



1 [Simply start] *S Y S -*

1.1 [Macro Config] *C F G*

- [Start/Stop] *b S t S*
- [Auto/Manual] *b A P P*
- [PID controller] *b P i d*
- [Preset speeds] *b P S P*
- [Modbus] *b M b C*
- [Multi-pump 1] *b M P 1*
- [Multi-pump 2] *b M P 2*

1.2 [Simply start] *S i P -*

- [Nominal Motor Power] *n P r*
- [Nom Motor Current] *n C r*
- [Motor Th Current] *i t H*
- [Acceleration] *a C C*
- [Deceleration] *d E C*
- [Low speed] *L S P*
- [High speed] *H S P*
- [Output Ph Rotation] *P H r*
- [Ref Freq 1 Config] *F r 1*
- [OutPhaseLoss Assign] *o P L*
- [2/3-Wire Control] *t C C*
- [Dual rating] *d r t*

1.3 [Modified parameters] *L P d -*

2 [Display] *P o n -*

2.1 [Motor parameters] *P P o -*

- [Motor Speed] *S P d*
- [Motor voltage] *u o P*
- [Motor Power] *o P r*
- [Motor Torque] *o t r*
- [Motor Current] *L C r*
- [Motor Therm State] *t H r*

2.2 [Drive parameters] *P P i -*

- [Pre-Ramp Ref Freq] *F r H*
- [Ref Frequency] *L F r*
- [Motor Frequency] *r F r*
- [Mains Voltage] *u L n*
- [DC bus voltage] *V b u S*
- [Drive Therm State] *t H d*
- [Used param. set] *C F P S*
- [Motor Run Time] *r t H H*
- [Power-on time] *P t H H*
- [IGBT Warning Counter] *t A C*
- [PID reference] *r P C*
- [PID feedback] *r P F*
- [PID Error] *r P E*
- [PID Output] *r P o*

2.3 [I/O Map] *i o P -*

- [Digital Input Map] *L i A -*
- [Analog inputs image] *A i A -*
 - [AI(x) assignment] *A i X A*
 - [AI(x) Min. Value] *u i L X*
 - [AI(x) Max Value] *u i H X*
 - [AI(x) Min. Value] *C r L X*
 - [AI(x) Max Value] *C r H X*
 - [AI(x) filter] *A i X F*
- where *x* is a number from 1 to 5
- [Analog outputs image] *A o A -*
 - [AQ(x) assignment] *A o X A*
 - [AQ(x) min Output] *u o L X*
 - [AQ(x) max Output] *u o H X*
 - [AQ(x) min output] *A o L X*
 - [AQ(x) max output] *A o H X*
 - [Scaling AQ(x)min] *A S L X*
 - [Scaling AQ(x)max] *A S H X*
 - [AQ(x) Filter] *A o X F*
- where *x* is a number from 1 to 2
- [Digital Output Map] *L o A*

2.4 [Energy parameters] *E n P -*

- [Motor Consumption] *n E 4*
- [Motor Consumption] *n E 3*
- [Motor Consumption] *n E 2*
- [Motor Consumption] *n E 1*
- [Motor Consumption] *n E 0*

2.5 [Communication map] *C P P -*

- [Command Channel] *C P d C*
- [Cmd Register] *C P d*
- [Ref Freq Channel] *r F C C*
- [Pre-Ramp Ref Freq] *F r H*
- [CIA402 State Reg] *E t A*
- [Modbus network diag] *P n d -*

- [COM LED] *P d b i*
- [Mdb Frame Nb] *M i c t*
- [Mdb NET CRC errors] *M I E c*
- [Com. scanner input map] *i S A -*
 - [Com Scan In(x) val.] *n n i* to *n n B*
- [Com scan output map] *o S A -*
 - [Com Scan Out(x) val.] *n c i* to *n c B*
- [Modbus HMI diag] *P d H -*
- [COM LED] *P d b 2*
- [Mdb NET frames] *M 2 c t*
- [Mdb NET CRC errors] *M 2 E c*
- [Command word image] *C W i -*
- [Modbus Cmd] *C P d i*
- [COM. Module cmd.] *C P d 3*
- [Freq. ref. word map] *r W i -*
 - [Modbus Ref Freq] *L F r i*
 - [Com Module Ref Freq] *L F r 3*

