## SpaceLogic MG600C SR

## Installation and Manual Override Instructions

| A CAUTION |
| :--- |
| DISCONNECT POWER FOR MANUAL OVERRIDE OPERATION |
| - Disable power to the actuator prior to operating the manual |
| override. |
| - If the hex key is left in the hex manual override drive socket, |
| the hex key will rotate as the actuator is driven. This is not |
| recommended and damage could occur if the key is not free |
| to rotate. |
| Failure to follow this instruction may result in equipment |
| damage or personal injury. |

## A CAUTION

RISK OF BURNS OR FLYING PARTS
If the valve stem, spindle, or plug has been damaged, it may blow out under pressure while servicing the actuator. - Isolate and depressurize the valve before servicing. - Manually check valve stem, spindle, or plug integrity by moving it within the valve. If the part can be removed, replace the valve assembly.
Failure to follow these instructions may result in death or serious injury.

Manual Overide Operation



1. Lock (flat screw driver) socket.
2. Hex (Allen Key) manual override drive socket
3. Socket Covers


Do not operate manual override with power tools.

NOTE: Remove Allen Key wrench before resuming normal operation. Only operate the manual override and the lock screw in the direction shown by the arrows on the actuator labels or this instruction manual. Upon re-connecting power to the actuator, the actuator will momentarily drive against the spring to ensure disengagement of the lock screw and return the actuator to automatic control.

## Mounting and Installation

1. Before assembling the valve and actuator, pull the valve stem up on the valve.
2. It will not be possible to properly mount the valve if the actuator stem connection brace is at either end of the stroke limits: Operate the manual overide with the 5 mm hex key. Only operate the manual override in the direction shown for the SRU/SRD variant.
3. Position the bracket in mid-position of actuator stroke range.
4. Once the actuator is in the mid- position, lock using a flat blade screw driver turning the socket in the direction shown.
5. To slide the actuator onto the valve, first align the valve stem connector to the actuator stem connection brace. Push the actuator down over the valve bonnet and secure with the U-bolt brace.
6. Unlock the actuator by operating the manual override and exchange a green indicator for a red (hot) or blue (cold) indicator as applicable and slide the stroke indicators around the stem connection brace. During the calibration process the actuator will automatically position the stroke indicators to the end stop limits of the valve.
7. Loosen the cover screws with a Phillips screwdriver and if neccessary pry off the cover using a flat screwdriver.
8. Install the cable glands and blanking plugs required as shown and wire and stroke calibrate the actuator once power is applied.

Mounting Orientation
The actuator can be mounted in any orientation other than upside down. Maximum actuator ambient temperature is $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$ for chilled water media. Maximum actuator ambient temperature is $46^{\circ} \mathrm{C}\left(115^{\circ}\right.$ F) when media temperature is $120^{\circ}$ C ( $248^{\circ} \mathrm{F}$ ).


(9)

(10)


Mount the cover again checking the correct positioning of the gaskets placed under the cover, and locking properly the 4 screws.

Wiring
Increase/Decrease (Floating)

Modulating (proportional) $0 \ldots 10 \mathrm{Vdc} / 2 \ldots 10 \mathrm{Vdc}$

$$
[+0 \ldots 5 / 2 \ldots 6 / 5 \ldots 10 / 6 \ldots 10 \mathrm{Vdc}]
$$



Short cable installation (3 wires to the actuator)


Electrical Connections

| Terminal | Function | Description |
| :--- | :--- | :--- |
| G | 24 Vac/dc | Power Supply |
| G0 | $\perp$ |  |
| $\mathbf{X} 1$ | Proportional (MOD) | Modulating (Proportional) Control <br> signal input |
| MX | Neutral, proportional (MOD) |  |
| VH | Increase, 3-point (Floating) | Increase / decrease (3 Point <br> floating) control signal input (Di- <br> rection switching on 0V / GND) |
| VC | Decrease, 3-point (Floating) | External supply, 25 mA max. |
| G1 | 16 Vdc | Feedback signal |
| Y | $0 . .100 \% ~(2-10 ~ V d c ~ / ~ 0-5 ~$ <br> Vdc) |  |



