

# Altivar Process ATV900

V4.5IE41

## 1. Safety information

You can Download and install **EcoStruxure Automation Device Maintenance** here:

- <https://www.se.com/ww/en/download/document/EADM/>

Carefully read the instructions contained in the

**Altivar User Manual for EcoStruxure Automation Device Maintenance,**

- available here: <https://www.se.com/ww/en/download/document/JYT50472/>
- or available on *Windows Start Menu > EcoStruxure Automation Device Maintenance > Documents.*

## 2. Software enhancements in this version

- [Hoisting] Improved behavior in Open Loop with Encoder
- [Hoisting] Support of a new feature: Time Delay Control
- Support of VW3A3530D ATV dPAC Module
- Extended setting range for fluxing high power motors
- Ability to configure I/O scanner from Graphic Display Terminal
- [Master / Slave] Improved behavior at Power ON
- Added new configuration of the braking resistor to be enabled only when motor is running
- Improved Undervoltage handling function
- [Braking] Offers consistent behavior of BRI and BCI settings
- [Energy Monitoring] Improved accuracy of displayed values for 110kW (and above) drives
- [Drive System] Improved Cabinet I/O functions
- [HMI] Improved refresh of Operating points for Torque curve
- Cybersecurity enhancements with the embedded Ethernet V2.3IE40

## 3. Notes

- To ensure that the new parameters and menus are correctly displayed, the Altivar Graphic Display Terminal labels can be updated. Refer to the instructions inside [https://www.se.com/ww/en/download/document/Languages\\_Drives\\_VW3A1111/](https://www.se.com/ww/en/download/document/Languages_Drives_VW3A1111/)

## 4. Software enhancements history

### Version V4.3IE40

- Firmware evolution to support the VW3A3802 Safety Module
- Firmware evolution to support the VW3A3809 Safety over Ethernet IP Module
- Firmware evolution to support the VW3A3807 PROFIsafe Module
- Improvement of the Safety Function SLS (Safely Limited Speed) behavior with the VW3A3802 Safety Module
- [DC bus management] CRDR parameter is now available via the Graphic Display terminal to set the Damping ratio of the current loop controller.
- Cybersecurity enhancements with the embedded Ethernet V2.3IE38B4
- Cybersecurity enhancements
- Improvement of the braking resistor and/or braking unit detection error on APM drives when [Braking Resistor] BRC is set to [No] NO
- Enhancement of the motor setting by providing a recommendation on parameters [Magnetizing Current] IDA and [Rotor Time Const] TRA

### Version V4.2IE39

- [Ethernet] Cybersecurity enhancements with the embedded Ethernet V2.3IE37B1
- Cybersecurity enhancements
- Enhance the DC bus management by automatically activating the DC Bus Ripple monitoring
- Improve Torque Control behavior with long [Torque ramp time]
- Improve the internal errors description by displaying subcode on Error History
- Improve the Reference Copy on Channel switch to manage the bidirectional copy
- Extend the maximum Relay Holding time
- Improve the configuration save result on keypad when using more than 16 files
- Improve Master/Slave management on multi-motor switching

### Version V4.1IE38

- Added TTOB and TOUT timeout parameters to the Graphic Display Terminal menus.
- [High Speed Hoisting] Ability to set COR and COF up to 200%
- Improvement of Gain & offset management of measured voltage & current when PHR=ACB
- Support of Undervoltage handling function with DC supply
- Ability to reset Electrical Energy counters.
- Improved PID behavior when switching from Manu to Auto
- Improvement of Encoder check function
- [Ethernet] Improved handling of ETHF alarm when switching the command channel.
- [Ethernet] Cybersecurity enhancements with the embedded Ethernet V2.3IE36B1

### Version V3.9IE35

- Support of the new Profinet module VW3A3647
- Ethernet cybersecurity enhancements with the embedded Ethernet V2.3IE35B1
- New parameters CRB (Current loop configured gain) and CRBA (Current loop default gain) now available to enhance the motor speed stability.
- High speed hoisting enhancement to avoid sporadic SCF1, ANF or OPF in specific use case.
- Improvement of the AB Encoder feedback in closed loop in Ready mode.
- PID behavior enhancement when the LSP (Low Speed) is different from 0.
- Improvement of the synchronous motor setting to avoid CFF in some specific cases.
- Improvement in EtherNet/IP with assembly 21/71 using messaging

## Version V3.8IE34

- It is now possible to set the parameter [Braking Resistor] BRC to [No] NO even when [Dec.Ramp Adapt] BRA is also set to [No] NO, which results in both the deceleration ramp adaptation and braking resistor deactivated at the same time.
- New possible setting [STO fct status] STOS is now available on drive outputs (digital outputs and relays). It allows to show the status of the Safe Torque Off STO function.
- In the menu [Motor monitoring] MOP, new parameter [Torque Filter Time] TPFV has been added to define a filter time constant applicable on the non-filtered output torque and power.
- Setting the date and time through the display terminal is now possible with version V3.8IE34
- With VW3A3424 HTL encoder interface module, it is now possible to use an encoder having a pulse number [PGI] which is not a multiple of 2 or which is lower than 256.
- Software enhancement for APM-Liquid Cooled (ATV-L0), to reduce motor vibration at low speed.

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