2.6 [Application Parameters] *A P r -*

- [Variable Speed Pump] *P P P -*
 - [Available Pumps] *P P A n*
 - [Nb of Staged Pumps] *P P S n*
 - [Lead Pump] *P L i d*
 - [Next Staged Pump] *P n t S*
 - [Next Destaged Pump] *P n t d*
 - [Pump (x) State] *P X S*
 - [Pump (x) Type] *P X t*
 - [Pump (x) Runtime] *P X o t*
 - [Pump (x) Nb Starts] *P X n S*
- where *x* is a number from 1 to 6
- [Booster Control Pump] *b c P -*
- [Booster Status] *b c S*

3 [Diagnostics] *d i A -*

3.1 [Diag. data] *d d t -*

- [Last Warning] *L A L r*
- [Last Error] *L F t*
- [Nb Of Starts] *n S n*
- [Motor Run Time] *r t H*
- [Other State] *S S t*
- [Identification] *o i d*

3.2 [Error history] *P F H -*

- [Last Error (x)] *d P i* to *d P B*
- [Drive state] *H S x*
- [Last Error (x) Status] *E P x*
- [ETI state word] *i P x*
- [Cmd word] *C P P x*
- [Motor current] *L C P x*
- [Output frequency] *r F P x*
- [Elapsed time] *r t P x*
- [DC bus voltage] *u L P x*
- [Motor therm state] *t H P x*
- [Command Channel] *d C C x*
- [Ref Freq Channel] *d r C x*
- [Motor Torque] *o t P x*
- [Drive Thermal State] *t d P x*
- [IGBT Junction Temp] *t J P x*
- [Switching Frequency] *S F P x*
- where *x* is a number from 1 to 8

3.3 [Warnings] *A L r -*

- [Actual Warnings] *A L r d*
- [Warning History] *A L h*

[-] after *c o d E* means there are more parameters levels

Some parameters have visibility constraints.
See ATV610 Programming manual (EAV64387).



4 [Complete settings] *C S t -*

4.1 [Motor parameters] *P P A -*

- [Motor Standard] *b F r*
- [Nominal Motor Power] *n P r*
- [Nom Motor Voltage] *u n S*
- [Nom Motor Current] *n C r*
- [Nominal Motor Freq] *F r S*
- [Nominal Motor Speed] *n S P*
- [Max frequency] *t F r*
- [Motor Th Current] *i t H*
- [Output Ph Rotation] *P H r*
- [Motor control type] *C t t*
- [Sync Nominal I] *n C r S (1)*
- [Nom SyncMotor Speed] *n S P S (1)*
- [Nom Motor torque] *t q S (1)*
- [Pole pairs] *P P n S (1)*
- [Angle setting type] *A S t (1)*
- [Syn. EMF constant] *P H S (1)*
- [SyncMotor Stator R] *r S A S (1)*
- [Autotune L d-axis] *L d S (1)*
- [Autotune L q-axis] *L q S (1)*
- [Sync Nominal Freq] *F r S S (1)*
- [PSI Align Curr Max] *P C r (1)*
- [Relative d-axis error] *r r d A E (1)*
- [Saliency mot. state] *S P o t (1)*
- [Tune selection] *S t u n (1)*
- [Rotational Current Level] *r C L (1)*
- [Rotational Torque Current] *r C t (1)*
- [RCI Max Freq] *r C S P (1)*
- [RCI Round Nb] *r C r P (1)*
- [RCI With Transformer] *r C i r (1)*
- [U/F Profile] *P F L*
- [U1] *u 1*
- [F1] *F 1*
- [U2] *u 2*
- [F2] *F 2*
- [U3] *u 3*
- [F3] *F 3*
- [U4] *u 4*
- [F4] *F 4*
- [U5] *u 5*
- [F5] *F 5*
- [IR compensation] *u F r*
- [Slip compensation] *S L P*
- [Switching frequency] *S F r*
- [Switch Freq Type] *S F t*
- [Noise Reduction] *n r d*
- [Motor Control 46] *E n 4 6*
- [Motor surge limit.] *S V L*
- [Attenuation time] *S o P*
- [Current Limitation] *C L i*
- [Autotuning] *t u n*
- [Autotuning Status] *t u S*
- [Dual rating] *d r t*
- [Boost activation] *b o A*
- [Boost] *b o o*
- [Freq Boost] *F A b*
- [Current Filter Time] *c r t F*
- [Currents Filter] *c r F A*
- [Input Filter] *d C r -*
 - [Input Filter] *i F i*
 - [DC Bus Ripple Config] *d C r C*
 - [Cur Loop Config Gain] *C r b*
 - [Cur Loop Default Gain] *C r b A*
 - [Cur Loop Damp Coef] *C r d r*