Dip Switch Settings

|  |  | 1 | Feedback signal | 2... 10 Vdc | $0 . . .5 \mathrm{Vdc}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 2 | Control mode | Modulating (Proportional) | Increase / decrease (3P floating) |
| MN | OUT <br> INC/DEC | 3 | Sequence operation | Normal operation (no sequence) | Sequence Control (Modulating only) <br> Refine sequential control signal using Sw. 4 and Sw. 5 |
|  | Sequence | 4 | Input voltage range (Modulating) | 0... 10 Vdc | 2... 10 Vdc |
| 0... 10 MOD <br> 5, 2... 6 SEQ | 2... 10 MOD | 5 | Working sequential control signal | $\begin{aligned} & 0 \ldots . .5 \mathrm{Vdc}(\text { (or } 2 \ldots . .6 \\ & \text { Vdc) (with Sw. } 4 \text { ON) } \end{aligned}$ | $\begin{aligned} & \hline \begin{array}{l} \text { 5... } 10 \mathrm{Vdc} \text { (or } 6 \ldots 10 \mathrm{Vdc} \text { ) } \\ \text { (with Sw. } 4 \text { ON) } \end{array} \\ & \hline \end{aligned}$ |
| 60s | 300s | 6 | Running time (floating control only) | 60 sec . | 300 sec . |
|  |  | 7 | Direction of movement | Normal (direct) movement to input signal | Inverse / reverse direction of operation to control signal |
| NORM <br> AUTO | LIN/LG <br> MAN | 8 | Flow Curve Linearization | Normal (no electronic flow curve adaptation) | Electronically adapts the the flow rate in an $E Q$ valve to a linear characterized flow |
| - Switch |  | 9 | Normal Operation / Stroke Calibration | Normal | Stroke Calibration, momentary flip sw. 9 ON and then OFF to adjust actuator control signal to valve stroke limits |

## Notes：Dip Switch Settings

Calibrate the actuator with Sw 9 after carrying out the first coupling and everytime some component and／or the coupling parts are changed on the valve．
1）Units are shipped with switches in a default＂off＂position．
2）Switch 3 must be in the off position if sequence control is not used．
3）Switch 5 is only active if switch 2 is off and switch 3 is on．
NOTE：For the actuator to register new settings of the switches，the supply voltage must be removed by removing power to the actuator，then change any of switches 1 through 8 as required and then restore power to the actuator．

Control direction according to Switch 7 （Normal／Inverse）


Actuator Spring Return Direction and Valve Function

|  | MG600C－SRU（Stem up） | MG600C－SRD（Stem down） |
| :--- | :--- | :--- |
| VG210 | Normally closed | Normally open |
| VG310 | Normally closed | Normally open |


| Commercial Reference | Range Name |  | Product Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { 880XXXXXXX } \\ \text { MXXX(X)A(X)(X)(-S2)(-VB) } \\ \text { MGXXX(-S(R)X)(-W) } \end{gathered}$ | SPACELOGIC <br> VALVES \＆ACTUATORS |  | SPACELOGIC 800 SERIES GLOBE VALVE ACTUATOR SR／NSR SPACELOGIC M SERIES GLOBE VALVE ACTUATOR SR／NSR SPACELOGIC MG SERIES GLOBE VALVE ACTUATOR SR／NSR SPACELOGIC MP SERIES PIBCV ACTUATOR SR／NSR |  |  | －20 |
| MPXXXX $(-S R X)(-W)$ | 有害物质－Hazardous Substances |  |  |  |  |  |
| 部件名称 Part Name | $\begin{gathered} \begin{array}{c} \text { 铅 } \\ (\mathrm{Pb}) \end{array} \end{gathered}$ | $\begin{gathered} \text { 汞 } \\ (\mathrm{Hg}) \end{gathered}$ | $\begin{gathered} \text { 镉 } \\ (\mathrm{Cd}) \end{gathered}$ | 六价铬 <br> （Cr（VI）） | 多溴联苯 (PBB) | 多溴二苯醚 （PBDE） |
| 属部件 Metal Parts | X | 0 | 0 | 0 | 0 | 0 |
| 塑料部件 Plastic Parts | 0 | 0 | 0 | 0 | 0 | 0 |
| 电子件 Electronic | X | 0 | 0 | 0 | 0 | 0 |
| 触点 Contacts | 0 | 0 | O | 0 | 0 | O |
| 线缆和线缆附件 Cable \＆Cabling Accessories | 0 | 0 | 0 | 0 | 0 | 0 |
| 本表格依据 SJ／T11364 的规定编制。 <br> O：表示该有害物质在该部件所有均质材料中的含量均在 GB／T 26572 规定的限量要求以下。 X：表示该有害物质至少在该部件的某一均质材料中的含量超出 GB／T 26572 规定的限量要求。 （企业可在此处，根据实际情况对上表中打＂$X$＂的技术原因进行进一步说明。） |  |  |  |  |  |  |
| This table is made according to $\mathrm{SJ} / \mathrm{T} 11364$. <br> O ：indicates that the concentration of hazardous substance in all of the homogeneous materials for this part is below the limit as stipulated in GB／T 26572. <br> X ：indicates that concentration of hazardous substance in at least one of the homogeneous materials used for this part is above the limit as stipulated in GB／T 26572 |  |  |  |  |  |  |


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