption on the fieldbus module. | • Check the environment (electromagnetic compatibility)  
• Check the wiring  
• Check the time-out  
• Replace the fieldbus module  
• Contact Schneider Electric Product Support |
| \( i \cdot L \cdot F \) | [internal com. link] Communication interruption between the fieldbus module and the drive. | • Check the environment (electromagnetic compatibility)  
• Check the connections  
• Replace the fieldbus module  
• Contact Schneider Electric Product Support |

#### Error Code Description

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Name / Description</th>
<th>Description</th>
<th>Possible Values</th>
</tr>
</thead>
</table>
| \( C \cdot n \cdot F \) | [Com. network] | This parameter indicates that a communication interruption has been detected. A value is stored depending on the interruption type. This detected error requires a power reset to be cleared.  
**NOTE:**  
\( C \cdot n \cdot F \) is available if the drive is:  
• in "operational" state and if the motor is running, or  
• in Ready State (\( r \cdot d \cdot y \)). | 0: No communication interruption  
1: Unspecified interruption  
17: lost of link (two ports)  
23: invalid Sync Manager configuration  
25: No valid outputs  
27: Sync Manager watchdog (one port)  
29: invalid Sync Manager config configuration  
30: invalid Sync Manager in configuration  
31: invalid watchdog configuration  
36: invalid input mapping  
37: invalid output mapping  
38: inconsistent settings  
43: No valid inputs and outputs  
44: Sync error  
80: EE no access  
81: EE error  
96: 0x60 |
| \( i \cdot L \cdot F \) | [internal com. link] | This parameter indicates an internal error. This detected error requires a power reset to be cleared. | – |

#### Tips

- If the display is not active, verify the power supply of the drive.
- If the channel for the reference value or command is assigned to fieldbus, the drive displays [Freewheel] \( n \cdot S \cdot E \) at the power-on until a command or a reference value is written.
Glossary

Abbreviations

Req. = Required
Opt. = Optional

CPx

CP0 up to CP4: Sercos III Communication phases

Error

Discrepancy between a detected (computed, measured, or signaled) value or condition and the specified or theoretically correct value or condition.

Factory setting

Default configuration of the product.

Fault

Fault is an operating state. If the monitoring functions detect an error, a transition to this operating state is triggered, depending on the error class. A "Fault reset" is required to exit this operating state after the cause of the detected error has been removed. Further information can be found in the pertinent standards such as IEC 61800-7, ODVA Common Industrial Protocol (CIP).

Fault Reset

A function used to restore the drive to an operational state after a detected error is cleared by removing the cause of the error so that the error is no longer active.

LSB

Least Significant Byte

MSB

Most Significant Byte

Monitoring function

Monitoring functions acquire a value continuously or cyclically (for example, by measuring) in order to check whether it is within permissible limits. Monitoring functions are used for error detection.

Parameter

Device data and values that can be read and set (to a certain extent) by the user.

PELV

Protective Extra Low Voltage, low voltage with isolation. For more information: IEC 60364-4-41

PLC

Programmable logic controller

Power stage

The power stage controls the motor. The power stage generates current for controlling the motor.
Quick Stop

The quick Stop function can be used for fast deceleration of a movement as a response to a detected error or via a command.

RWS

Read and write (write only possible when the drive is not in RUN mode). It is not possible to write these parameters in "5-Operation enabled" or "6-Quick stop active" states. If the parameter is written in the "4-Switched on" state, transition to "2-Switch on disabled" is activated.

VSD

Variable Speed Drive

Warning

If the term is used outside the context of safety instructions, a warning alerts to a potential problem that was detected by a monitoring function. A warning does not cause a transition of the operating state.

Zone of operation

This term is used in conjunction with the description of specific hazards, and is defined as it is for a hazard zone or danger zone in the EC Machinery Directive (2006/42/EC) and in ISO 12100-1.