(1) Not available for
Frame Size 7 =
ATV610C22N4
ATV610C25N4

4.2 [Input/Output] *i o P -*

- [2/3-Wire Control] *t C C*
- [2-wire type] *t C t*
- [Reverse Assign] *r r S*
- [D11 Assignment] *L i L -*
 - [D11 Low Assignment] *L i L*
 - [D11 High Assignment] *L i H*
 - [D11 Delay] *L i d*
- [D12 Assignment] *L i 2 C -*
- [D13 Assignment] *L i 3 C -*
- [D14 Assignment] *L i 4 C -*
- [D15 Assignment] *L i 5 C -*
- [D16 Assignment] *L i 6 C -*
- [D111 Assignment] *L i 1 1 C -*
- [D112 Assignment] *L i 1 2 C -*
- [D113 Assignment] *L i 1 3 C -*
- [D114 Assignment] *L i 1 4 C -*
- [D115 Assignment] *L i 1 5 C -*
- [D116 Assignment] *L i 1 6 C -*

[Ref Freq template] *bSP*
 [AI1 configuration] *A, I, -*
 [AI1 assignment] *A, I, IA*
 [AI1 Type] *A, I, t*
 [AI1 Min. Value] *u, L, I*
 [AI1 Max Value] *u, H, I*
 [AI1 Min. Value] *Cr, L, I*
 [AI1 Max Value] *Cr, H, I*
 [AI1 filter] *A, I, F*
 [AI1 Intern. point X] *A, I, IE*
 [AI1 Intern. point Y] *A, I, IS*
 [AI2 configuration] *A, I, 2 -*
 [AI3 configuration] *A, I, 3 -*
 [AI4 configuration] *A, I, 4 -*
 [AI5 configuration] *A, I, 5 -*
 [AIV1 assignment] *AV, IA -*
 [DQ11 configuration] *do, I, 1 -*
 [DQ12 configuration] *do, I, 2 -*
 [R1 configuration] *r, I, -*
 [R1 Assignment] *r, I*
 [R1 Delay time] *r, I, d*
 [R1 Active at] *r, I, S*
 [R1 Holding time] *r, I, H*
 [R2 configuration] *r, 2 -*
 [R3 configuration] *r, 3 -*
 [R4 configuration] *r, 4 -*
 [R5 configuration] *r, 5 -*
 [R6 configuration] *r, 6 -*
 [AQ1 configuration] *AQ, I, -*
 [AQ1 assignment] *AQ, I, -*
 [AQ1 Type] *AQ, I, t*
 [AQ1 min output] *AQ, L, I*
 [AQ1 max output] *AQ, H, I*
 [AQ1 min output] *u, L, I*
 [AQ1 max output] *u, H, I*
 [Scaling AQ1 min] *AS, L, I*
 [Scaling AQ1 max] *AS, H, I*
 [AQ1 Filter] *AQ, I, F*
 [AQ2 configuration] *AQ, 2 -*

4.3 [Command and Reference] *Cr, P, -*

[Low Speed] *LSP*
 [High Speed] *HSP*
 [Ref Freq 1 Config] *F, r, 1*
 [Reverse Disable] *r, in*
 [Stop Key Enable] *PSt*
 [Control Mode] *CHCF*
 [Command Switching] *CCS*
 [Cmd channel 1] *Cd, 1*
 [Cmd channel 2] *Cd, 2*
 [Freq Switch Assign] *r, FC*
 [Ref Freq 2 Config] *F, r, 2*
 [Copy Ch1-Ch2] *C, o, P*
 [Forced Local Freq] *FL, o, C*
 [Time-out forc. local] *FL, o, t*
 [Forced Local Assign] *FL, o*
 [HMI cmd.] *b, n, P*

4.4 [Generic functions] *CSGF, -*

[Ramp] *r, A, n, P, -*
 [Ramp Type] *r, P, t*
 [Ramp increment] *i, n, r*
 [Acceleration] *ACC*
 [Deceleration] *dEC*
 [Begin Acc round] *t, A, 1*
 [End Acc round] *t, A, 2*
 [Begin Dec round] *t, A, 3*
 [End Dec round] *t, A, 4*
 [Ramp 2 Thd] *F, r, t*
 [Ramp Switch Assign] *r, P, S*
 [Acceleration 2] *ACC, 2*
 [Deceleration 2] *dEC, 2*
 [Dec.Ramp Adapt] *b, r, A*
 [+/- speed] *u, P, d, -*
 [+ Speed Assign] *u, SP, -*
 [- Speed Assign] *d, SP, -*
 [Ref Frequency Save] *S, t, r*
 [Stop configuration] *S, t, t, -*
 [Type of stop] *S, t, t*
 [Freewheel Stop] *n, S, t*
 [Freewheel stop Thd] *F, F, t*
 [Fast Stop Assign] *F, S, t, -*
 [Ramp Divider] *d, C, F*
 [DC Injection Assign] *d, C, I*
 [DC Inj Level 1] *i, d, C*
 [DC Inj Time 1] *t, d, I*
 [DC Inj Level 2] *i, d, C, 2*
 [DC Inj Time 2] *t, d, C, 2*
 [Auto DC injection] *A, d, C, -*
 [Auto DC injection] *A, d, C*
 [Auto DC inj Level 1] *S, d, C, 1*
 [Auto DC inj Time 1] *t, d, C, 1*
 [Auto DC inj Level 2] *S, d, C, 2*
 [Auto DC inj Time 2] *t, d, C, 2*
 [Jog] *J, o, G, -*
 [Jog Assign] *J, o, G, -*
 [Jog Frequency] *J, o, G, F*

[Jog Delay] *J, G, t*
 [Preset Speeds] *P, S, S, -*
 [2 Preset Freq] *P, S, 2*
 [4 Preset Freq] *P, S, 4*
 [8 Preset Freq] *P, S, 8*
 [16 Preset Freq] *P, S, 16*
 [Preset Speed 2] *S, P, 2*
 [Preset Speed 3] *S, P, 3*
 [Preset Speed 4] *S, P, 4*
 [Preset Speed 5] *S, P, 5*
 [Preset Speed 6] *S, P, 6*
 [Preset Speed 7] *S, P, 7*
 [Preset Speed 8] *S, P, 8*
 [Preset Speed 9] *S, P, 9*
 [Preset Speed 10] *S, P, 10*
 [Preset Speed 11] *S, P, 11*
 [Preset Speed 12] *S, P, 12*
 [Preset Speed 13] *S, P, 13*
 [Preset Speed 14] *S, P, 14*
 [Preset Speed 15] *S, P, 15*
 [Preset Speed 16] *S, P, 16*

[Skip Frequency] *J, P, F*
 [Skip Frequency 2] *J, F, 2*
 [3rd Skip Frequency] *J, F, 3*
 [Skip Freq.Hysteresis] *J, F, H*
 [Define system units] *S, u, C, -*
 [P sensor unit] *S, u, P, r*
 [Flow rate unit] *S, u, F, r*
 [Temperature unit] *S, u, t, P*
 [Currency unit list] *S, u, C, u*
 [Liquid Density] *r, H, o*

[PID controller] *P, I, d, -*
 [PID Feedback] *F, d, b*
 [Type of control] *t, o, C, t*
 [PID feedback Assign] *P, I, F*
 [Min PID feedback] *P, I, F, 1*
 [Max PID feedback] *P, I, F, 2*
 [PID feedback] *r, P, F*
 [Min fbk Warning] *P, A, L*
 [Max fbk Warning] *P, A, H*

[PID Reference] *r, F, -*

[Intern PID Ref] *P, I, -*
 [Ref Freq 1 Config] *F, r, 1*
 [Min PID Process] *P, I, P, 1*
 [Max PID Process] *P, I, P, 2*
 [Internal PID ref] *r, P, I*
 [Auto/Manual assign.] *P, A, u*
 [Manual PID reference] *P, I, n*
 [PID preset references] *P, r, I, -*
 [2 PID Preset Assign] *P, r, 2*
 [4 PID Preset Assign] *P, r, 4*
 [Ref PID Preset 2] *r, P, 2*
 [Ref PID Preset 3] *r, P, 3*
 [Ref PID Preset 4] *r, P, 4*

[Predictive Speed Ref] *F, P, I*
 [Speed input %] *P, S, P*

[Settings] *S, t, -*

[PID Prop.Gain] *r, P, G*
 [PID Intgl.Gain] *r, I, G*
 [PID derivative gain] *r, d, G*
 [PID ramp] *P, r, P*
 [PID Inversion] *P, I, C*
 [PID Min Output] *P, o, L*
 [PID Max Output] *P, o, H*
 [PID error Warning] *P, E, r*
 [PID Integral OFF] *P, I, S*
 [PID acceleration time] *A, C, C, P*
 [PID Start Ref Freq] *S, F, S*

[Sleep/Wakeup] *S, P, W*

[Sleep menu] *S, L, P, -*
 [Sleep Detect Mode] *S, L, P, n*
 [Sleep Switch Assign] *S, L, P, W*
 [Inst. Flow Assign.] *F, S, IA*
 [Sleep Flow Level] *S, L, n, L*
 [Sleep Pressure Level] *S, L, P, L*
 [Sleep Min Speed] *S, L, S, L*
 [Sleep Power Level] *S, L, P, r*
 [Sleep Delay] *S, L, P, d*

[Boost] *S, b, t, -*

[Sleep Boost Speed] *S, L, b, S*

[Sleep Boost Time] *S, L, b, t*

[Advanced sleep check] *A, d, S, -*

[Sleep Mode] *A, S, L, n*

[Sleep Condition] *A, S, L, C*

[Sleep Check Delay] *A, S, L, d*

[Check Sleep Ref spd] *A, S, L, r*

[Wake up menu] *W, k, P, -*

[Wake Up Mode] *W, u, P, n*

[Wake Up Process level] *W, u, P, F*

[Wake Up Process Error] *W, u, P, E*

[Wake Up Delay] *W, u, P, d*

[Threshold reached] *t, H, r, e, -*

[High Current Thd] *C, t, d*

[Low I Threshold] *C, t, d, L*

[Motor Freq Thd] *F, t, d*

[Low Freq.Threshold] *F, t, d, L*

[Freq. threshold 2] *F, 2, d*

[2 Freq. Threshold] *F, 2, d, L*
 [Motor Therm Thd] *t, h, d*
 [Reference high Thd] *r, t, d*
 [Reference low Thd] *r, t, d, L*
 [Mains contactor command] *L, L, C, -*
 [Mains V. time out] *L, t, e*
 [Mains Contactor] *L, L, c*
 [Drive Lock] *L, E, S*
 [Parameters switching] *n, L, P, -*
 [2 Parameter sets] *c, h, A, I*
 [3 Parameter sets] *c, h, A, 2*
 [Parameter Selection] *S, P, S*
 [Stop after speed timeout] *P, r, S, P, -*
 [Low Speed Timeout] *t, L, S*
 [Sleep Offset Thres.] *S, L, E*
 [Advanced sleep check] *A, d, S*
 [Sleep Mode] *A, S, L, n*
 [Sleep Condition] *A, S, L, c*
 [Sleep Check Delay] *A, S, L, d*
 [Check Sleep Ref spd] *A, S, L, r*

[Booster Control] *b, S, t, -*

[System Architecture] *n, P, P, -*

[Pump System Arch] *n, P, P, S, A*

[Nb Of Pumps] *n, P, P, n*

[Pumps Configuration] *P, u, n, P, -*

[Pump 1 Cmd Assign] *n, P, o, 1*

[Pump 1 Ready Assign] *n, P, 1, I*

[Pump 2 Cmd Assign] *n, P, o, 2*

[Pump 2 Ready Assign] *n, P, 2, I*

[Pump 3 Cmd Assign] *n, P, o, 3*

[Pump 3 Ready Assign] *n, P, 3, I*

[Pump 4 Cmd Assign] *n, P, o, 4*

[Pump 4 Ready Assign] *n, P, 4, I*

[Pump 5 Cmd Assign] *n, P, o, 5*

[Pump 5 Ready Assign] *n, P, 5, I*

[Pump 6 Cmd Assign] *n, P, o, 6*

[Pump 6 Ready Assign] *n, P, 6, I*

[Pump Cycling Mode] *n, P, P, c*

[Lead Pump Altern.] *n, P, L, A*

[Altern Wait Time] *n, P, A, t*

[Pump Auto Cycling] *n, P, c, P*

[Pump Ready Delay] *n, P, I, d*

[MultiPump ErrorResp] *n, P, F, b*

[Booster Control] *b, S, c, -*

[Booster Control] *b, c, n*

[Stage/Destage Cond.] *S, d, c, n, -*

[Boost Working range] *b, c, W, A*

[Booster Stg Delay] *b, S, d*

[Booster Dstg Delay] *b, d, d*

[Boost Override range] *b, c, o, A*

[Booster S/D Interval] *b, S, d, t*

4.5 [Generic monitoring] *G, P, r, -*

[Stall monitoring] *S, t, P, r, -*

[Stall monitoring] *S, t, P, c*

[Stall Max Time] *S, t, P, I*

[Stall Current] *S, t, P, 2*

[Stall Frequency] *S, t, P, 3*

[Therm sensor monit] *n, t, S, P, -*

[AI2 Th Monitoring] *t, h, 2, S*

[AI2 Type] *A, I, 2, t*

[AI2 Th Warn Level] *t, h, 2, A*

[AI2 Th Error Level] *t, h, 2, F*

[AI2 Th Error Resp] *t, h, 2, b*

[AI2 Th Value] *t, h, 2, V*

[AI3 Th Monitoring] *t, h, 3, S*

[AI3 Type] *A, I, 3, t*

[AI3 Th Warn Level] *t, h, 3, A*

[AI3 Th Error Level] *t, h, 3, F*

[AI3 Th Error Resp] *t, h, 3, b*

[AI3 Th Value] *t, h, 3, V*

[AI4 Th Monitoring] *t, h, 4, S*

[AI4 Type] *A, I, 4, t*

[AI4 Th Warn Level] *t, h, 4, A*

[AI4 Th Error Level] *t, h, 4, F*

[AI4 Th Error Resp] *t, h, 4, b*

[AI4 Th Value] *t, h, 4, V*

[AI5 Th Monitoring] *t, h, 5, S*

[AI5 Type] *A, I, 5, t*

[AI5 Th Warn Level] *t, h, 5, A*

[AI5 Th Error Level] *t, h, 5, F*

[AI5 Th Error Resp] *t, h, 5, b*

[AI5 Th Value] *t, h, 5, V*

4.6 [Error/Warning handling] *C, S, W, n, -*

[Fault Reset] *r, S, t, -*

[Fault Reset Assign] *r, S, F*

[Prod Restart Assign] *r, P, A*

[Product restart] *r, P*

[Auto Fault Reset] *A, t, r, -*

[Auto Fault Reset] *A, t, r*

[Fault Reset Time] *t, A, r*

[Catch on the fly] *F, L, r, -*

[Catch On Fly] *F, L, r*

[Catch on Fly Sensitivity] *V, c, b*

[Catch on Fly Mode] *c, o, F, n*

[Motor thermal monit] *EHt -*
 [Motor Thermal Mode] *EhE*
 [Motor Therm Thd] *EtE*
 [MotorTemp ErrorResp] *oLL*
 [Output phase Loss] *oPL -*
 [OutPhaseLoss Assign] *oPL*
 [OutPhaseLoss Delay] *oEt*
 [Input phase loss] *iPL -*
 [InPhaseLoss Assign] *iPL*
 [External error] *EEF -*
 [Ext Error assign] *EEF*
 [Ext Error Resp] *EPL*
 [Undervoltage handling] *uSb -*
 [Undervoltage Resp] *uSb*
 [Mains voltage] *urES*
 [Undervoltage level] *uSL*
 [UnderVolt timeout] *uSt*
 [Stop Type PLoss] *StP*
 [UnderV. restart tm] *ESn*
 [Prevention level] *uPL*
 [Max stop time] *Stn*
 [DC bus maintain time] *EtS*
 [Ground Fault] *GrFL -*
 [Ground Fault Activation] *GrFL*
 [4-20 mA loss] *LFL -*
 [AI1 4-20mA loss] *LFL1*
 [AI2 4-20mA loss] *LFL2*
 [AI3 4-20mA loss] *LFL3*
 [AI4 4-20mA loss] *LFL4*
 [AI5 4-20mA loss] *LFL5*
 [AI Loss Inhibition] *inLF*
 [Fallback speed] *LFF -*
 [Fallback speed] *LFF*
 [Error detection disable] *inH -*
 [ErrorDetect Disable] *inH*
 [Fieldbus Interrupt Resp] *CLL -*
 [Modbus Error Resp] *SLL*
 [Communication Module] *CnPo -*
 [Fieldbus Interrupt Resp] *CLL*
 [Tuning Error Resp] *EnL*
 [Process underload] *uLd -*
 [Unld T. Del. Detect] *uLd*
 [Unld. Thr.Nom.Speed] *LuN*
 [Unld. Thr.0.Speed] *LuL*
 [Unld. FreqThr. Det.] *rNuD*
 [Hysteresis Freq] *Srb*
 [Underload Mangmt.] *uDL*
 [Underload T.B.Rest.] *Ftu*
 [Process overload] *oLd -*
 [Ovld Time Detect.] *oLd*
 [Ovld Detection Thr.] *Ldc*
 [Hysteresis Freq] *Srb*
 [Ovld.Proces.Mngmt] *oDL*
 [Overload T.B.Rest.] *Fto*
 [Warning groups config] *AGCF -*
 [Warn grp 1 definition] *A1c*
 [Warn grp 2 definition] *A2c*
 [Warn grp 3 definition] *A3c*
 [Warn grp 4 definition] *A4c*
 [Warn grp 5 definition] *A5c*

4.7 [Maintenance] *C5NA -*

[Diagnostics] *dAu -*
 [FAN Diagnostics] *Fnt*
 [LED Diagnostics] *hLl*
 [IGBT Diagnostics with motor] *iWt*
 [IGBT Diagnostics w/o motor] *iWoE*
 [Fan management] *FANA -*
 [Fan mode] *FFn*
 [Time Counter Reset] *rPr*
 [Overmodul. Activation] *oVNA*

5 [Communication] *CnN -*

[Modbus Address] *Add*
 [Modbus baud rate] *Ebr*
 [Modbus Format] *Efo*
 [ModbusTimeout] *EtO*
 [Com. scanner input] *iCS -*
 [Scan. IN1 address] *nNA1*
 [Scan. IN2 address] *nNA2*
 [Scan. IN3 address] *nNA3*
 [Scan. IN4 address] *nNA4*
 [Scan. IN5 address] *nNA5*
 [Scan. IN6 address] *nNA6*
 [Scan. IN7 address] *nNA7*
 [Scan. IN8 address] *nNAB*
 [Com. scanner output] *oCS -*
 [Scan.Out1 address] *ncA1*
 [Scan.Out2 address] *ncA2*
 [Scan.Out3 address] *ncA3*
 [Scan.Out4 address] *ncA4*
 [Scan.Out5 address] *ncA5*
 [Scan.Out6 address] *ncA6*
 [Scan.Out7 address] *ncA7*
 [Scan.Out8 address] *ncAB*
 [Profibus] *Pbc -*
 [Address] *Adrc*

6 [File management] *Fnl -*

6.1 [Transfer config file] *EtCF -*

[Copy to the drive] *oPF*
 [Copy from the drive] *SrF*

6.2 [Factory settings] *FCS -*

[Config. Source] *FCS*
 [Parameter group list] *Fry -*
 [Go to Factory Settings] *GFS*
 [Save Configuration] *SCS*

6.3 [Firmware Update] *FWuP -*

[Firmware update diag] *FWud -*
 [Firmware Update Status] *FWSt*
 [Firmware Update Error] *FWEr*
 [Identification] *oid -*
 [Package version] *Pfu -*
 [Package Type] *PKEP*
 [Package Version] *PKV5*
 [Update Firmwre] *FWuP -*
 [Abort Firmware Update] *FWCL*

7 [My preferences] *NYP -*

7.1 [Language] *LNG -*

7.2 [Password] *Cod -*

[Password status] *PSSt*
 [Password] *PWd*
 [Upload rights] *uLr*
 [Download rights] *dLr*

7.3 [Customization] *CUS -*

[Display screen type] *NSC -*
 [Display value type] *Ndt*
 [Parameter Selection] *PPc*

7.4 [Access Level] *LAc -*

[Basic] *bAS*
 [Expert] *EPe*

7.5 [LCD settings] *cnL -*

[Screen Contrast] *cSt*
 [Standby] *SbY*
 [Display Terminal locked] *KLCK*



Troubleshooting

Scan the QR code in front of the drive to open the ATV610 Programming manual ([EAV64387](#)) and select *Diagnostics and Troubleshooting* chapter.

Notes